iMASTER C1
INSTRUCTION MANUAL

Precautions

Keep this manual close to the handler responsible for the operation and maintenance inspection.
Be sure to familiarize yourself with the handling manual before performing an inspection, and use it correctly according to the instructions of the instrument's knowledge, safety information, precautions, operation, and handling methods.
Always observe the various specifications in the handbook.
Also, perform the correct inspection and repair to prevent the failure.

Warranty for the unit

The warranty period for the delivery product is one year after delivery to the designated place of the order.
In the event of a failure under normal use within the product specifications in accordance with this manual, the defect shall be replaced or repaired free of charge.
However, the warranty will be void if the fault is due to;

(1) In case of unfair treatment and use by the consumer;
(2) If the cause of failure is due to a reason other than the product supplied,
(3) In case of modifications or repairs other than suppliers;
(4) In case the supplier is not responsible for other natural disasters or disasters;

In addition, the warranty is for the inverter only, any damage caused to other equipment by malfunction of the inverter is not covered by the warranty.

Repair cost

Any repairs after the warranty period (1 year) will be paid. In addition, even during the warranty period, repairs for reasons other than the above warranty coverage and investigation into the cause of failure will be treated as a charge.
Please contact your place of purchase or service center – please refer to the list of back cover.

Questions on Unit

If you have any questions regarding damage to the unit, unknown parts or for general inquiries, please contact service center with the following information.

(1) Date of purchase
(2) Company name of purchase
(3) Manufacturing number (MFG. No.)
(4) Failure details (as detailed as possible)

CAUTION FOR UL/cUL REQUIREMENTS

- THE ADT CO., LTD iMASTER C1 VFD UL FILE NUMBER IS E479086
  CONFIRMATION OF UL LISTING CAN BE FOUND ON THE UL WEB SITE: www.ul.com

- DO NOT CONNECT OR DISCONNECT WIRING, OR PERFORM SIGNAL CHECKS WHILE THE POWER SUPPLY IS TURNED ON.

- THERE ARE LIVE PARTS INSIDE THE VFD. NEVER TOUCH THE PRINTED CIRCUIT BOARD (PCB) WHILE THE POWER SUPPLY IS TURNED ON.

[WARNING] THE BUS CAPACITOR DISCHARGE TIME IS 5 MINUTES. BEFORE STARTING WIRING OR INSPECTION, SWITCH POWER OFF, WAIT FOR MORE THAN 5 MINUTS, AND CHECK FOR RESIDUAL VOLTAGE BETWEEN TERMINAL P (+) AND N (-) WITH A METER ETC., TO AVOID HAZARD OF ELECTRICAL SHOCK.

[**SHORT CIRCUIT RATING]** THIS VFD IS SUITABLE FOR USE ON A CIRCUIT CAPABLE OF DELIVERING NOT MORE THAN ___*1___ARMS SYMMETRICAL AMPERES, 480 VOLTS FOR HF TYPE AND 240 VOLTS FOR SF,LF TYPE MAXIMUM.

BRANCH CIRCUIT SHORT CIRCUIT PROTECTION SHALL BE PROVIDED BY FUSE ONLY.

*1 **iMASTER C1 MODELs and KA VALUE**

5KA	iMASTER C1-004SF ~ iMASTER C1-370HF All Model
10KA	iMASTER C1-450HF ~ iMASTER C1-1320HF All Model
18KA	iMASTER C1-1600HF ~ iMASTER C1-2200HF All Model
30KA	iMASTER C1-2800HF ~ iMASTER C1-3500HF All Model

[**OVERSPEED PROTECTION]** THIS VFD DOES NOT PROVIDE OVERSPEED PROTECTION

[**MOTOR OVERLOAD PROTECTION]** THIS VFD PROVIDES MOTOR OVERLOAD PROTECTION. OVERLOAD PROTECTION LEVEL IS 20 ~ 120% OF FULL LOAD CURRENT. THE PROTECTION LEVEL MAY BE ADJUSTED BY PARAMETER (b04). REFER TO THE iMASTER C1 USER GUIDE OR CATALOG.

[**MOTOR OVERTEMPERATURE]** MOTOR OVERTEMPATURE SENSING IS NOT PROVIDED BY THE VFD.

[ENVIRONMENT]

MAXIMUM AMBIENT TEMPERATURE	50℃(WHEN CARRIER FREQUENCY EQUAL TO OR LESS THAN DEFAULT VALUE)
AMBIENT HUMIDITY	90% RH OR LESS(NO CONDENSING)
STORAGE TEMPERATURE	-20~60℃
VIBRATION	5.9㎨OR LESS
ALTITUDE	ALTITUDE 1,000m OR LESS
AMBIENCE	INDOORS(NO CORROSIVE AND FLAMMABLE GASES, OIL MIST, DUST AND DIRT)
POLLUTION DEGREE	2

SAFETY

- FOR THE SAFE OPERATION OF THE iMASTER C1 SERIES VFD, READ THIS MANUAL AND ALL OF THE WARNING SIGNS ATTACHED TO THE INVERTER CAREFULLY BEFORE INSTALLING AND OPERATING IT, AND FOLLOW THE INSTRUCTION EXACTLY. KEEP THIS MANUAL HANDY FOR YOUR QUICK REFERENCE.

SYMBOLS AND DEFINITION

- A SAFETY INSTRUCTION (MESSAGE) IS GIVEN WITH A HAZARD ALERT SYMBOL AND/OR A WARNING or CAUTION.
- EACH SIGNAL HAS THE FOLLOWING MEANING THROUGHOUT THIS MANUAL

HAZARDOUS HIGH VOLTAGE.

IT USED TO CALL YOUR ATTENTION TO ITEMS OR OPERATIONS THAT COULD BE DANGEROUS TO YOU OR OTHER PERSONS OPERATING THIS EQUIPMENT.
READ THESE MESSAGES AND FOLLOW THESE INSTRUCTIONS CAREFULLY.

SAFETY ALERT SYMBOL

THIS SYMBOL IS USED TO CALL YOUR ATTENTION TO ITEMS OR OPERATIONS THAT COULD BE DANGEROUS TO YOU OR OTHER PERSONS OPERATING THIS EQUIPMENT.
READ THESE MESSAGES AND FOLLOW THESE INSTRUCTIONS CAREFULLY.
.

WARNING INDICATES A POTENTIALLY HAZARDOUS SITUATION WHICH, IF NOT AVOIDED, CAN RESULT IN SERIOUS INJURY OR DEATH.

CAUTION INDICATES A POTENTIALLY HAZARDOUS SITUATION WHICH, IF NOT AVOIDED, CAN RESULT IN MINOR TO MODERATE INJURY, OR SERIOUS DAMAGE OF PRODUCT.
THE MATTERS DESCRIBED UNDER ⚠**CAUTION** MAY, IF NOT AVOIDED, LEAD TO SERIOUS RESULTS DEPENDING ON THE SITUATION. IMPORTANT MATTERS ARE DESCRIBED IN **CAUTION** (AS WELL AS WARNING), SO BE SURE TO OBSERVE THEM.

NOTE INDICATES AN AREA OR SUBJECT OF SPECIAL MERIT, EMPHASIZING EITHER THE PRODUCT`S CAPABILITIES OR COMMON ERRORS IN OPERATION OR MAINTENANCE.

HAZARDOUS HIGH VOLTAGE

- MOTOR CONTROL EQUIPMENT AND ELECTRONIC CONTROLLERS ARE CONNECTED TO THE HAZARDOUS LINE VOLTAGE.
- WHEN SERVICING VFD AND ELECTRONIC CONTROLLERS, THERE MIGHT BE EXPOSED COMPONENTS OR ABOVE LINE POTENTIAL.
- EXTREME CARE SHOULD BE TAKEN TO PRODUCT AGAINST SHOCK. STAND ON AN INSULATING PAD AND MAKE IT A HABIT TO USE ONLY ONE HAND WHEN CHECKING COMPONENTS.
- ALWAYS WORK WITH ANOTHER PERSON IN CASE AN EMERGENCY OCCURS.
- DISCONNECT POWER BEFORE CHECKING CONTROLLER OR PERFORMING MAINTENANCE.
- BE SURE EQUIPMENT IS PROPERLY GROUNDED. WEAR SAFETY GLASSES WHENEVER WORKING ON AN ELECTRIC CONTROLLER OR ROTATING ELECTRICAL EQUIPMENT.

PRECAUTION

- A SAFETY INSTRUCTION (MESSAGE) IS GIVEN WITH A HAZARD ALERT SYMBOL AND A WARNING or CAUTION.

WARNING THIS IS EQUIPMENT SHOULD BE INSTALLED, ADJUSTED AND SERVICED BY QUALIFIED ELECTRICAL MAINTENANCE PERSONAL FAMILIAR WITH THE CONSTRUCTION AND OPERATION OF THE EQUIPMENT AND THE HAZARDS INVOLVED. FAILURE TO OBSERVE THIS PRECAUTION COULD RESULTS IN BODILY INJURY.

WARNING THE USER IS RESPONSIBLE FOR ENSURING THAT ALL DRIVEN MACHINERY, DRIVE TRAIN MECHANISM NOT SUPPLIED BY HYUNDAI AND PROCESS LINE MATERIAL ARE CAPABLE OF SAFE OPERATION AT AN APPLIED FREQUENCY OF 150% OF THE MAXIMUM SELECTED FREQUENCY RANGE TO THE AC MOTOR. FAILURE TO DO SO CAN RESULT IN DESTRUCTION OF EQUIPMENT AND INJURY TO PERSONNEL SHOULD A SINGLE POINT FAILURE OCCUR.

WARNING FOR PROTECTION, INSTALL AN EARTH LEAKAGE BREAKER WITH A HIGH FREQUENCY CIRCUIT CAPABLE OF LARGE CURRENTS TO AVOID AN UNNECESSARY OPERATION.
THE GROUND FAULT PROTECTION CIRCUIT IS NOT DESIGNED TO PROTECT PERSONAL INJURY.

CAUTION HEAVY OBJECT. TO AVOID MUSCLE STRAIN OR BACK INJURY,
USE LIFTING AIDS AND PROPER LIFTING TECHNIQUES WHEN REMOVING OR REPLACING.

CAUTION THESE INSTRUCTIONS SHOULD BE READ AND CLEARLY UNDERSTOOD BEFORE WORKING ON iMASTER C1 SERIES EQUIPMENT.

CAUTION PROPER GROUNDS, DISCONNECTING DEVICES AND OTHER SAFETY DEVICES AND THEIR LOCATION ARE THE RESPONSIBILITY OF THE USER AND ARE NOT PROVIDED BY HYUNDAI.

CAUTION BE SURE TO CONNECT A MOTOR THERMAL SWITCH OR OVERLOAD DEVICES TO THE iMASTER C1 SERIES VFD TO ASSURE THAT INVERTER WILL SHUT DOWN IN THE EVENT OF AN OVERLOAD OR AN OVERHEATED MOTOR

CAUTION ROTATING SHAFTS AND ABOVE GROUND ELECTRICAL POTENTIALS CAN BE HAZARDOUS. THEREFORE, IT IS STRONGLY RECOMMENDED THAT ALL ELECTRICAL WORK CONFORM TO THE NATIONAL ELECTRICAL CODES AND LOCAL REGULATIONS.
ONLY QUALIFIED PERSONNEL SHOULD PERFORM INSTALLATION, ALIGNMENT AND MAINTENANCE. FACTORY RECOMMENDED TEST PROCEDURES, INCLUDED IN THE INSTRUCTION MANUAL, SHOULD BE FOLLOWED.
ALWAYS DISCONNECT ELECTRICAL POWER BEFORE WORKING ON THE UNIT.

NOTE: POLLUTION DEGREE 2

- THE VFD MUST BE USED IN THE ENVIRONMENT OF THE POLLUTION DEGREE 2.
- TYPICAL CONSTRUCTIONS THAT REDUCE THE POSSIBILITY OF CONDUCTIVE POLLUTION ARE,

1) THE USE OF AN UNVENTILATED ENCLOSURE.
2) THE USE OF A FILTERED VENTILATED ENCLOSURE WHEN THE VENTILATION IS FAN FORCED THAT IS, VENTILATION IS ACCOMPLISHED BY ONE OR MORE BLOWERS WITHIN THE ENCLOSURE THAT PROVIDE A POSITIVE INTAKE AND EXHAUST.

CAUTION FOR EMC (ELECTROMAGNETIC COMPATIBILITY)

TO SAFELY FOLLOW THE EMC DIRECTIVE AND TO COMPLY WITH STANDARDS, FOLLOWS THE CHECK LIST BELOW.

WARNING

THIS EQUIPMENT SHOULD BE INSTALLED, ADJUSTED, AND SERVICED BY QUALIFIED PERSONAL FAMILIAR WITH CONSTRUCTION AND OPERATION OF THE EQUIPMENT AND THE HAZARDS INVOLVED. FAILURE TO OBSERVE THIS PRECAUTION COULD RESULT IN BODILY INJURY.

1. THE POWER SUPPLY TO iMASTER C1 INVERTER MUST MEET THESE SPECIFICATIONS
   a. VOLTAGE FLUCTUATION: ± 10% OR LESS.
   b. VOLTAGE IMBALANCE: ± 3% OR LESS.
   c. FREQUENCY VARIATION: ± 4% OR LESS.
   d. VOLTAGE DISTORTION: THD = 10% OR LESS

2. INSTALLATION MEASURE :
   a. USE A FILTER DESIGNED FOR iMASTER C1 INVERTER

3. WIRING
   a. SHIELDED WIRE (SCREENED CABLE) IS REQUIRED FOR MOTOR WIRING, AND THE LENGTH MUST BE LESS THAN 20 METERS.
   b. THE CARRIER FREQUENCY SETTING MUST BE LESS THAN 5KHZ TO SATISFY EMC REQUIREMENTS.
   c. SEPARATE THE MAIN CIRCUIT FROM THE SIGNAL/PROCESS CIRCUIT WIRING.
   d. IN CASE OF REMOTE OPERATING WITH CONNECTOR CABLE, THE INVERTER DOES NOT CONFORM TO EMC

4. ENVIRONMENTAL CONDITIONS – WHEN USING A FILTER, FOLLOW THESE GUIDELINES:
   a. AMBIENT AIR TEMPERATURE: -10 - +50℃
   b. HUMIDITY : 20 TO 90% RH(NON-CONDENSING)
   c. VIBRATION : 5.9 M/S^2 (0.6G) 10 – 55HZ ((iMASTER C1-0.4kW(0.5 HP) ~ 350kW(468 HP)
   d. LOCATION : 1000 METERS OR LESS ALTITUDE, INDOORS
      (NO CORROSIVE GAS OR DUST)

CONFORMITY TO THE UNDERVOLTAGE DIRECTIVE (UVD)

THE PROTECTIVE ENCLOSURE MUST CONFORM TO THE UNDERVOLTAGE DIRECTIVE.
THE VFD CAN CONFORM TO THE UVD BY MOUNTING INTO A CABINET OR BY ADDING COVERS AS FOLLOWS.

CABINET AND COVER

THE VFD MUST BE INSTALLED INTO A CABINET WHICH HAS THE PROTECTION DEGREE OF TYPE IP2X.
IN ADDITION THE TOP SURFACES OF CABINET ARE EASILY ACCESSIBLE SHALL MEET AT LEAST THE REQUIREMENTS OF THE PROTECTIVE TYPE IP4X, OR WHICH IS CONSTRUCTED TO PREVENT SMALL OBJECTS FROM ENTERING INVERTER.

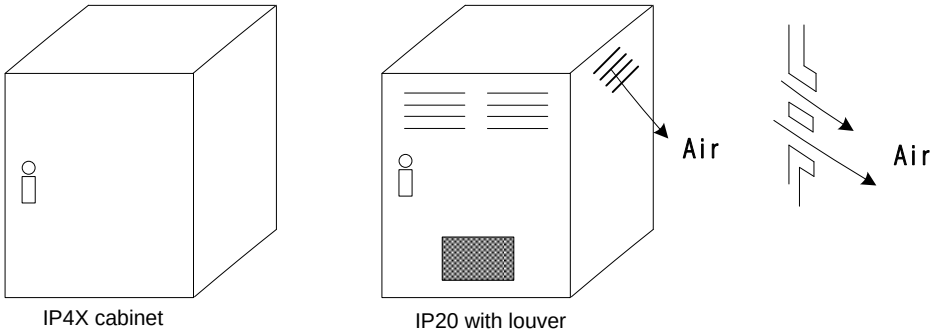


Fig 1. INVERTER CABINET

UL WARNINGS AND CAUTIONS MANUAL FOR iMASTER C1 SERIES

- THIS AUXILIARY INSTRUCTION MANUAL SHOULD BE DELIVERED TO THE END USER.

1. WIRE MARKING FOR ELECTRICAL PRACTICE AND WIRE SPECIFICATIONS

"USE COPPER CONDUCTOR ONLY, 75℃WITH A TORQUE RATING.

2. TIGHTENING TORQUE AND WIRE RANGE

TIGHTENING TORQUE AND WIRE RANGE FOR FIELD WIRING TERMINALS ARE MARKED ADJACENT TO THE TERMINAL OR ON THE WIRING DIAGRAM.

MODEL NAME IMASTER C1	TIGHTENING TORQUE [LB-IN]	WIRE RANGE		RING TERMINALSIZE MAXIMUM WIDTH [inch]
		AWG	kcmil	
iMASTER C1 -004SF	8.7	14	4.1	0.228
iMASTER C1 -004LF	8.7	14	4.1	0.228
iMASTER C1 -007SF	8.7	14	4.1	0.228
iMASTER C1 -007LF	8.7	14	4.1	0.228
iMASTER C1 -015SF	15.9	12	6.5	0.315
iMASTER C1 -015LF	8.7	14	4.1	0.228
iMASTER C1 -022SF	15.9	10	10.4	0.315
iMASTER C1 -022LF	15.9	12	6.5	0.315
iMASTER C1 -037LF	15.9	10	10.4	0.315
iMASTER C1 -004HF	15.9	14	4.1	0.315
iMASTER C1 -007HF	15.9	14	4.1	0.315
iMASTER C1 -015HF	15.9	14	4.1	0.315
iMASTER C1 -022HF	15.9	14	4.1	0.315
iMASTER C1 -037HF	15.9	12	6.5	0.315
iMASTER C1 -055LF	12.4	8	16.5	0.4
iMASTER C1 -075LF	12.4	8	16.5	0.4
iMASTER C1 -110LF	26.6	6	41.7	0.51
iMASTER C1 -150LF	26.6	4	41.7	0.51
iMASTER C1 -055HF	12.4	12	6.53	0.4
iMASTER C1 -075HF	12.4	10	10.4	0.4
iMASTER C1 -110HF	26.6	8	16.5	0.51
iMASTER C1 -150HF	26.6	8	16.5	0.51
iMASTER C1 -185HF	26.6	8	16.5	0.51
iMASTER C1 -220HF	26.6	6	26.3	0.51
iMASTER C1 -300HF	35.4	4	-	17
iMASTER C1 -370HF	35.4	2	-	17
iMASTER C1 -450HF	58.4	1	-	22
iMASTER C1 -550HF	58.4	2/0	-	22
iMASTER C1 -750HF	58.4	4/0	-	29
iMASTER C1 -900HF	58.4	-	300 (kcmil)	29
iMASTER C1 -1100HF	105.7	-	350 (kcmil)	30
iMASTER C1 -1320HF	105.7	-	400 (kcmil)	30
iMASTER C1 -1600HF	113	4/0*2P	-	38
iMASTER C1 -1850HF	113	-	300 (kcmil)*2P	38
iMASTER C1 -2200HF	113		300 (kcmil)*2P	38
iMASTER C1 -2800HF	113	4/0*4P	-	38
iMASTER C1 -3500HF	113	-	300 (kcmil)*4P	38

3. FUSE SIZE

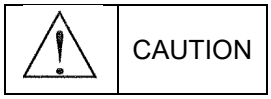
DISTRIBUTION FUSE SIZE INFORMATION IS SHOWN IN THE TABLE BELOW. THE FUSE MUST BE A UL LISTED, 600V, INVERSE TIME RATED FUSE WITH THE CURRENT RATINGS SHOWN BELOW

MODEL NAME	FUSE [A]
iMASTER C1 -004SF	10
iMASTER C1 -004LF	6
iMASTER C1 -007SF	15
iMASTER C1 -007LF	10
iMASTER C1 -015SF	25
iMASTER C1 -015LF	15
iMASTER C1 -022SF	30
iMASTER C1 -022LF	20
iMASTER C1 -037LF	30
iMASTER C1 -004HF	3
iMASTER C1 -007HF	6
iMASTER C1 -015HF	10
iMASTER C1 -022HF	15
iMASTER C1 -037HF	20
iMASTER C1 -055LF	30
iMASTER C1 -075LF	40
iMASTER C1 -110LF	60
iMASTER C1 -150LF	80
iMASTER C1 -055HF	15
iMASTER C1 -075HF	20
iMASTER C1 -110HF	30
iMASTER C1 -150HF	40
iMASTER C1 -185HF	50
iMASTER C1 -220HF	60
iMASTER C1 -300HF	80
iMASTER C1 -370HF	100
iMASTER C1 -450HF	125
iMASTER C1 -550HF	150
iMASTER C1 -750HF	200
iMASTER C1 -900HF	250
iMASTER C1 -1100HF	300
iMASTER C1 -1320HF	400
iMASTER C1 -1600HF	500
iMASTER C1 -1850HF	800
iMASTER C1 -2200HF	800
iMASTER C1 -2800HF	1200
iMASTER C1 -3500HF	1200

General Safety Information

A SAFETY INSTRUCTION (MESSAGE) INCLUDES A HAZARD ALERT SYMBOL AND A SIGNAL WORD, DANGER OR CAUTION. EACH SIGNAL WORD HAS THE FOLLOWING MEANING:
THIS SYMBOL IS THE “SAFETY ALERT SYMBOL.” IT OCCURS WITH EITHER OF TWO SIGNAL WORDS: DANGER OR CAUTION, AS DESCRIBED BELOW.

: INDICATES A POTENTIALLY HAZARDOUS SITUATION WHICH, IF NOT AVOIDED, CAN RESULT IN SERIOUS INJURY OR DEATH.



: INDICATES A POTENTIALLY HAZARDOUS SITUATION WHICH, IF NOT AVOIDED, CAN RESULT IN MINOR TO MODERATE INJURY, OR SERIOUS DAMAGE TO THE PRODUCT.

THE SITUATION DESCRIBED IN THE CAUTION MAY, IF NOT AVOIDED, LEAD TO SERIOUS RESULTS. IMPORTANT SAFETY MEASURES ARE DESCRIBED IN CAUTION (AS WELL AS DANGER), SO BE SURE TO OBSERVE THEM.

⚠CAUTION

- All illustrations in this handbook may be depicted with the cover or blockage removed to explain the details.
  When operating the machine, operate the machine in accordance with the handling manual, with the specified covers.
- No notification is given if the contents change due to product improvement or manual re-organization. The changes are indicated by the number in the revised manual.
- If you have lost or damaged the manual, please contact your dealer or your nearest dealer.
- Product damage caused by user arbitrary operation is not within the scope of maintenance and is not liable for it.

General Safety Information

1. Installation

⚠ CAUTION

- Be sure to install the unit on flame resistant material such as metal.
- Be sure not to place anything highly flammable in the vicinity.
- Do not carry unit by top cover, always carry by supporting base of unit.
- Be sure not to let foreign matter enter VFD such as cut wire refuse, spatter from welding, iron refuse, wire, dust, etc.
- Be sure to install inverter in a place which can support the weight according to the specifications in the text. (Chapter 2. Installation)
- Be sure to install the unit on a perpendicular wall which is not subject to vibration
- Be sure not to install and operate a VFD which is damaged or has parts which are missing.
- Be sure to install the inverter in an area which is not exposed to direct sunlight and is well ventilated. Avoid environments which tend to be high in temperature, high in humidity or to have condensation, as well as places with dust, corrosive gas, explosive gas, highly flammable gas, grinding-fluid mist, salt damage, etc.

2. Wiring

⚠ CAUTION

- Be sure to ground the unit.
  Electrical wiring work should be carried out by qualified electricians.
- Do the wiring work by an electrician.
  There is a possibility of electric shock and fire.
- Check the input power OFF before wiring.
  There is a possibility of electric shock and fire.
- Be sure to attach the main body and wire it.

There are concerns of electric shock and injury.

General Safety Information

⚠ CAUTION

- Make sure that the rated voltage and AC power voltage of the product match.
  There are concerns about accidents and fires.
- Do not use single phase input.
  There is a fire hazard.
- Do not connect AC power to the output terminals (U,V,W).
  Risk of injury and fire.
- Tighten to the specified torque of the screw. Check that the screws are not loose.
  There is a fire hazard.
- Install a short circuit breaker on the input side.
  There is a fire hazard.
- Install the fuse in the operating circuit (same as main power).
  There is a fire hazard.
- Use power lines, short-circuit breakers and electronic contactors at the specified capacity (qualification).
  There is a fire hazard.

3. Control and Operation

⚠ CAUTION

- Be sure to put the input power after you remove the front cover.
  Do not open the cover while it is energized.
  There is a possibility of electric shock.
- Do not operate the switch with wet hands.
  There is a possibility of electric shock.
- Do not contact the inverter terminals during powering or shutdown of the inverter.
  There is a possibility of electric shock.
- If retriever mode is selected, a sudden restart will occur even the inverter stopped by trip.
  (Please designed a machine can protect with retriever mode.)
  Please keep away from the machine. There are concerns of an accident.
- If a short power outage occurs, the driver's command can be entered to re-run after the power outage. If there is a possibility of danger to a person, use the circuit that is not re-driving after power-up. There are concerns of an accident.
- STOP keys are valid only when the function is set.
  Prepare the emergency stop switch separately. There are concerns of an accident.
- Do not set the alarm reset with the operation command together, it will re-start without caution.
  Make sure operation command is off and set the alarm rest.
  There are concerns of an accident.
- Do not put any contacts or sticks inside the inverter while it is on.
  There is a possibility of electric shock and fire.

General Safety Information

⚠ CAUTION

- The heat sink fins will have a high temperature. Be sure not to touch them..
  There is a risk of burns.
- Low to high speed operation of the inverter can be easily set. Be sure to operate it after checking the tolerance of the motor and machine.
  There are concerns of an accident.
- Install an external braking system if needed.
  There are concerns of an accident.
- If the motor needs to operate at a frequency higher than standard Max Frequency setting (50Hz/60Hz), be sure to check with the manufacturers of both the motor and the machine for their approval.
  There is a concern of machine failure.
- Check the following before and during the test run.
  Was the direction of the motor correct?
  Were the RPM and frequency motor correct?
  Were there any abnormal motor vibrations or noises?
- The AC reactor must be installed when the power is not stable in order to avoid damage to the VFD.
- Do not switch drive inputs when starting or stopping the motor.
  Turning the drive on and off often shortens the life of the drive.
  Damage to the DC bus charging circuit and the DC bus capacitor may result in premature drive failure.
  For maximum performance, the maximum number of charging cycles (i.e. power-up by power supply) of the DC capacitor is:
  Less than five times in ten minutes.

4. Maintenance, Inspection and Part Replacement

⚠ CAUTION

- After turning off the input power supply, do not perform the maintenance and inspection for at least 10 minutes.
  There is a possibility of electric shock.
- Make sure that only qualified persons will perform maintenance, inspection and/or part replacement.
  (Before starting the work, remove metallic objects (wristwatch, bracelet, etc.)
  (Be sure to use insulated tools.)

5. Others

⚠ CAUTION

- Never modify the unit.
  There is a possibility of electric shock and accident.

CONTENTS

1. GENERAL INFORMATION

1.1 Inspection on purchase

1.1.1 Product inspection

Please inspect following before installation.

(1) No damage made to the unit during transportation?
(2) One Instruction manual is enclosed?
(0.4kw to 3.7kw inverter Instruction manual is not enclosed, Instruction manual can be viewed as a QR code.)
(3) Check the label specification if the correct product is delivered per your order.

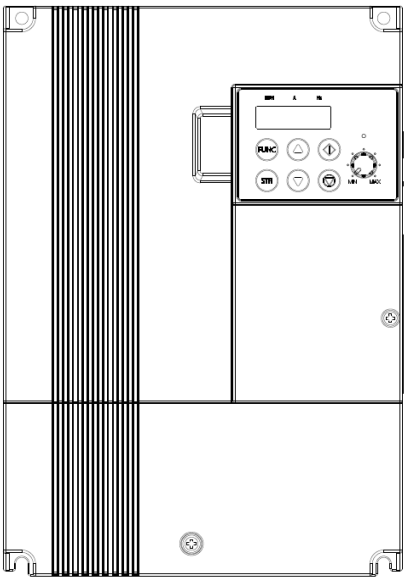


Figure 1-1 Outlook of iMASTER C1

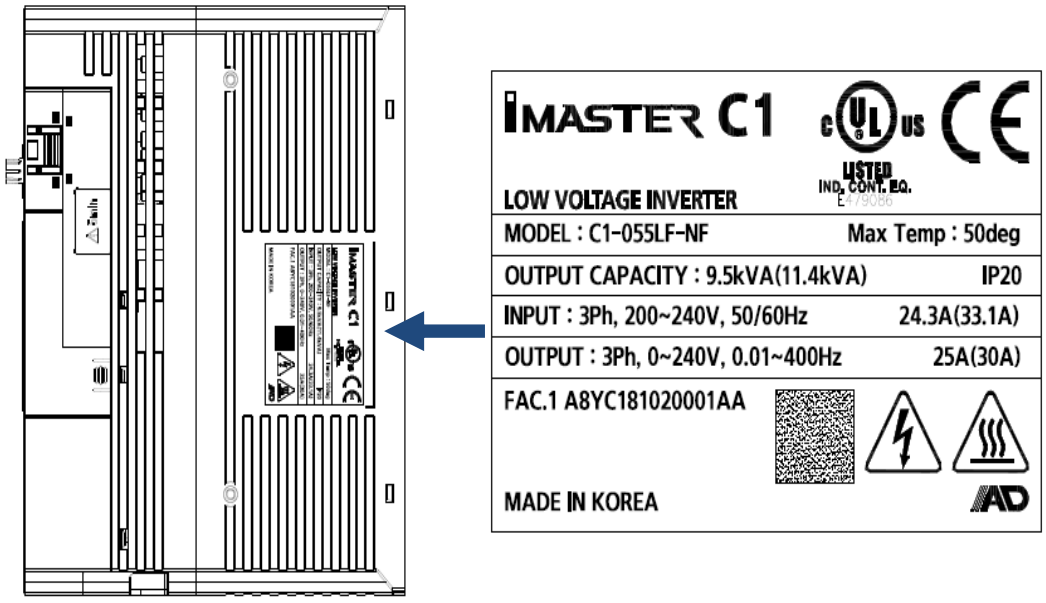


Figure 1-2 iMASTER C1 Specification on label

1.1.2 Instruction manual

This instruction manual is for the iMASTER C1 series.
Carefully read the manual before operating the inverter and please read this manual and keep it as a reference.
In addition, this manual is intended to be delivered to the final user.

1.2 Inquiry and warranty

1.2.1 Inquiry

• If you have any questions about damage to the inverter, unknown parts, or other information, please contact the place of purchase with the following information.
(1) Product model name
(2) Manufacturing number (MFG. No.)
(3) Date of purchase
(4) Failure details (as detailed as possible)
Damaged parts, condition, etc.
Unknown parts, condition, etc.

1.2.2 Warranty of unit

• The warranty period for the delivery product is one year after delivery.
However, the warranty will be void if the fault is due to;
(1) In case of unfair treatment and use by the consumer
(2) If the cause of failure is due to a reason other than the product supplied
(3) When using a product that is out of specification
(4) In case the supplier is not responsible for other natural disasters (earthquake, lightning)

• Since the warranty mentioned here means the inverter itself, the damage caused by the inverter failure shall not be liable.

• After warranty period, the entire test or repair will be charged.
Any failure caused by above mentioned items within the warranty period will be claimed.
Please contact your place of purchase for any problems that have occurred within the warranty period

1.3 Panel view

1.3.1 iMASTER C1-004SF~007SF, 004LF~015LF

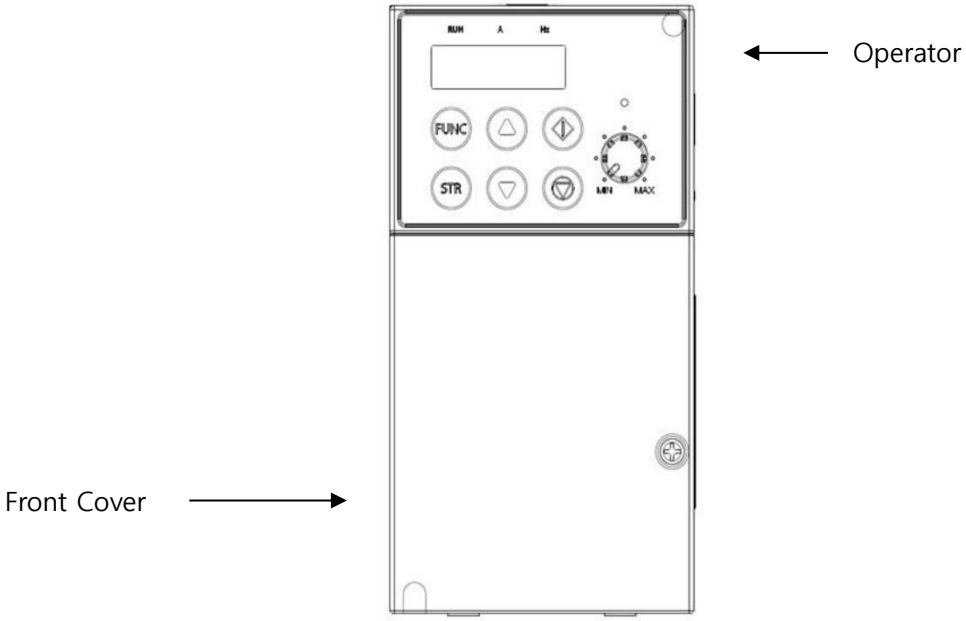


Figure 1-3 Front view with front cover

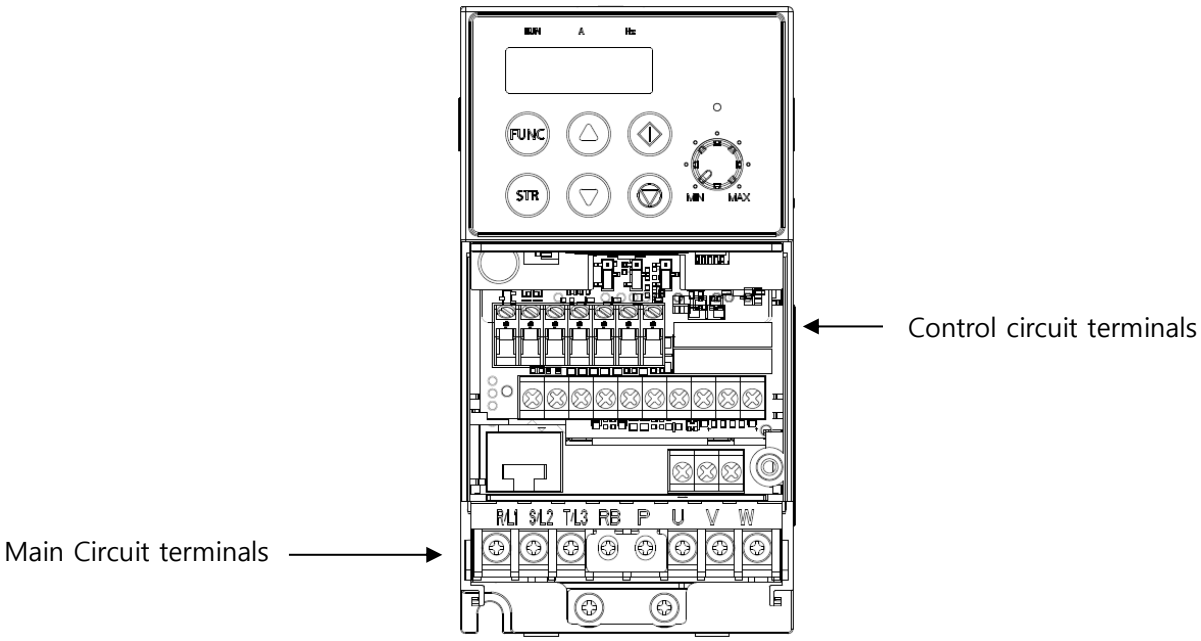


Figure 1-4 Front view without front cover

1.3.2 iMASTER C1-015SF~022SF, 022LF, 004HF~022HF

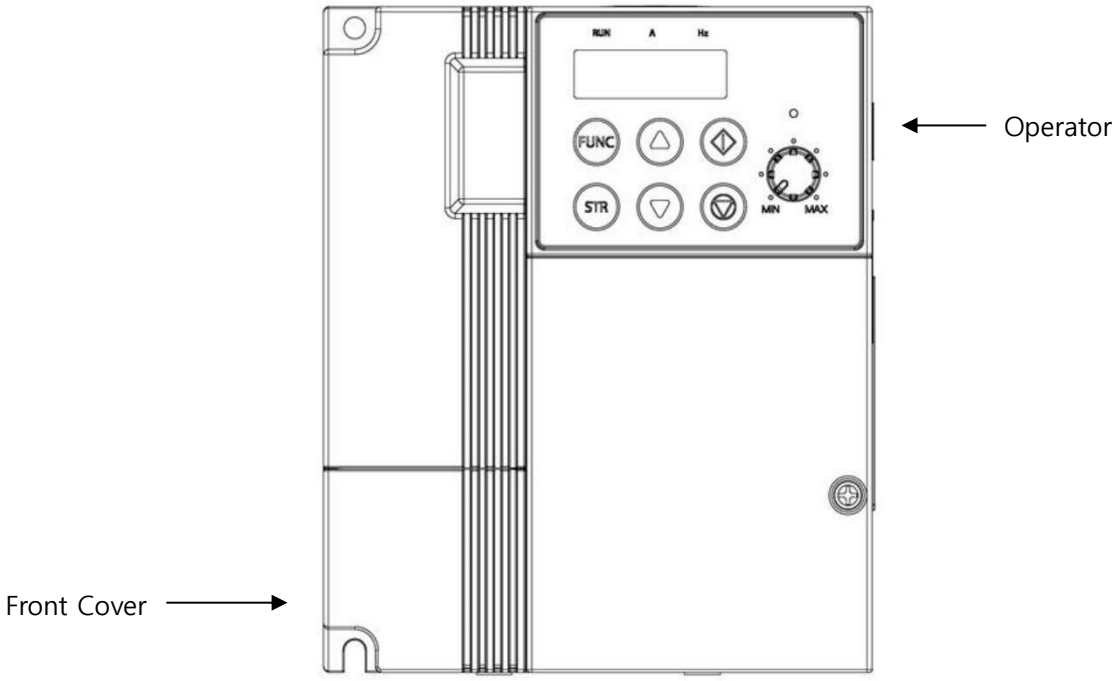


Figure 1-5 Front view with front cover

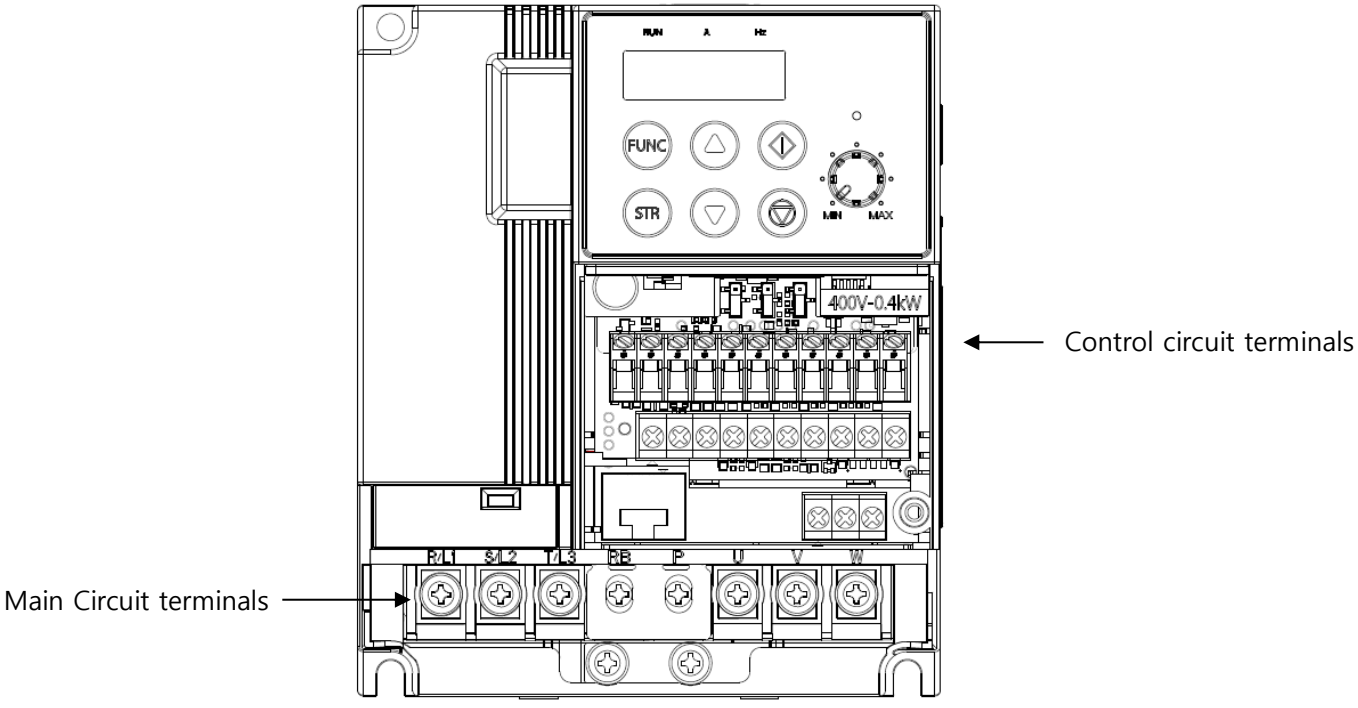


Figure 1-6 Front view with front cover

1.3.3 iMASTER C1-037LF, 037HF

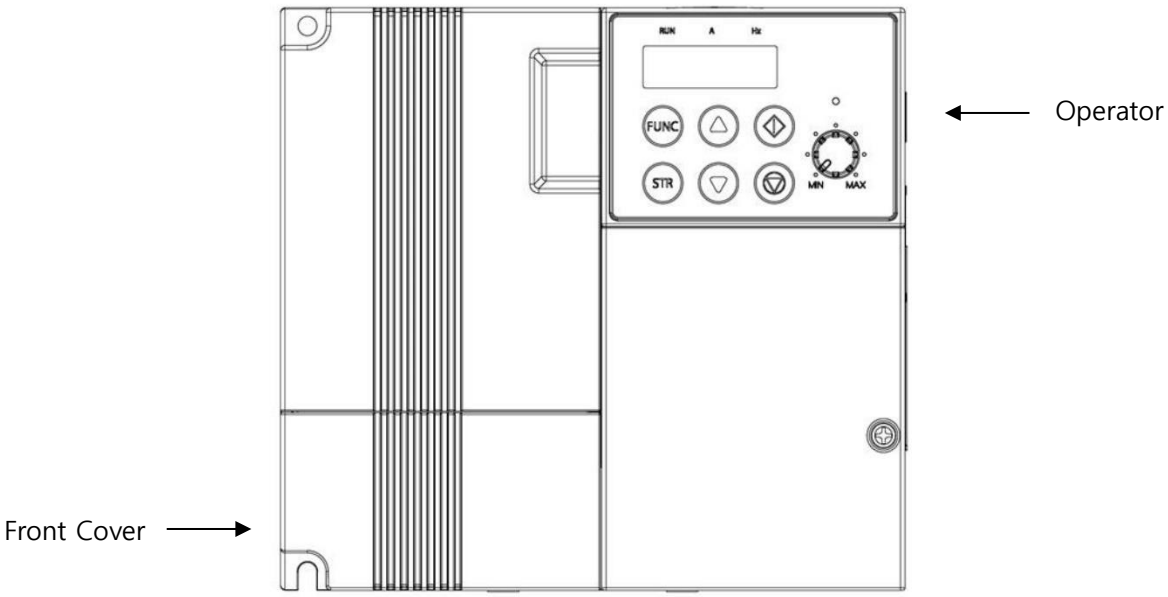


Figure 1-7 Front view with front cover

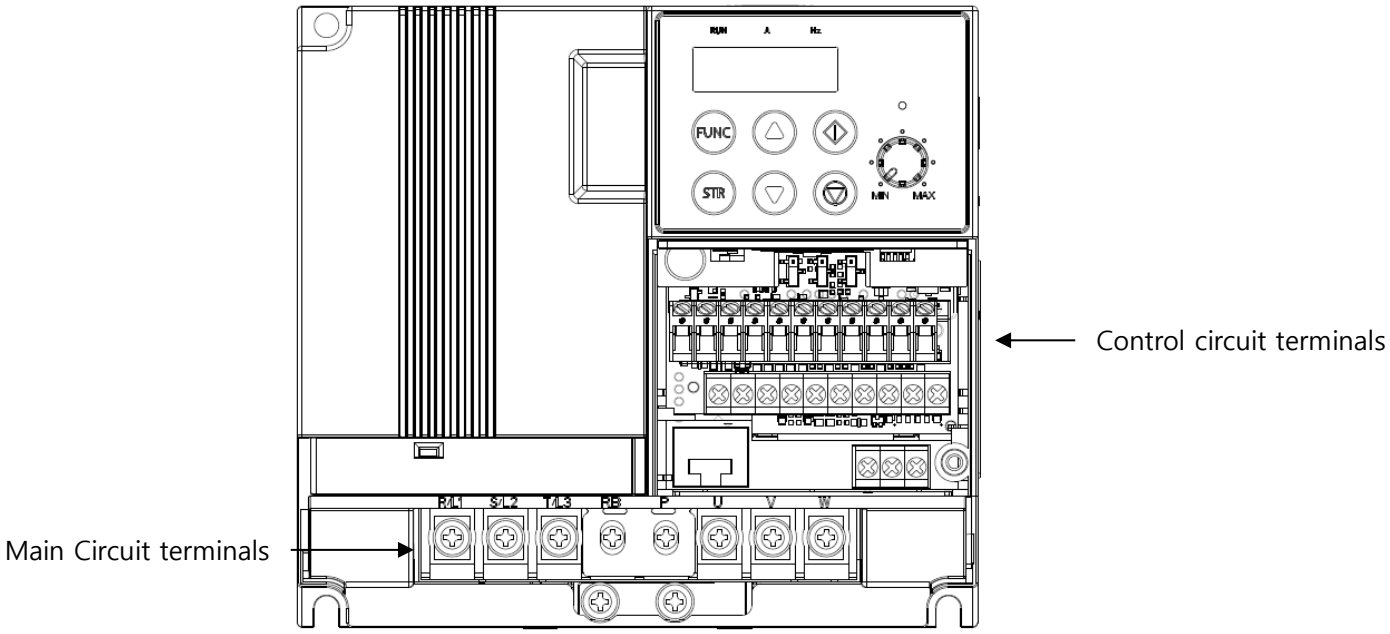


Figure 1-8 Front view without front cover

1.3.4 iMASTER C1-055LF ~ 075LF, 055HF ~ 075HF

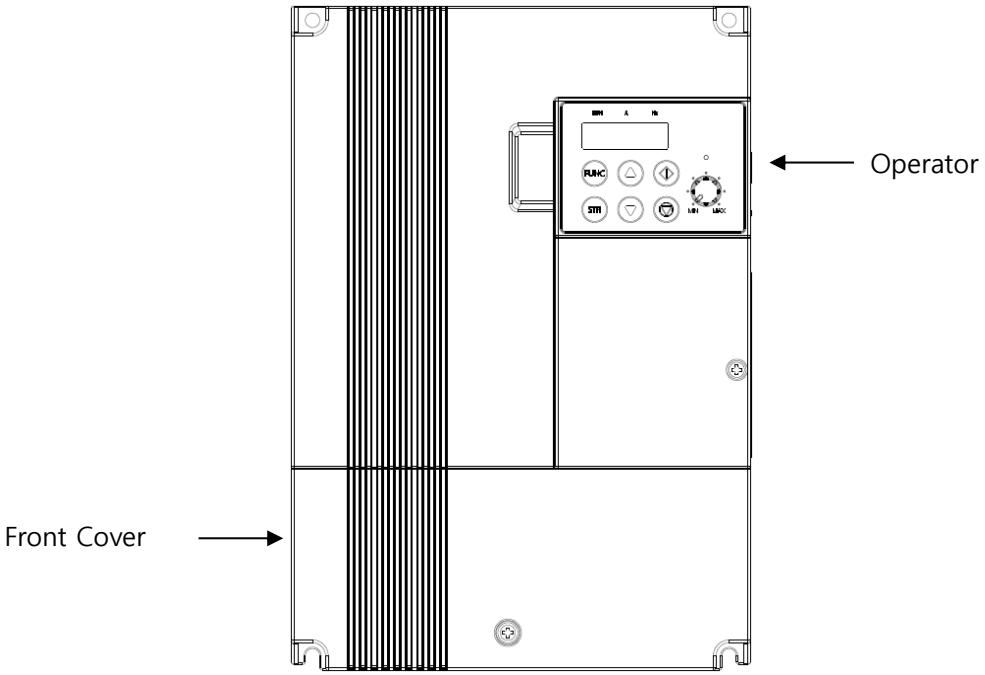


Figure 1-9 Front view with front cover

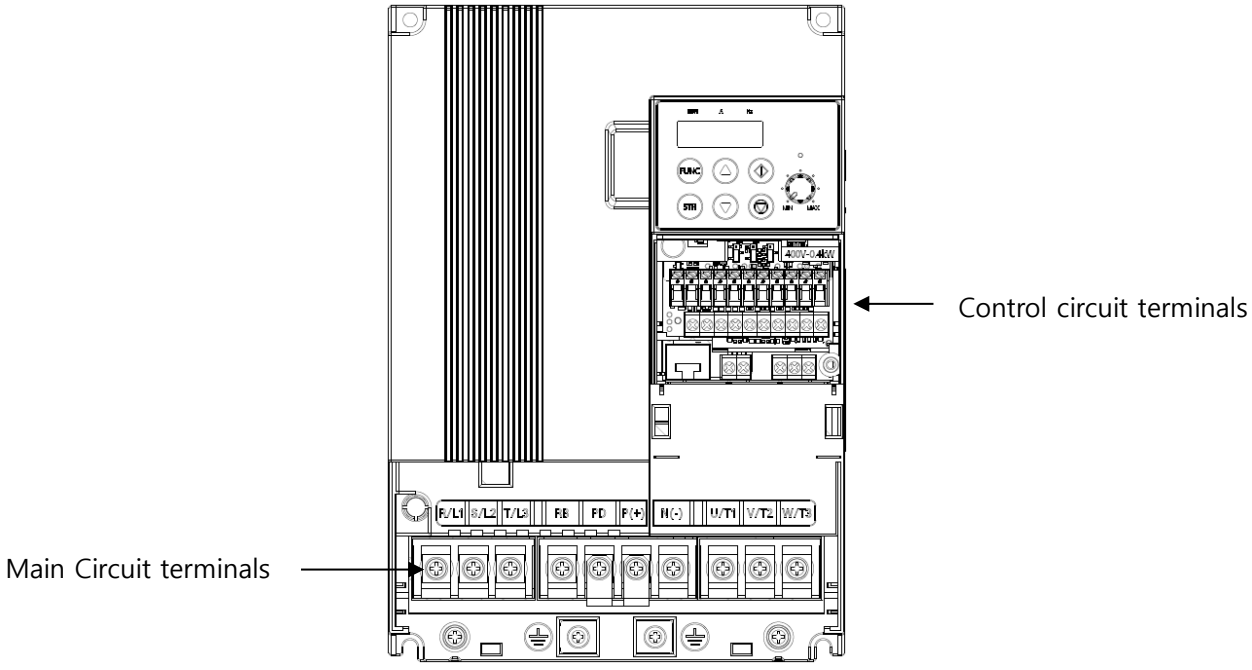


Figure 1-10 Front view without front cover

1.3.5 iMASTER C1-110LF, 110HF ~ 150HF

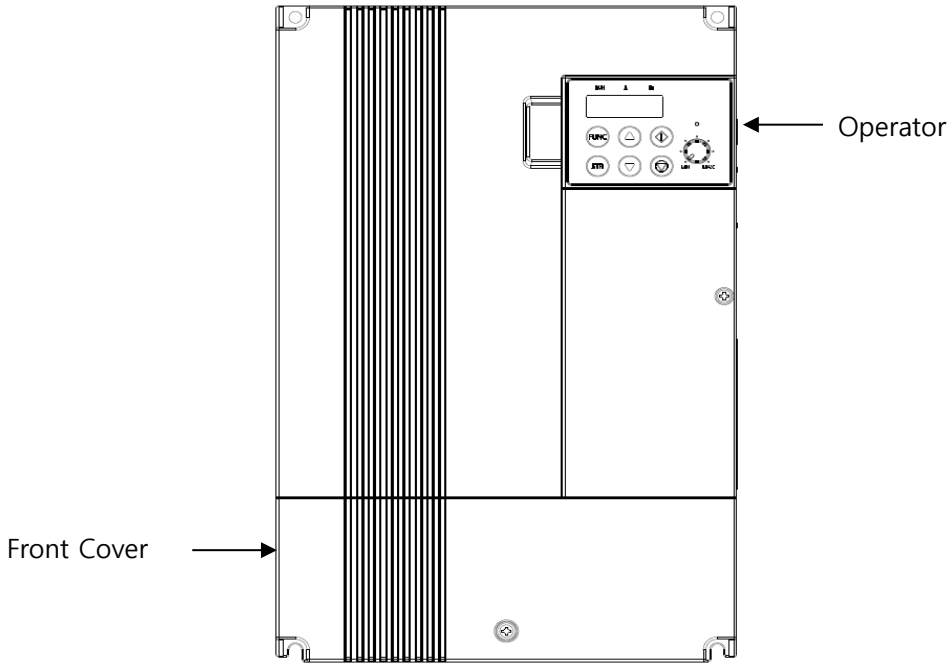


Figure 1-11 Front view with front cover

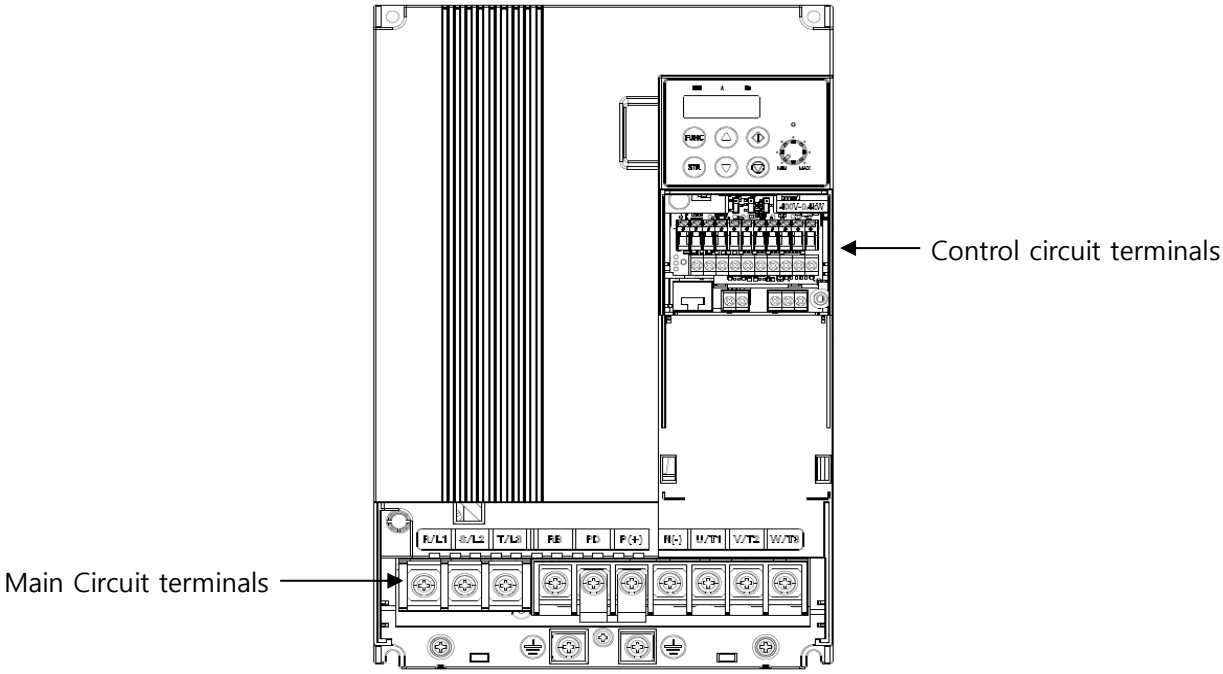


Figure 1-12 Front view without front cover

1.3.6 iMASTER C1-150LF, 185HF ~ 220HF

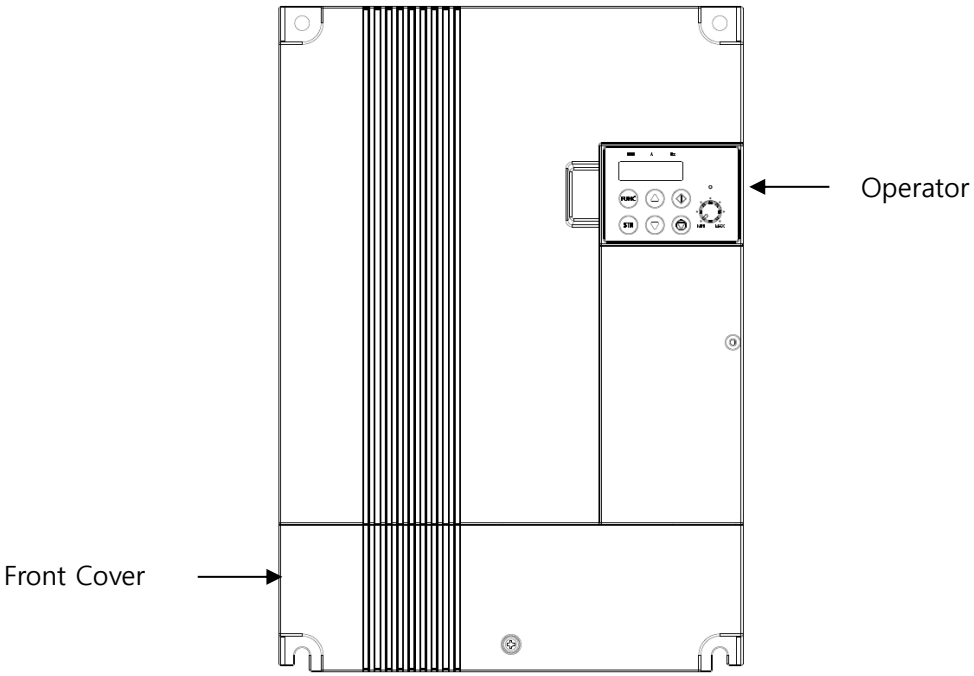


Figure 1-13 Front view with front cover

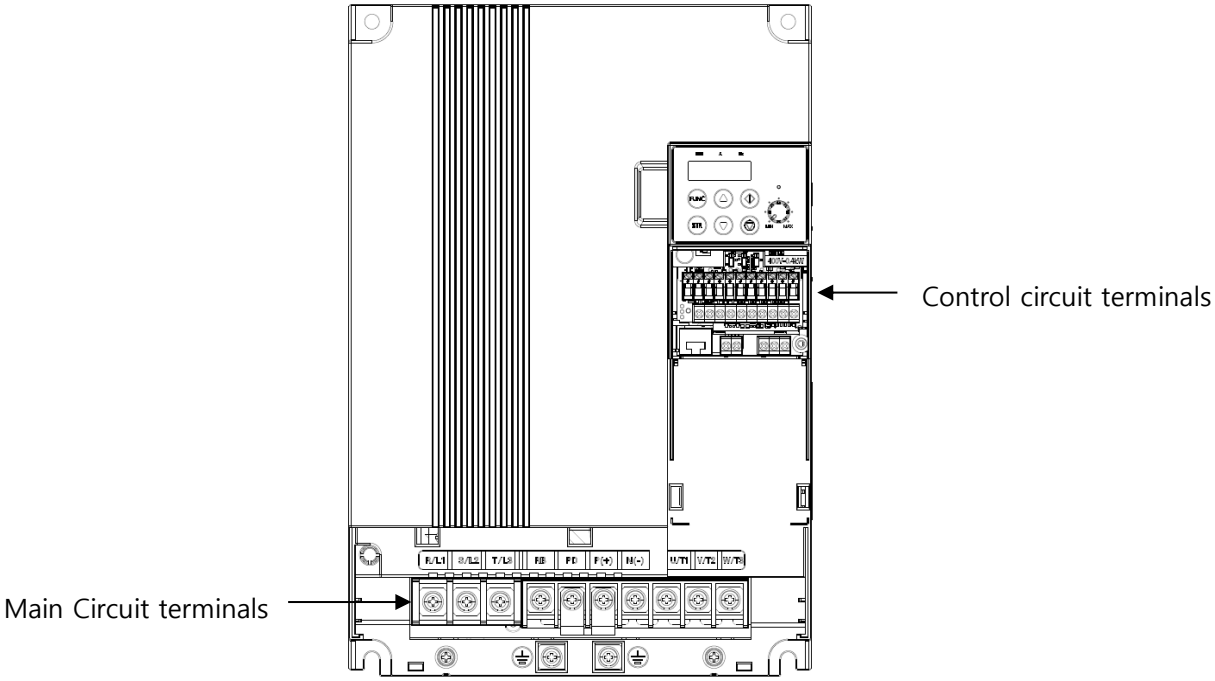


Figure 1-14 Front view without front cover

1.3.7 iMASTER C1-300HF ~ 370HF

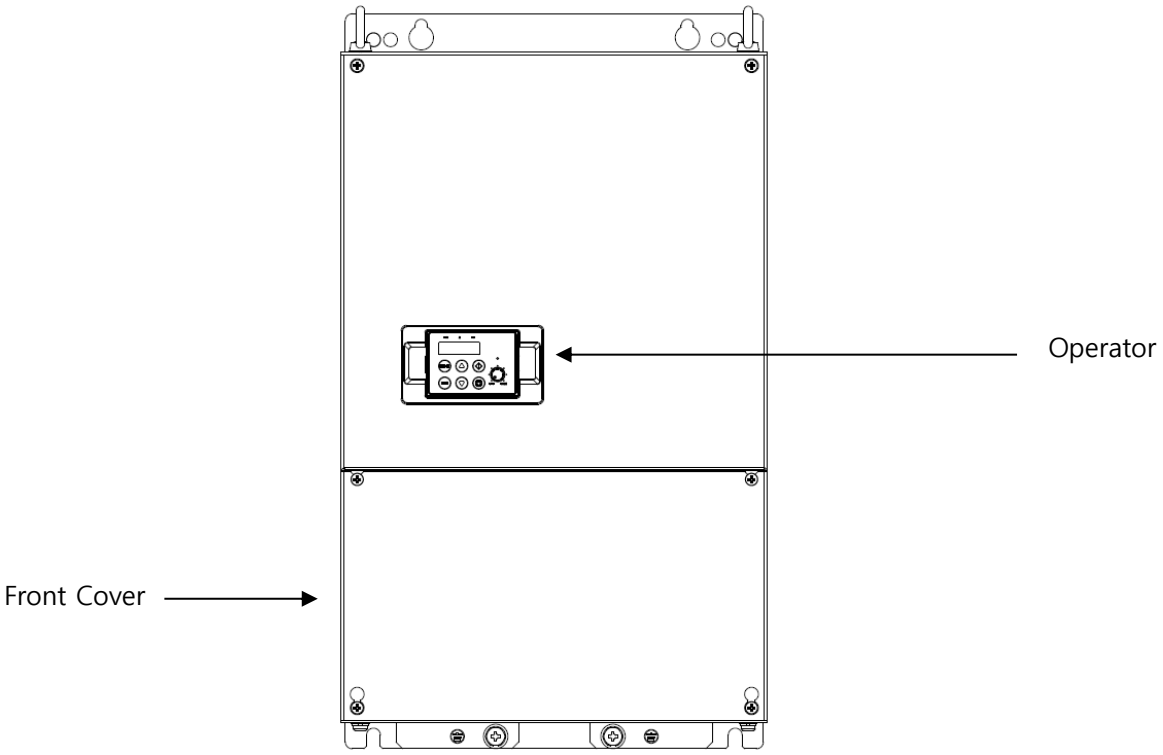


Figure 1-15 Front view with front cover

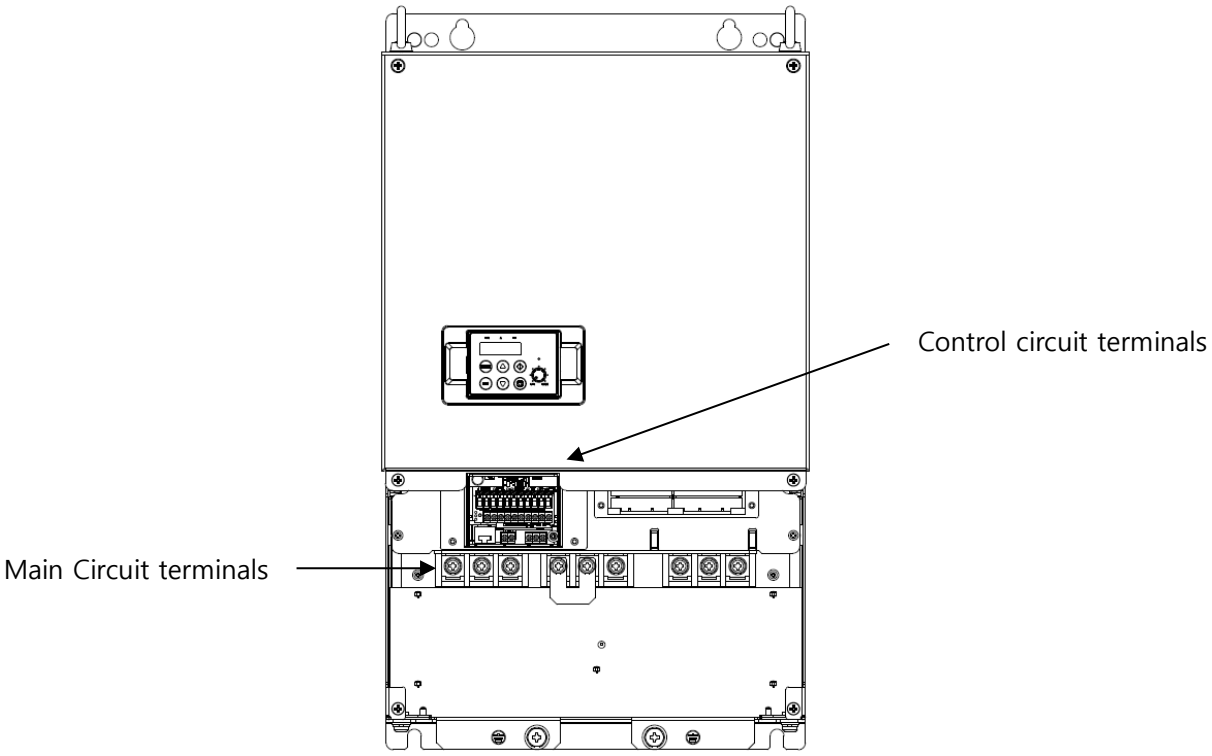


Figure 1-16 Front view without front cover

1.3.8 iMASTER C1-450HF ~ 550HF

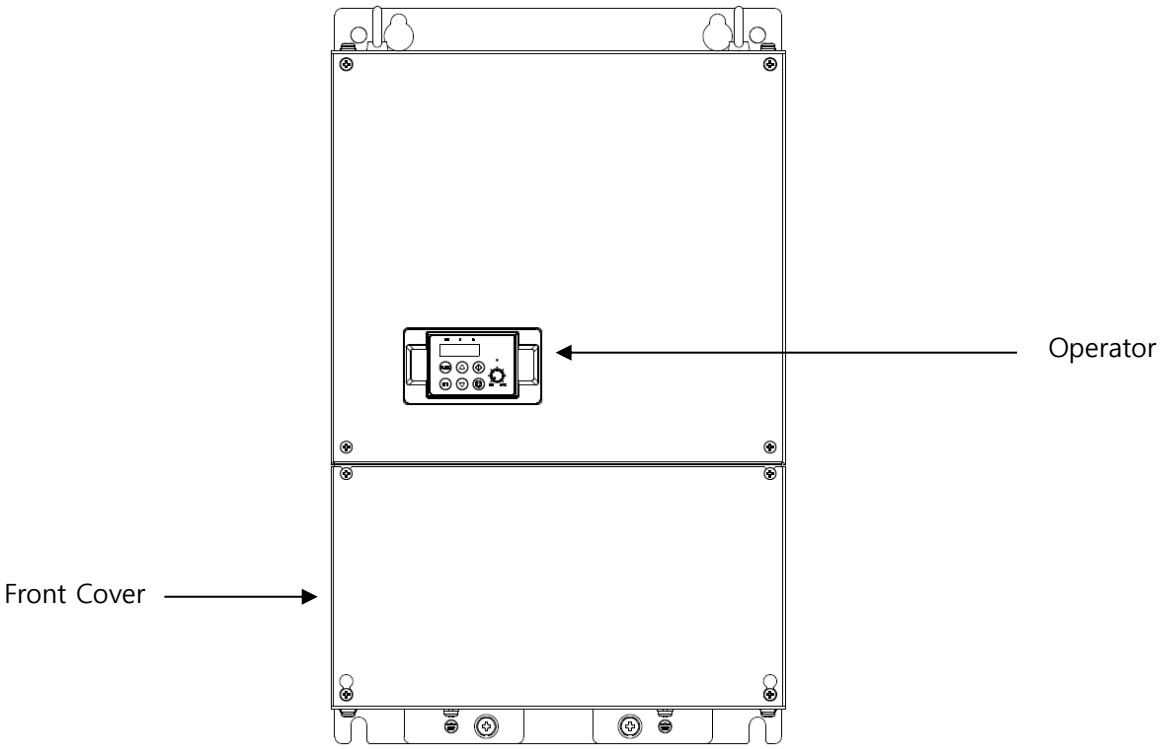


Figure 1-17 Front view with front cover

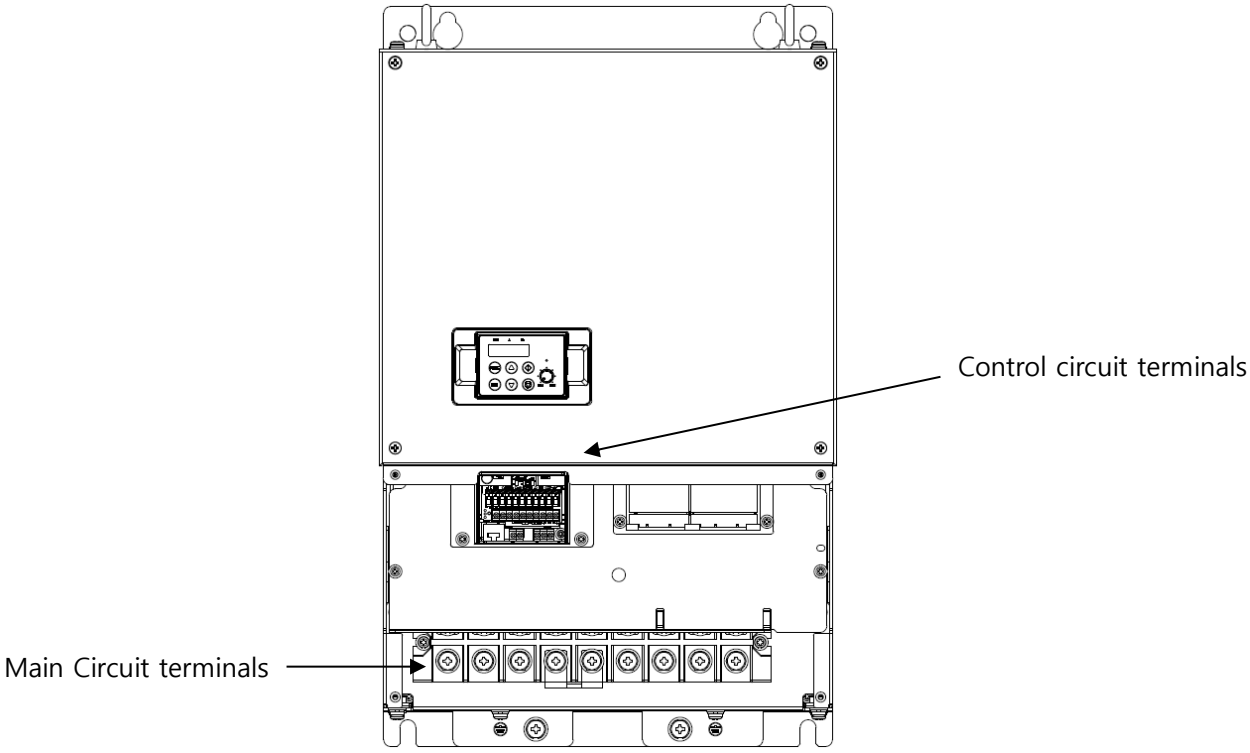


Figure 1-18 Front view without front cover

1.3.9 iMASTER C1-750HF ~ 900HF

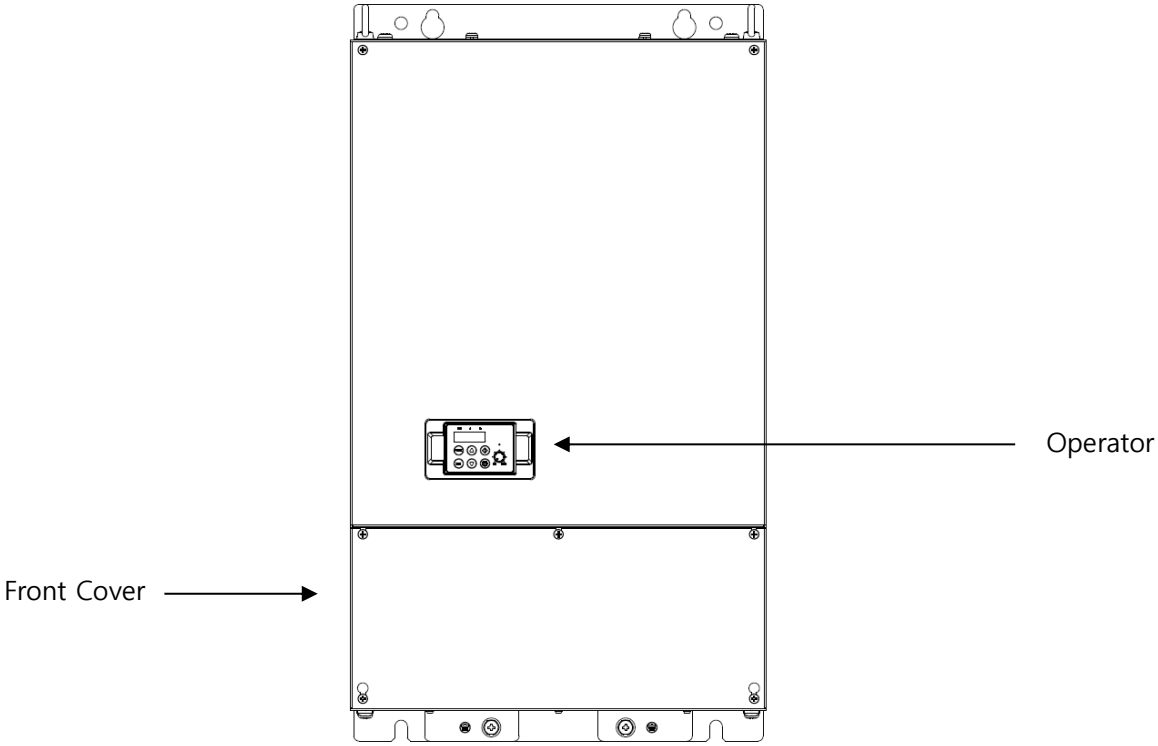


Figure 1-19 Front view with front cover

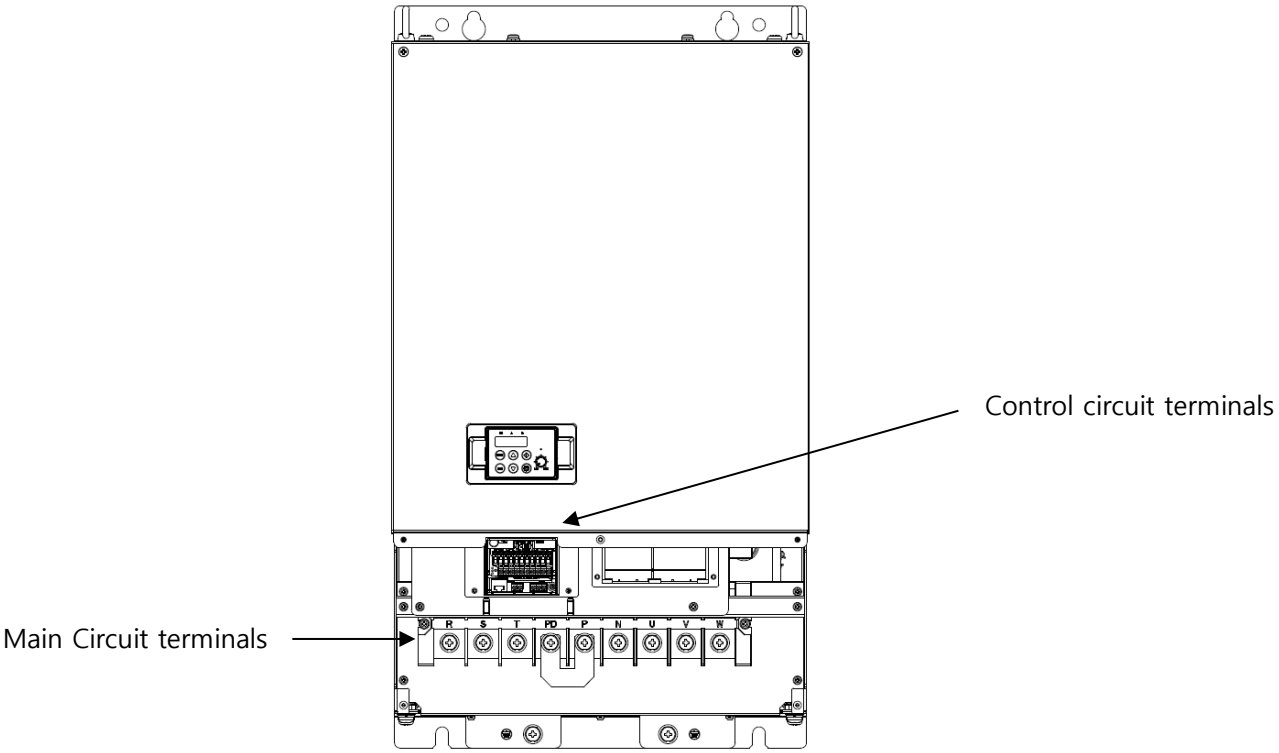


Figure 1-20 Front view without front cover

1.3.10 iMASTER C1-1100HF ~ 1600HF

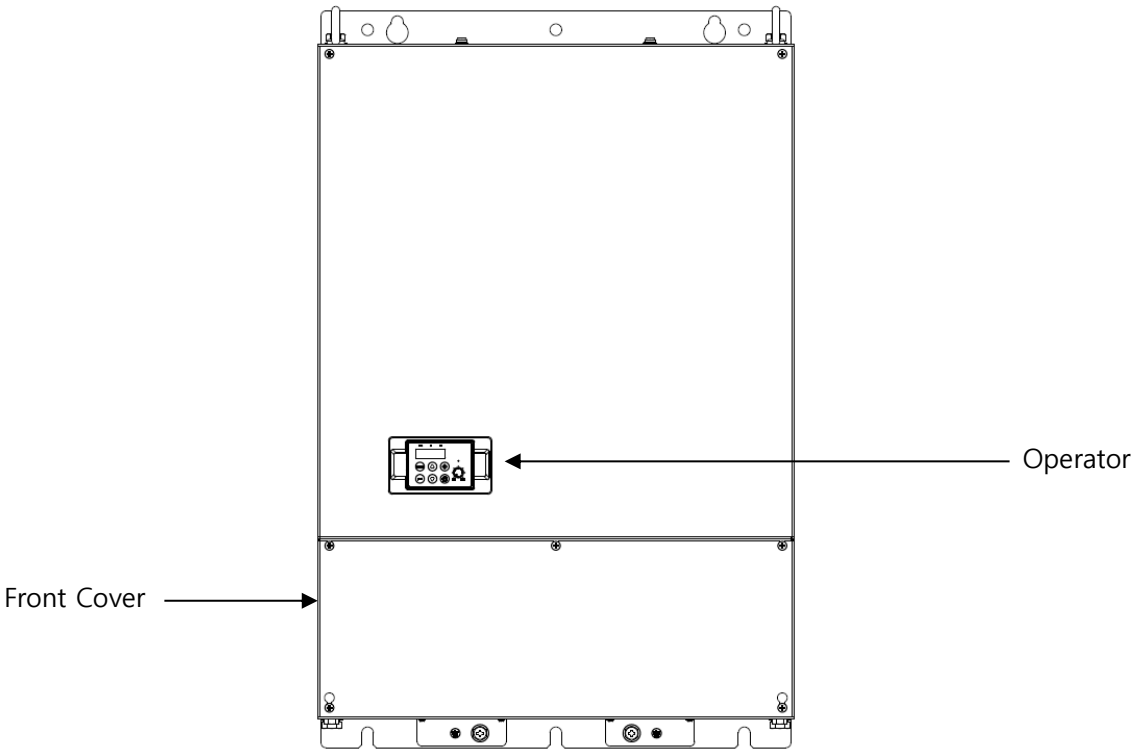


Figure 1-21 Front view with front cover

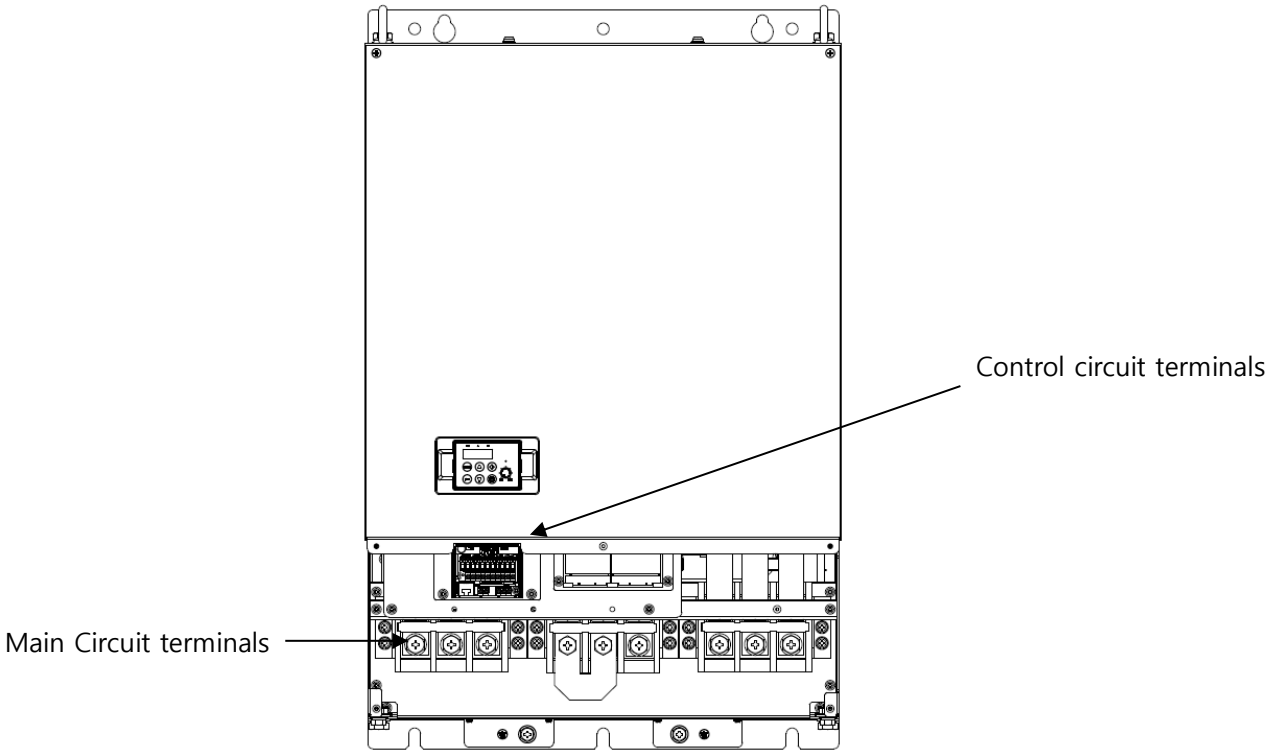


Figure 1-22 Front view without front cover

1.3.11 iMASTER C1-1850HF ~ 2200HF

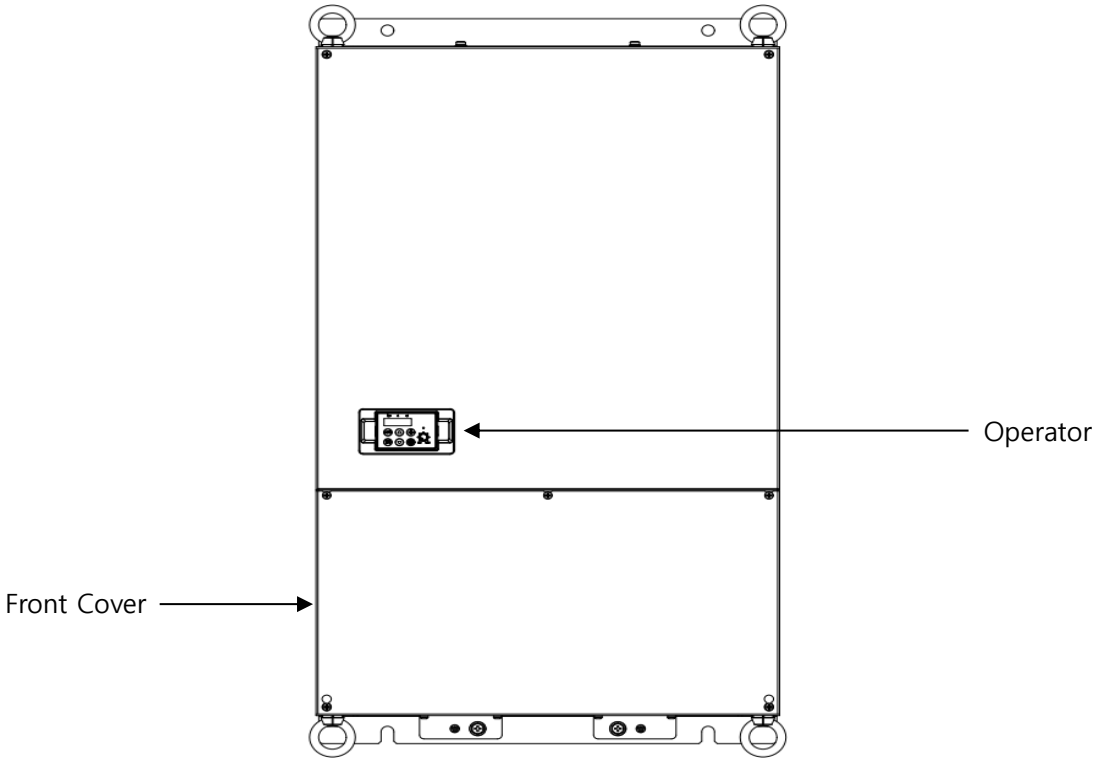


Figure 1-23 Front view with front cover

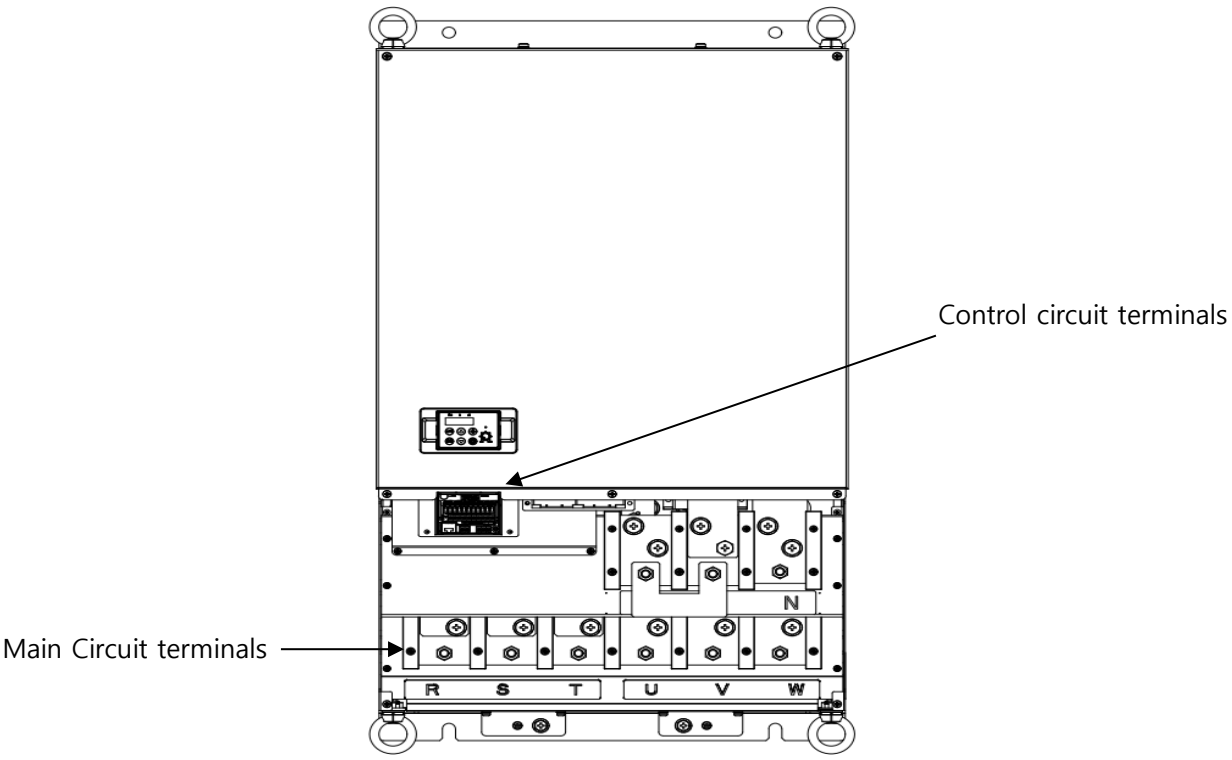


Figure 1-24 Front view without front cover

1.3.12 iMASTER C1-2800HF ~ 3500HF

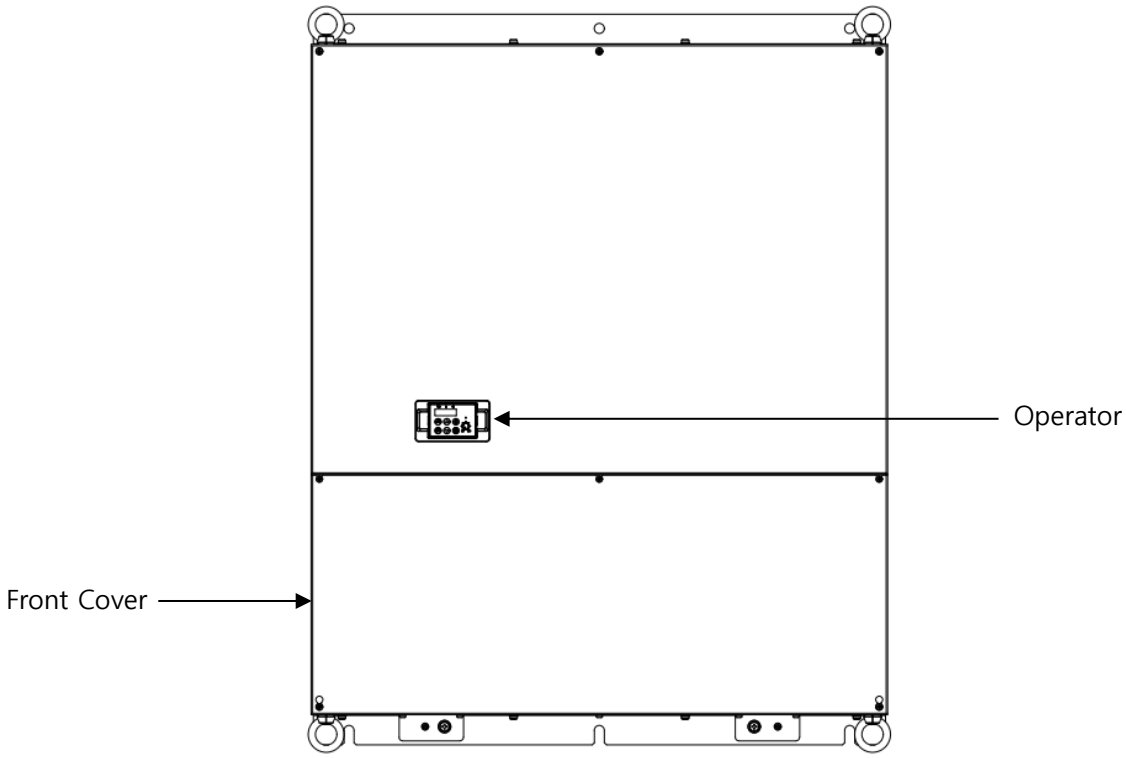


Figure 1-25 Front view with front cover

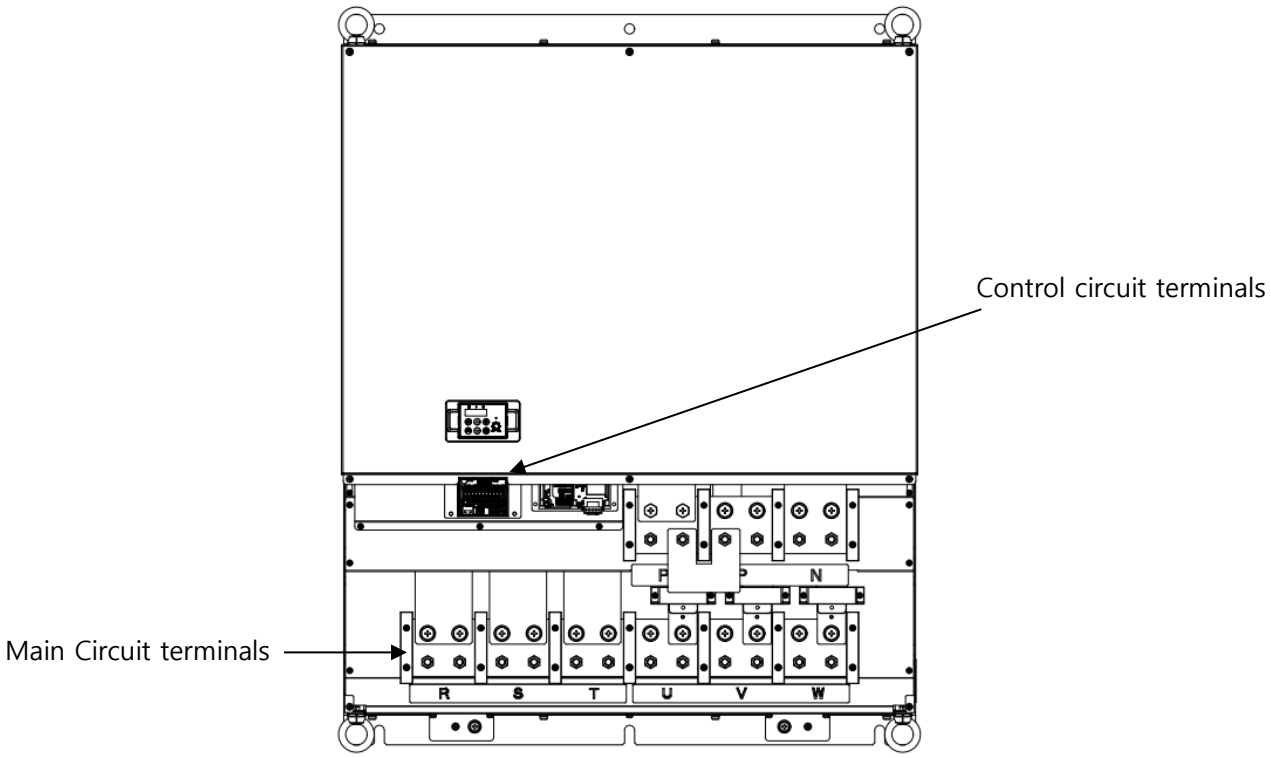


Figure 1-26 Front view without front cover

2. INSTALLATION AND WIRE

2.1 Installation

⚠ CAUTION

- Be sure to install the unit on flame resistant material such as metal.
  There is a fire hazard.
- Be sure not to place anything flammable such as corrosive gas, explosive gas, inflammable gas, grinding fluid mist, salt in the vicinity.
- Do not carry the unit by the top cover, but always by supporting the base of the unit
  There is a possibility of an accident by falling down.
- Be sure not to let foreign matter enter such as cut wire refuse, spatter from welding, iron refuse, wire, dust, etc.
- Be sure to install the VFD in a place which can support the weight according to the specification in the manual.
- Do not install or run the damaged inverter.
  There are concerns of an accident.
- Avoid high temperature, humidity, condensation dust corrosive gas, explosive gas, combustible gas and install the inverter with good ventilation without direct sunlight.
  There is a fire hazard.
- To prevent injury, make sure to wear electric working gloves before working.

2.1.1 Precaution

(1) Caution in transport
- The inverter uses plastic parts. Care must be taken to avoid damage.
  In particular, fasten it with designated parts to ensure that it is firmly secured to the wall or panel. Also, do not operate the inverter with damage and loss of parts.

(2) Install it on the non-flammable (metal, etc.) surface
- Inverter heat shield temperatures can be very high.
  As there is a risk of fire, place it on a non-flammable vertical wall (metal, etc.).
  Attention should also be made to the air gap surrounding the inverter.
  Especially, when there is a heat source such as a breaking resistor or reactor.
  Keep sufficient space to prevent clogging of cooling ventilation by the up/down wiring.

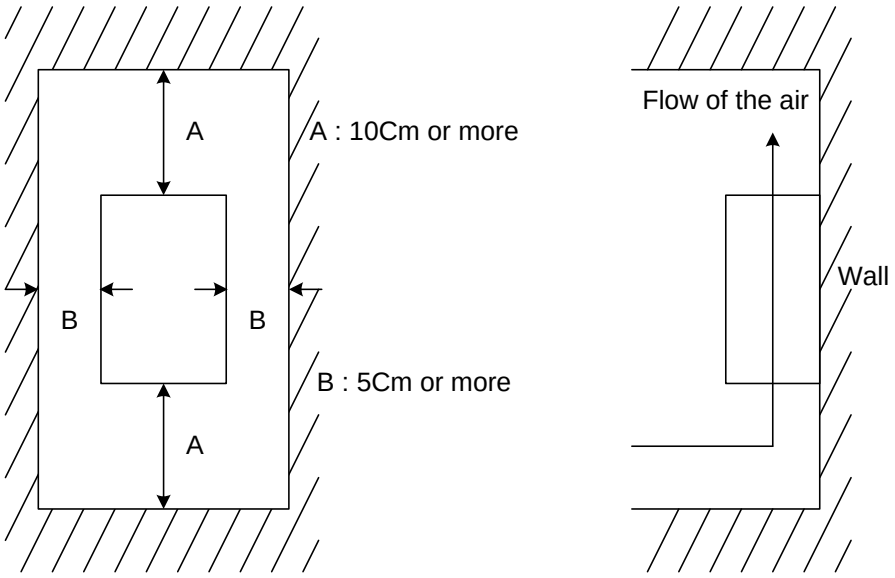


Figure 2-1 Air gap (Installation)

(3) Ambient temperature
- The ambient temperature surrounding the inverter should not exceed the allowable temperature range (HD: -10 to 50℃/ND: -10 to 40℃). Measure the ambient temperature about 5cm from the bottom center of the inverter body and make sure that it is within the allowable temperature range.
  If the temperature exceeds the allowable temperature, component life will become shortened especially in the case of the bus capacitors.

(4) Humidity
- The humidity surrounding the inverter should be within the limit of the allowable percentage range (20% to 90% / RH).
  Under no circumstances should the inverter be in an environment where there is the possibility of moisture entering the inverter.
  Also avoid having the inverter mounted in a place that is exposed to the direct sunlight.

(5) Caution in the installation
- Please be install the inverter avoid dust, corrosive gases, explosive gases, combustible gases.

(6) Installation of inverter

• Mount the inverter in a vertical position using screws or bolts. The mounting surface should also be free from vibration and can easily hold the weight of the inverter.

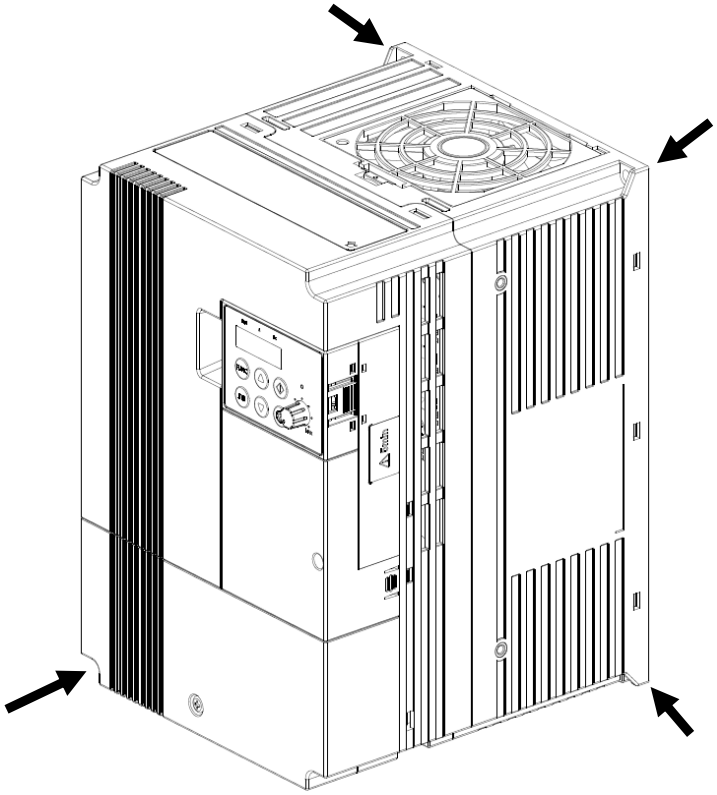


Figure 2-2 Mounting Position

(7) Ventilation in panel

• Install a ventilation fan when installing the inverter inside the panel. The position of the inverter cooling fan and air inlet is critical. If the position is incorrect, the air flow around the inverter will decrease and the temperature around the inverter will increase. Make sure that the ambient temperature is within the allowable range.

2.2 Wiring

⚠ DANGER
• Be sure to ground the unit. There is a possibility of electric shock and fire. • Wiring work should be carried out by qualified electricians There is a possibility of electric shock and fire. • Implement wiring after checking that the power supply is off. There is a possibility of electric shock. • After mounting the VFD, carry out wiring. There is a possibility of electric shock.

⚠ CAUTION
• Make sure that the rated voltage and AC power voltage are same. There are concerns of an accident and fire • Be sure not to connect AC power supply to the output terminals (U, V, W). There are concerns of an accident and fire • Install the short circuit breaker on the input side. There is a fire hazard. • Use rated power lines, short circuit breakers and electronic contactors. There is a fire hazard. • Do not use the electromagnetic contactors on the primary side of the inverter as means of start/stop control.

2.2.1 0.4kW ~ 3.7kW Terminal connection diagram and description

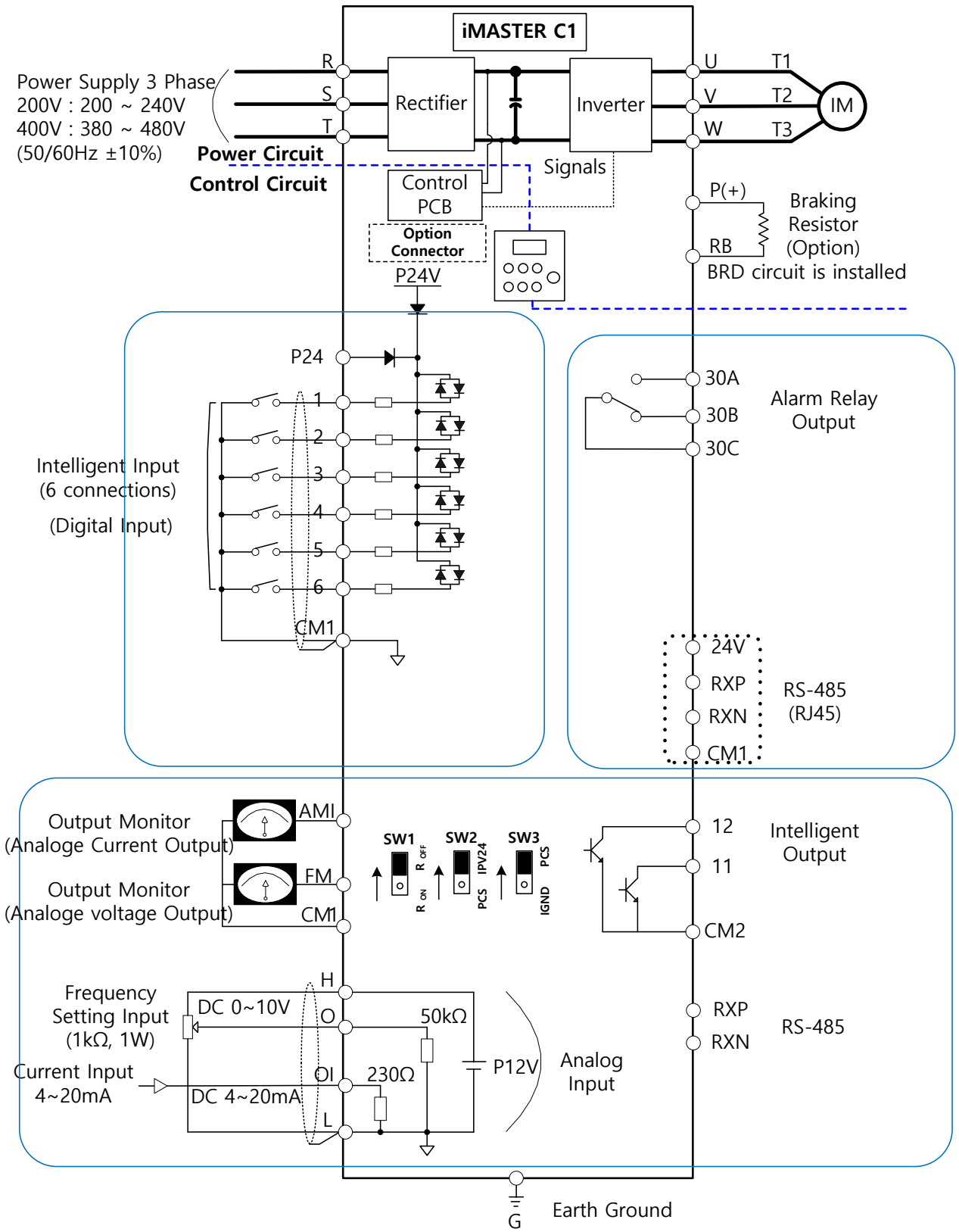


Figure 2-3 Terminal connection diagram (Sink type)

2.2.2 5.5kW ~ 350kW Terminal connection diagram and description

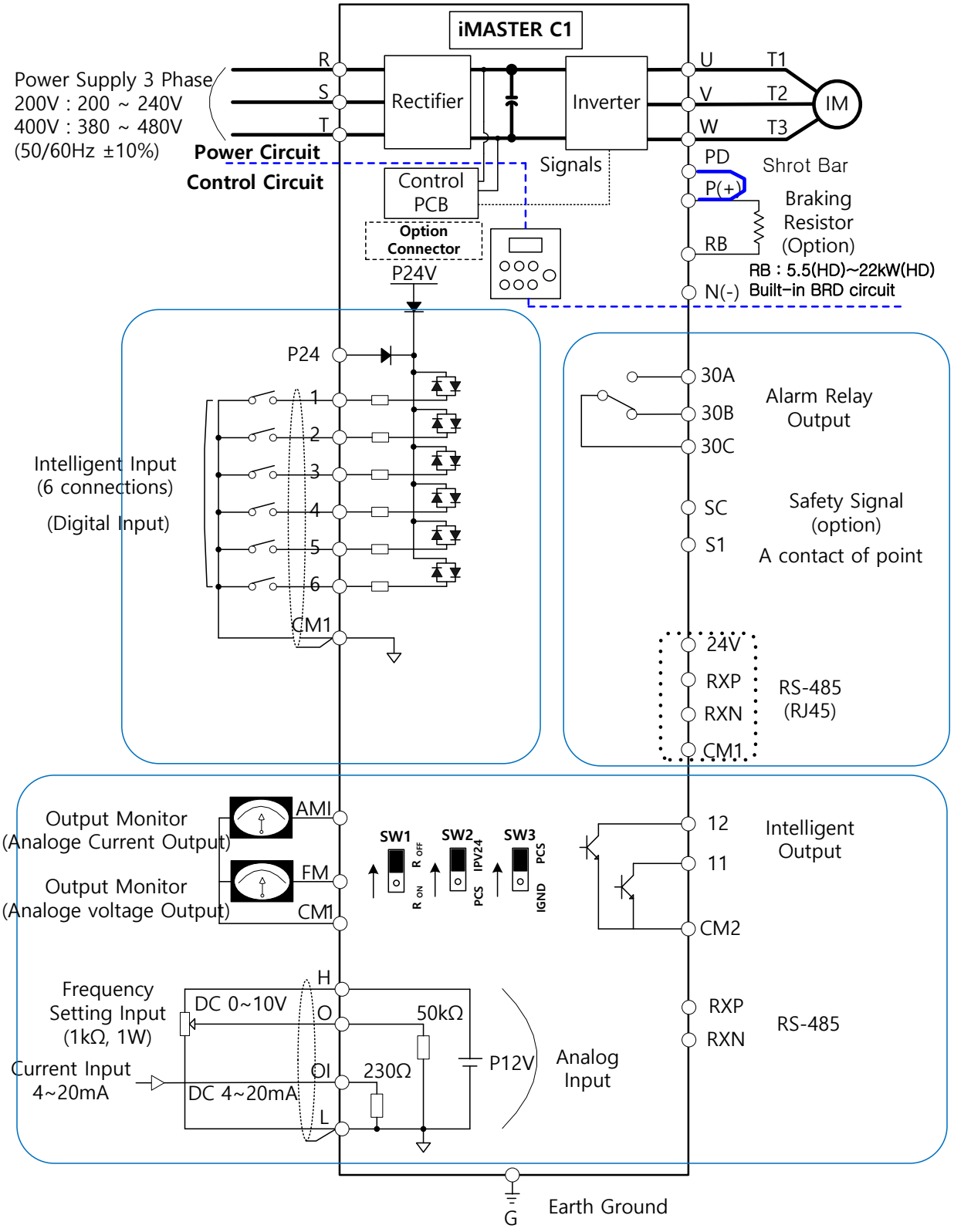


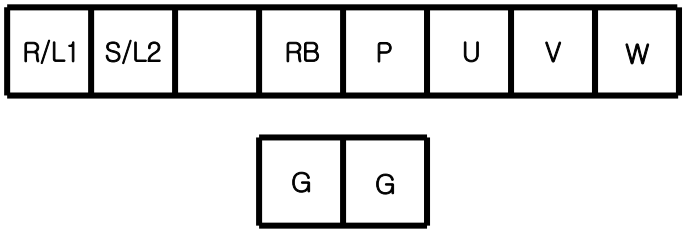
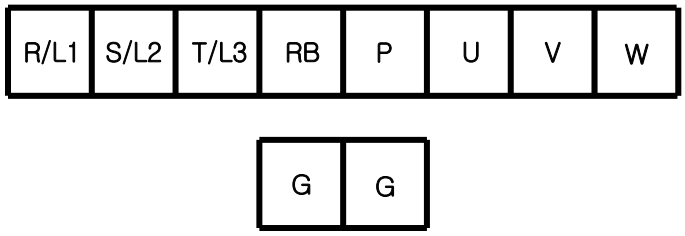
Figure 2-4 Terminal connection diagram (Sink type)

2.2.3 0.4kW ~ 3.7kW Main circuit terminal description

Table 2-1 Main circuit terminal description

Terminal	Terminal Name	Function
R,S,T (L1,L2,L3)	Main power input	AC input power supply
U,V,W (T1,T2,T3)	Inverter output	PWM output power for motor
P, RB (+,-)	External Braking Resistance Connection	Optional External Braking Resistor Connector.
G	Inverter ground	Ground Terminal

Table 2-2 Main circuit terminals view

Main circuit terminals	Corresponding type	Screw size	width (㎜)
	004SF 007SF	M3	6.02
	015SF 022SF	M3	8
	004LF 007LF 015LF	M3	6.02
	022LF 037LF 004HF 007HF 015HF 022HF 037HF	M4	8

Step1) Connecting 3-phase power to the input end of the inverter.
Connect 3-phase power to the inverter power input terminal R(L1), S(L2), T(L3) as table 2-2.
Step2) Connect the inverter to the three-phase motor.
Connect the inverter output stage U(T1), V(T2), W(T3) to the three-phase motor as table 2-2
Step3) The optional braking resistance is connected to the RB and P terminals as indicated.

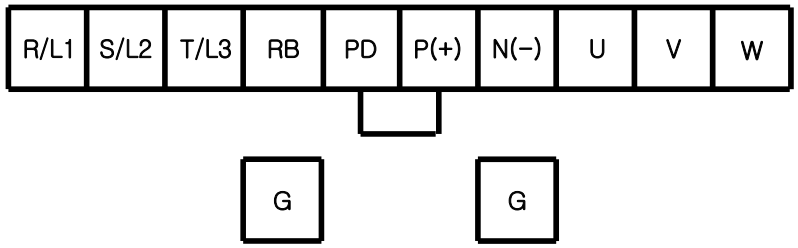
⚠ Do not connect AC power to the output terminals (U,V,W). There is a fire hazard.

2.2.4 5.5kW ~ 22kW Main circuit terminal description

Table 2-3 Main circuit terminal description

Terminal	Terminal Name	Function
R,S,T (L1,L2,L3)	Main power input	AC input power supply
U,V,W (T1,T2,T3)	Inverter output	PWM output power for motor
PD,P (+1,+)	DC Reactor Connection	Remove the shorting bar between PD and P for connection to DC Reactor.
P, RB (+,-)	External Braking Resistance Connection	Optional External Braking Resistor Connector.
P, N	External Braking Unit Connection	Optional External Braking Unit Connector.
G	Inverter ground	Ground Terminal

Table 2-4 Main circuit terminals view

Main circuit terminals	Corresponding type	Screw size	width (㎜)
	055LF 075LF 055HF 075HF	M4	10.3
	110LF 110HF 150HF	M5	13
	150LF 185HF 220HF	M5	13

Step1) Connecting 3-phase power to the input end of the inverter.
Connect 3-phase power to the inverter power input terminal R(L1), S(L2), T(L3) as table 2-2.
Step2) Connect the inverter to the three-phase motor.
Connect the inverter output stage U(T1), V(T2), W(T3) to the three-phase motor as table 2-2
Step3) The optional direct current reactors are hardwired to the P and PD terminals as shown.
However, remove the shorting bar when connecting the DC reactor.

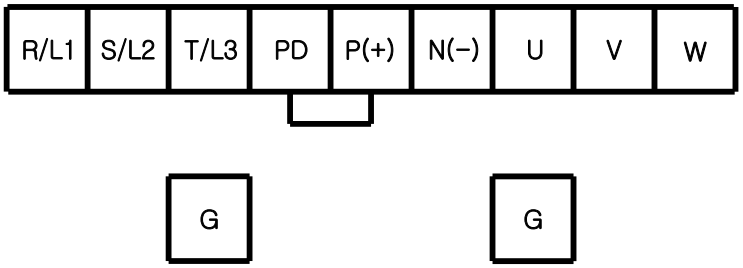
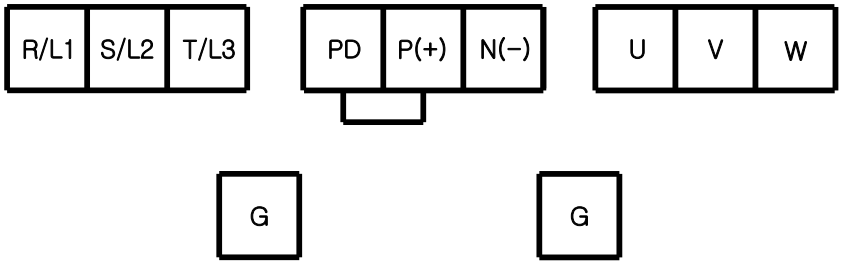
⚠ Do not connect AC power to the output terminals (U,V,W). There is a fire hazard.

2.2.5 30kW ~ 160kW Main circuit terminal description

Table 2-5 Main circuit terminal description

Terminal	Terminal Name	Function
R,S,T (L1,L2,L3)	Main power input	AC input power supply
U,V,W (T1,T2,T3)	Inverter output	PWM output power for motor
PD,P (+1,+)	DC Reactor Connection	Remove the shorting bar between PD and P for connection to DC Reactor.
P, N	External Braking Unit Connection	Optional External Braking Unit Connector.
G	Inverter ground	Ground Terminal

Table 2-6 Main circuit terminals view

Main circuit terminals	Corresponding type	Screw size	width (㎜)
	300HF 370HF	M6	17
	450HF 550HF	M8	23.5
	750HF 900HF	M8	29
	1100HF 1320HF 1600HF	M10	30

Step1) Connecting 3-phase power to the input end of the inverter.
Connect 3-phase power to the inverter power input terminal R(L1), S(L2), T(L3) as table 2-2.
Step2) Connect the inverter to the three-phase motor.
Connect the inverter output stage U(T1), V(T2), W(T3) to the three-phase motor as table 2-2
Step3) The optional direct current reactors are hardwired to the P and PD terminals as shown.
However, remove the shorting bar when connecting the DC reactor.

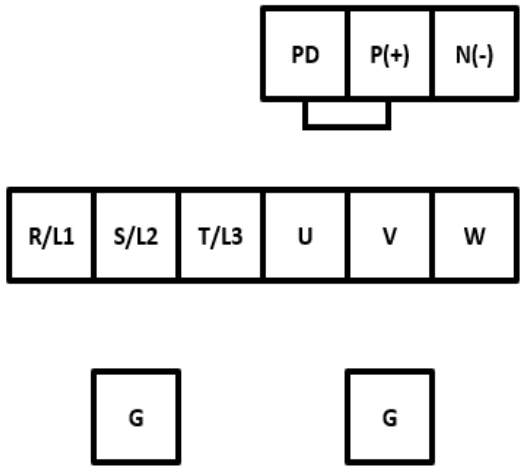
⚠ Do not connect AC power to the output terminals (U,V,W). There is a fire hazard.

2.2.6 185kW ~ 350kW Main circuit terminal description

Table 2-7 Main circuit terminal description

Terminal	Terminal Name	Function
R,S,T (L1,L2,L3)	Main power input	AC input power supply
U,V,W (T1,T2,T3)	Inverter output	PWM output power for motor
PD,P (+1,+)	DC Reactor Connection	Remove the shorting bar between PD and P for connection to DC Reactor.
P, N	External Braking Unit Connection	Optional External Braking Unit Connector.
G	Inverter ground	Ground Terminal

Table 2-8 Main circuit terminals view

Main circuit terminals	Corresponding type	Screw size	width (㎜)
	1850HF 2200HF 2800HF 3500HF	M10	38

Step1) Connecting 3-phase power to the input end of the inverter.
Connect 3-phase power to the inverter power input terminal R(L1), S(L2), T(L3) as table 2-2.
Step2) Connect the inverter to the three-phase motor.
Connect the inverter output stage U(T1), V(T2), W(T3) to the three-phase motor as table 2-2
Step3) The optional direct current reactors are hardwired to the P and PD terminals as shown.
However, remove the shorting bar when connecting the DC reactor.

⚠ Do not connect AC power to the output terminals (U,V,W). There is a fire hazard.

2.2.7 Main circuit terminal wiring

(1) Warning on wiring

When carrying out work on the inverter wiring make sure to wait for at least ten minutes before you remove the cover. Be sure to verify that the charge lamp is not illuminated.
A final check should always be made with a voltage meter.
After removing the power supply, there is a time delay before the capacitors will dissipate their charge.

1) Main power terminals: R(L1), S(L2), T(L3)

- Connect the main power terminals (R(L1), S(L2) and T(L3)) to the power supply through an electromagnetic contactor or an earth-leakage breaker. Use a high harmonic sensitivity current value as the short circuit breaker may malfunction due to harmonic effects. Install an electronic contactor to turn off the inverter power to prevent failure or accident when inverter's protection function is activated.

- LF/HF unit is for a three-phase power supply. Be sure not to power a three-phase only inverter with single phase power.

- Do not stop operation by switching off the electromagnetic contactors on the primary or secondary sides of the inverter.

- The inverter enters into the following condition at the occurrence of open phase if it is selected open phase protection is valid: R phase, S phase or T phase, open phase condition:
  It becomes single-phase operation condition. Trip operation, such as a deficiency voltage or over current, may occur.

- A converter module may be damaged as a result of the following conditions. Use caution when,
  - Unbalanced power supply voltage more than 3%
  - Power supply capacity is more than 10 times of the capacity of inverter
  - A drastic change in the power supply

- Turning on/off the power supply more than three times in one minute. Could be damaged.

2) Inverter output terminals: U(T1), V(T2), W(T3)

- Make sure to use a heavier gauge wire when you have long motor leads. This will help to reduce the voltage drop.

- Do not install power factor correction capacitors or a surge absorber to the output of the inverter. Inverter will trip or sustain damage to the output transistors.

- In the case of the cable length being more than 20 meters, it is possible that a surge voltage will be generated and damage to the motor is caused by the floating capacity or the inductance in the wire. When an EMC filter is to be installed, please contact to us.
- In the case of two or more motors, install a thermal relay to each motor.
- Make the RC value of the thermal relay the value of 1.1 times of motor rated electric current

3) Direct current reactor (DCL) connection terminals (PD, P)

- Only 5.5kw to 22kw inverters are available.
- These are the terminals to connect the current reactor DCL (optional) to help improve the power factor. The short bar is connected to the terminals when shipped from the factory, if you are to connect a DCL you will need to disconnect the short bar first.

- The cable length should be less than 5 meters.

4) External braking resistor connection terminals (P, RB)

- The regenerative braking circuit (BRD) is built-in as standard.

- When braking is required, install an external braking resistor to these terminals.

- The cable length should be less than 16 feet, and twist the two connecting wires to reduce inductance.

- Do not connect any other device other than the external braking resistor to these terminals. When installing an external braking resistor make sure that the resistance is correctly rated to limit the current drawn through the BRD.

5) Earth ground (G)

- Make sure that you securely ground the inverter and motor for prevention of electric shock. The inverter and motor must be connected to an appropriate safety earth ground and follow all local electrical codes.

- In case connecting 2 or more inverters, use caution not to use a loop which can cause some malfunction of the inverter.

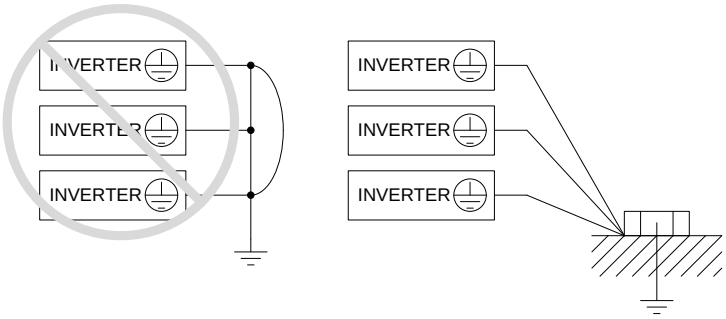


Figure 2-5 Earth Ground (G)

2.2.8 Control circuit terminal description

Table 2-7 Control Circuit Terminal Description

Signal	Terminal	Terminal Name	Function
Input signal	P24	Power terminal for input signal	24VDC ±15%, 100㎃
	6(RS)	Intelligent input terminal (C01~C06) Forward run command (FW), Reverse run command (RV), Multi-speed commands1-4(CF1-4), (Zero) Zero speed commands, 2-stage accel/decel (2CH), Reset (RS), Free run stop (FRS), External trip (EXT), Terminal software lock (SFT), Current input selection (AT), Jogging operation (JG), Unattended start protection (USP), 3 wires input (STA,STP,F/R), Up/Down (Up, Down), Local keypad operation(O/R), Local terminal input operation(T/R), PID integral reset (PIDIR), PID disable (PIDD), Add A11 to setting frequency(F.O),Cancel add A11(R.O), External trip2(EXT2),External trip3(EXT3), External trip4(EXT4), External trip5(EXT5) External trip6(EXT6), Up/Down Value Clear	Contact input: Close: ON (Operating) Open: OFF (Stop) Minimum ON TIME:12ms
	5(AT)		
	4(CF2)		
	3(CF1)		
	2(RV)		
	1(FW)		
	CM1	Common terminal for input or monitors signal	
Monitor signal	FM	Analog Monitor (Frequency, Current, Voltage, Power, Torque, Communication, DC voltage)	0~10Vdc, 1mA
	AMI	Analog Monitor (Frequency, Current, Voltage, Power, Torque, Communication, DC voltage)	4~20mA, 250Ω
Frequency command signal	H	Frequency power	10.5VDC
	O	Frequency command power terminal (voltage)	0-10VDC, Input impedance: 50k Ω
	OI	Frequency command terminal (current)	4-20mA Input impedance: 230Ω
	L	Analog power common	-
Intelligent relay output signal	30A	Relay output terminal (C13) Run status signal (RUN), Frequency arrival signal (FA1), Set frequency arrival signal (FA2), Overload advance notice signal (OL), PID error deviation signal (OD),Alarm signal (AL), MO (Modbus communication),SOL (System Overload), SUL (System Underload), SOL/SUL(System Overload/Underload detection), AI_LOSS(Analog Input loss detection), KEY_LOSS(keypad loss detection), BRK(Control external braking)	AC 250V 2.5A (Resistor load) 0.2A (Inductor load) DC 30V 3.0A (Resistor load) 0.7A (Induction load)
	30B		
	30C		

Signal	Terminal	Terminal Name	Function
Intelligent output signal	11	Open collector output (C14~C15) Run status signal (RUN), Frequency arrival signal (FA1), Set frequency arrival signal (FA2), Overload advance notice signal (OL), PID error deviation signal (OD), Alarm signal (AL), MO (Modbus communication), SOL (System Overload), SUL (System Underload), SOL/SUL(System Overload/Underload detection) AI_LOSS(Analog Input loss detection), KEY_LOSS(keypad loss detection), BRK(Control external braking)	24VDC, 50mA max
	12		
	CM2	Common terminal for output	-
1st communication (RJ-45)	RXP	RJ-45 connector no. 3	RS-485 communication terminal
	RXN	RJ-45 connector no. 6	
Safety input signal	SC	Common terminal for safety input	Emergency stop Intelligent input (Only 5.5kW~160kW Inverter are Available)
	S1	Safety A point input	
2nd communication (speed set b31)	RXP	RS–485 (+)	2nd RS-485 communication terminal
	RXN	RS–485 (-)	

2.2.9 Control circuit terminal wiring

(1) Wiring of control circuit terminal

The control circuit terminal of iMASTER C1 is as below,

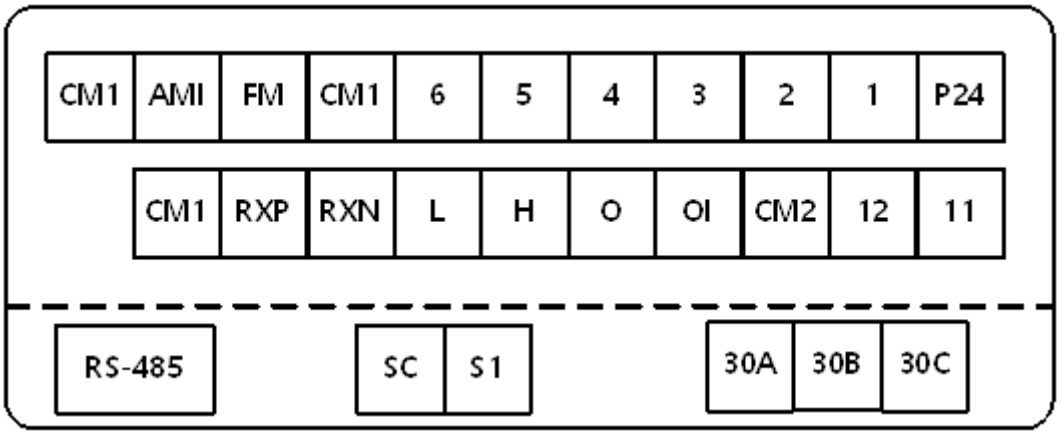


Figure 2-6 Control circuit terminal[note1]

Note 1) The SC and C1 terminals only provide Inverter over 5.5 kW

(2) Example of control circuit wiring

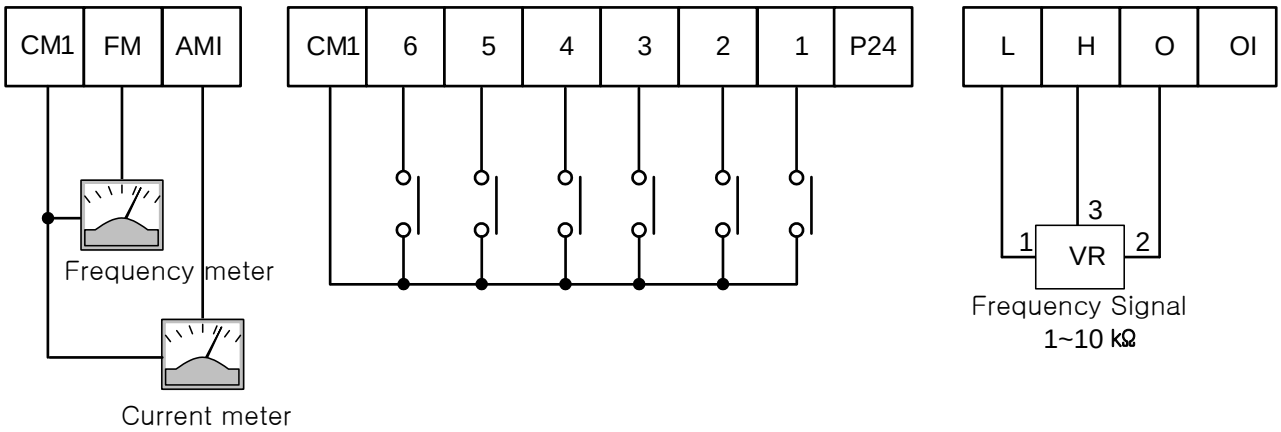


Figure 2-7 Example of control circuit wiring

(3) Precaution of wiring

1) Control terminals are insulated to its power lines (R, S, T, U, V, W, PD, N, RB).
   Do not connect those terminals to power lines or ground.
2) Use twisted screened cable, for the input and output wires of the control circuit terminals. Connect the screened cable to the common terminal.
3) Limit the connection wires to 20 meters.
4) Separate the control circuit wiring from the main power and relay control wiring.
   If it is inevitable to cross, make it orthogonal. There is a concern of inverter malfunction.

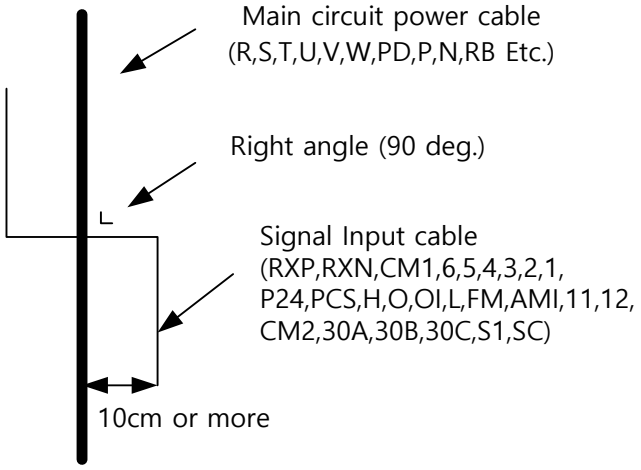


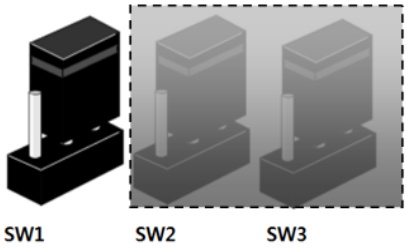
Figure 2-8 Separate of main circuit and control circuit wire

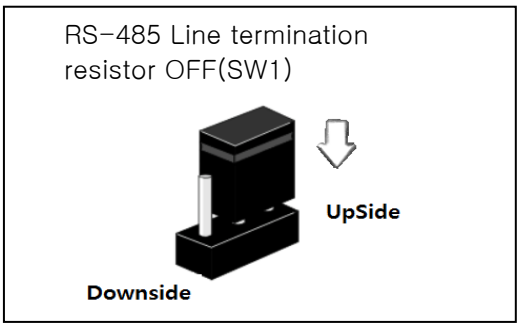
5) When using relays for the FW terminal or an intelligent input terminal use a control relay that is designed to work with 24Vdc.
6) When a relay is used as an intelligent output, connect a diode for surge protection parallel to the relay coil.
7) Do not short the analog voltage terminals H and L or the internal power terminals P24 and all CM1's. Otherwise there is risk of Inverter damage.

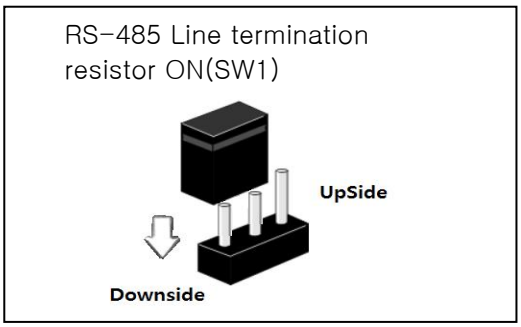
(4) Selection the switches

1) RS-485-line termination resistor
Line termination resistor is used to decrease delay of distortion and attenuation at the long distance. It inserts one on the line termination. line termination resistor of inverter is build-in and it can be selected by SW1 switch.

<Line termination resistor switch selection >
SW1: Default value is OFF







2) Connections between Relay output and PLC

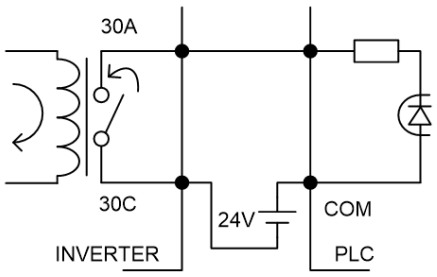
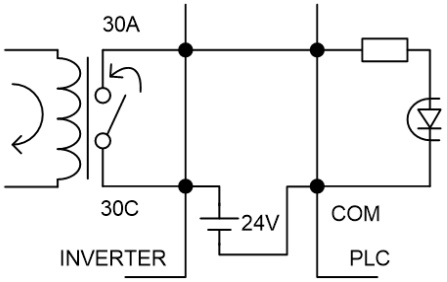
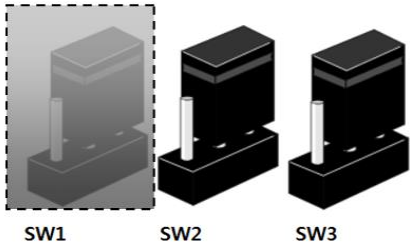
Sink Type	Source Type
	

Figure 2-9 Connections between Relay and PLC

3) Connection between Input terminal and PLC: Factory setting is Sink type mode
- SW2: Power Source switch for Internal 24V (factory setting) or external PCS input
- SW3: Select switch for Sink type mode (factory setting) and Source type mode



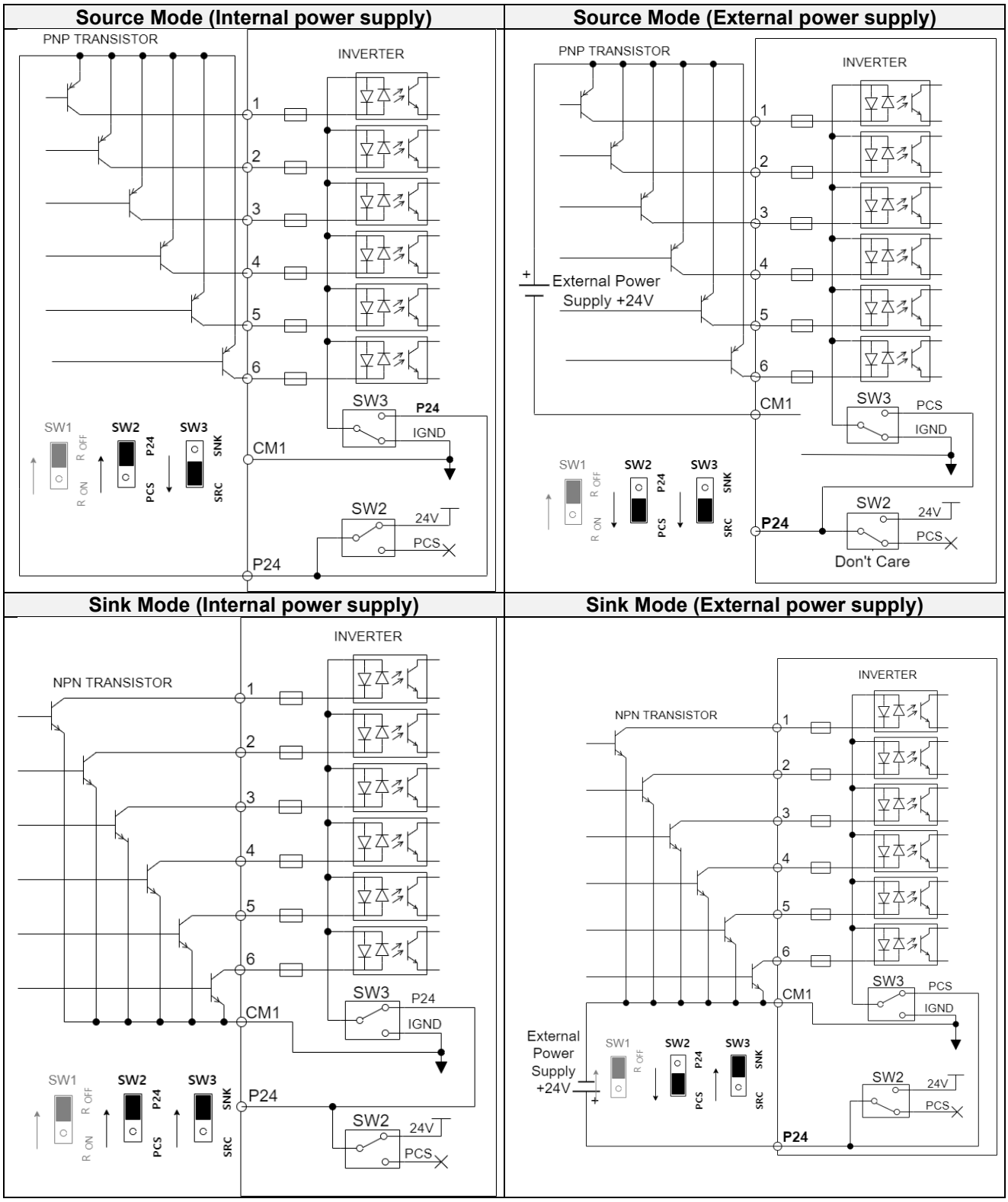
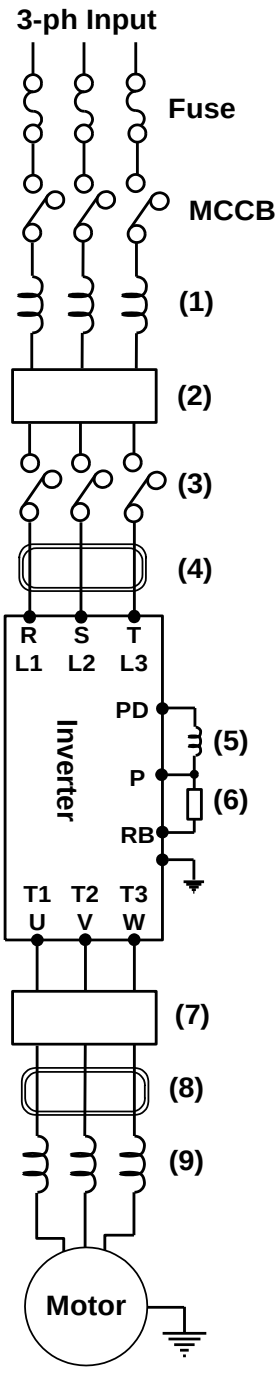


Figure 2-10 Input Terminal and PLC Connection Diagram

2.2.10 Accessory wiring



Note1: The applicable equipment is for HYUNDAI standard four pole squirrel cage motor.

Note2: Be sure to consider the capacity of the circuit breaker to be used.

Note3: Be sure to use larger wire for power lines if the distance exceeds 20m.

Note4: Be sure to use MCCB for the safety.

Note5: Do not operate the electronic contactor when the inverter is running.

Note6: Use 0.75㎟ for AL relay and RN relay. Separate by the sum (wiring distance from inverter to power supply, from inverter to motor) for the sensitive current of leakage breaker (MCCB).

Note7: When using CV line and wiring by rigid metal conduit, leak flows

Wiring distance	Sensitive current(mA)
100m and less	50mA
300m and less	100mA

Note8: IV line is high dielectric constant that is why the current will be increased 8 times. Therefore, use the sensitive current 8 times as large as that of the left list.
And if the distance of wire is over 100m, use CV line.

Note9: Do not stop operation by switching off the electromagnetic contactors.
If you need to use electromagnetic contactors for predation because of bypass operation, be sure the protective circuit must be configured so that it cannot be switched on or off during inverter operation.

Figure 2-11
Example of Option connection

Table 2-8 Optional accessories for improved performance

No.	Item	Function
(1)	Input AC Reactor	Recommended to use when the unbalance voltage rate is 3% or more and power supply is 500 kVA or more, and there is a rapid change in the power supply. It also reduces harmonics and improves the power factor.
(2)	Noise filter for Inverter	Reduces common noise generated between the power supply and the ground, as well as normal noise. Put it in the primary side of inverter.
(3)	Radio Noise Filter (zero-phase reactor)	Helps to reduce noise on a peripheral radio when an inverter is running.
(4)	Input Radio Noise Filter	Reduces radiation noise emitted from wire at the input.
(5)	DC Reactor[note1]	Helps to improve power factor for the inverter.
(6)	Breaking Resistor/ Regenerative Breaking Unit	Used for applications that need to increase the brake torque of the inverter or to frequently start/stop and to run high inertia load.
(7)	Output Noise Filter	Reduces noise emitted from the inverter motor leads. This helps to minimize interference with sensitive equipment (i.e.: sensors or weight scale).
(8)	Radio Noise Filter (Zero-phase reactor)	Reduces noise generated at the output of the inverter. (It is possible to use for both input and output.)
(9)	Output alternation reactor Reducing vibration, thermal Relay, preventing Misapplication	Running motors with the inverter generates vibration greater than that with commercial power supply. This part installed between the inverter and motor reduces torque ripple. When the cable length between the inverter and motor is long (10m or more), a countermeasure for a malfunction of the thermal relay by harmonic due to switching on inverter is taken by inserting reactor. There is the way to use current sensor instead of thermal relay.
	LCR filter	Sine-wave filter for output

Note 1) Only inverters greater than 5.5kw are available.

2.2.11 Torque and wire specification

Table 2-9 Applicable tools for iMASTER C1 HD / ND (Heavy duty) note2

Class	Motor Output (kW)	Inverter model	Power lines note1 R,S,T, U,V,W,PD,P	External resistor between P and RB	Screw size of Terminal	Torque (N•m)	Applicable Tools		
							Molded case circuit breaker (MCCB)		Electro-magnetic Controller (MC)
200V Class	0.4	004SF	2.1	2.1	M3	0.5	EBS33c	5A	MC-6a
	0.4	004LF	2.1	2.1	M3	0.5	EBS33c	5A	MC-6a
	0.75	007SF	2.1	2.1	M3	0.5	EBS33c	10A	MC-9a
	0.75	007LF	2.1	2.1	M3	0.5	EBS33c	10A	MC-9a
	1.5	015SF	3.3	3.3	M4	1.2	UTE100H	15A	MC-18a
	1.5	015LF	2.1	2.1	M3	0.5	UTE100H	15A	MC-18a
	2.2	022SF	5.3	5.3	M4	1.2	UTE100H	20A	MC-22b
	2.2	022LF	3.3	3.3	M4	1.2	UTE100H	20A	MC-22b
	3.7	037LF	5.3	5.3	M4	1.2	UTE100H	30A	MC-32a
	5.5	055LF	More than 6	6	M4	1.2	UTS150H	50A	MC-50a
	7.5	075LF	More than 10	6	M4	1.2	UTS150H	50A	MC-50a
	11	110LF	More than 16	6	M5	3.0	UTS150H	75A	MC-75a
	15	150LF	More than 25	16	M5	3.0	UTS150H	100A	MC-85
400V Class	0.4	004HF	2.1	2.1	M4	1.2	UTS150L	5A	MC-6a
	0.75	007HF	2.1	2.1	M4	1.2	UTS150L	5A	MC-6a
	1.5	015HF	2.1	2.1	M4	1.2	UTS150L	10A	MC-9a
	2.2	022HF	2.1	2.1	M4	1.2	UTS150L	10A	MC-9a
	3.7	037HF	3.3	3.3	M4	1.2	UTS150L	15A	MC-18a
	5.5	055HF	More than 4	4	M4	1.2	UTS150L	30A	MC-32a
	7.5	075HF	More than 4	4	M4	1.2	UTS150L	30A	MC-32a
	11	110HF	More than 6	6	M4	1.2	UTS150L	50A	MC-50a
	15	150HF	More than 10	10	M5	3.0	UTS150L	50A	MC-50a
	18.5	185HF	More than 16	10	M5	3.0	UTS150L	75A	MC-65a
	22	220HF	More than 25	10	M5	3.0	UTS150L	75A	MC-65a
	30	300HF	More than 25	-	M6	4.5	UTS150L	100A	MC-85a
	37	370HF	More than 35	-	M6	4.5	ABS204c	100A	MC-85a
	45	450HF	More than 35	-	M8	6.0	ABS204c	150A	MC-130a
	55	550HF	More than 70	-	M8	6.0	ABS204c	175A	MC-150a
	75	750HF	More than 35x2	-	M8	6.0	ABS404c	250A	MC-225a
	90	900HF	More than 35x2	-	M8	6.0	ABS404c	250A	MC-225a

Table 2-9 Applicable tools for iMASTER C1 (Heavy duty) note2

Class	Motor Output (kW)	Inverter model	Power lines note1 R,S,T, U,V,W,PD,P	External resistor between P and RB	Screw size of Terminal	Torque (N•m)	Applicable Tools		
							Molded case circuit breaker (MCCB)		Electro-magnetic Controller (MC)
400V Class	110	1100HF	More than 50x2	-	M10	10.0	ABS404c	350A	MC-330a
	132	1320HF	More than 80x2	-	M10	10.0	ABS404c	350A	MC-330a
	160	1600HF	More than 110x2	-	M10	10.0	ABS804S	700A	MC-400a
	185	1850HF	More than 150x2	-	M10	10.0	ABS804S	800A	MC-400a
	220	2200HF	More than 150x2	-	M10	10.0	ABS804S	800A	MC-500a
	280	2800HF	More than 110x4	-	M10	10.0	ABS1004b	1000A	MC-630a
	350	3500HF	More than 150x4	-	M10	10.0	ABS1204b	1250A	MC-800a

Note 1) Use a 600V, 75°C copper wire for wires.
Note 2) 3.7 kW or less inverter are based on (Heavy duty).

Table 2-10 Applicable tools for iMASTER C1 HD / ND (Normal duty)

Class	Motor Output (kW)	Inverter model	Power lines note1 R,S,T, U,V,W,PD,P	External resistor between P and RB	Screw size of Terminal	Torque (N•m)	Applicable Tools		
							Molded case circuit breaker (MCCB)		Electro-magnetic Controller (MC)
200V Class	7.5	055LF/075LF	More than 10	6	M4	1.2	UTS150H	50A	MC-50a
	11	075LF/110LF	More than 16	6	M5	3.0	UTS150H	75A	MC-75a
	15	110LF/150LF	More than 25	16	M5	3.0	UTS150H	100A	MC-85a
	18.5	150LF/185LF	More than 30	16	M6	4.5	UTS150H	150A	MC-130a
400V Class	7.5	055HF/075HF	More than 4	4	M4	1.2	UTS150L	30A	MC-32a
	11	075HF/110HF	More than 6	6	M4	1.2	UTS150L	50A	MC-50a
	15	110HF/150HF	More than 10	10	M5	3.0	UTS150L	50A	MC-50a
	18.5	150HF/185HF	More than 16	10	M5	3.0	UTS150L	75A	MC-65a
	22	185HF/220HF	More than 25	10	M5	3.0	UTS150L	75A	MC-65a
	30	220HF/300HF	More than 25	-	M6	4.5	UTS150L	100A	MC-85a
	37	300HF/370HF	More than 25	-	M6	4.5	UTS150L	100A	MC-85a
	45	370HF/450HF	More than 35	-	M6	4.5	ABS204c	100A	MC-130a
	55	450HF/550HF	More than 35	-	M8	6.0	ABS204c	150A	MC-130a
	75	550HF/750HF	More than 70	-	M8	6.0	ABS204c	175A	MC-150a
	90	750HF/900HF	More than 35x2	-	M8	6.0	ABS404c	250A	MC-225a
	110	900HF/1100HF	More than 35x2	-	M8	6.0	ABS404c	250A	MC-225a
	132	1100HF/1320HF	More than 50x2	-	M10	10.0	ABS404c	350A	MC-330a
	160	1320HF/1600HF	More than 80x2	-	M10	10.0	ABS404c	350A	MC-330a
	200	1600HF/2000HF	More than 110x2	-	M10	10.0	ABS804S	700A	MC-400a

Note 1) Use a 600V, 75°C copper wire for wires.

Class	Motor Output (kW)	Inverter model	Power lines[note1] R,S,T, U,V,W,PD,P	External resistor between P and RB	Screw size of Terminal	Torque (N•m)	Applicable Tools		
							Molded case circuit breaker (MCCB)		Electro-magnetic Controller (MC)
400V Class	220	1850HF/2200HF	More than 150x2	-	M10	10.0	ABS804S	800A	MC-400a
	250	2200HF/2500HF	More than 150x2	-	M10	10.0	ABS804S	800A	MC-500a
	320	2800HF/3200HF	More than 110x4	-	M10	10.0	ABS1004b	1000A	MC-630a
	380	3500HF/3800HF	More than 150x4	-	M10	10.0	ABS1204b	1250A	MC-800a

3. SPECIFICATION

3.1 Specification

3.1.1 200V Class Single Phase specification

Inverter model			004SF	007SF	015SF	022SF
Applicable motor (4P, kW) (Note1)		HD	0.4	0.75	1.5	2.2
Rated capacity (kVA)	HD	200V	1.0	1.7	2.6	3.8
		240V	1.2	2.0	3.1	4.6
Rated input voltage			Single Phase 200 ~ 240 V +/- 10 %, 50/60 Hz +/- 5%			
Rated output voltage (Note2)			Three Phase 200 ~ 240 V (Corresponding to Input Voltage)			
Rated output current(A) (Note3)		HD	2.8(3.2)	4.8(5)	7.5(8.5)	11(12.5)
Weight (Kg)			0.76	0.76	0.96	0.96
Protection Design			IP20			

3.1.2 200V Class Three Phase specification

Inverter model			004LF	007LF	015LF	022LF	037LF
Applicable motor (4P, kW) (Note1)		HD	0.4	0.75	1.5	2.2	3.7
Rated capacity (kVA)	HD	200V	1.0	1.7	2.6	3.8	5.9
		240V	1.2	2.0	3.1	4.6	7.1
Rated input voltage			Three Phase 200 ~ 240 V +/- 10 %, 50/60 Hz +/- 5%				
Rated output voltage (Note2)			Three Phase 200 ~ 240 V (Corresponding to Input Voltage)				
Rated output current(A) (Note3)		HD	2.8(3.2)	4.8(5)	7.5(8.5)	11(12.5)	17(19.5)
Weight (Kg)			0.76	0.76	0.76	0.96	1.34
Protection Design			IP20				

Inverter model			055LF	075LF	110LF	150LF
Applicable motor (4P, kW) (Note1)		HD	5.5	7.5	11	15
		ND	7.5	11	15	18.5
Rated capacity (kVA)	HD	200V	8.7	11.4	16.3	22.2
		240V	10.4	13.7	19.5	26.6
	ND	200V	10.4	13.7	19.5	26.6
		240V	12.5	16.6	23.3	30.3
Rated input voltage			Three Phase 200 ~ 240 V +/- 10 %, 50/60 Hz +/- 5%			
Rated output voltage (Note2)			Three Phase 200 ~ 240 V (Corresponding to Input Voltage)			
Rated output current(A)		HD	25	33	47	64
		ND	30	40	56	73
Weight (Kg)			4.2	4.5	4.5	7
Protection Design			IP20			

Note 1: The applicable motor refers to HYUNDAI standard 3-phase motor (4-pole).
To use other motors, care must be taken to prevent the rated motor current (50/60Hz) from exceeding the rated output current of the inverter.

Note 2: The output voltage decreases as the main supply voltage decreases (except for use of the AVR function).
In any case, the output voltage cannot exceed the input power supply voltage.

Note 3: Ambient temperature is less or than 40℃, you can be used as a rated current within ().

3.1.3 400V Class specification

Inverter model			004HF	007HF	015HF	022HF	037HF
Applicable motor (4P, kW) (Note1)		HD	0.4	0.75	1.5	2.2	3.7
Rated capacity (kVA)	HD	380V	1.0	1.8	2.8	3.6	5.9
		480V	1.2	2.2	3.5	4.6	7.5
Rated input voltage			Three Phase 380 ~ 480 V +/- 10 %, 50/60 Hz +/- 5%				
Rated output voltage (Note2)			Three Phase 380 ~ 480 V (Corresponding to Input Voltage)				
Rated output current(A) (Note3)		HD	1.5(1.8)	2.7(3.4)	4.2(4.8)	5.5(7.2)	9.0(10.5)
Weight (Kg)			0.76	0.76	0.96	0.96	1.34
Protection Design			IP20				

Inverter model			055HF	075HF	110HF	150HF	185HF	220HF
Applicable motor (4P, kW) (Note1)		HD	5.5	7.5	11	15	18.5	22
		ND	7.5	11	15	18.5	22	30
Rated capacity (kVA)	HD	380V	9.7	11.8	15.8	21.1	25.7	29.6
		480V	12.3	15.0	20.0	26.6	32.4	37.4
	ND	380V	11.5	15.1	20.4	25	29.0	38.2
		480V	14.5	19.1	25.8	31.6	36.6	48.2
Rated input voltage			Three Phase 380 ~ 480 V +/- 10 %, 50/60 Hz +/- 5%					
Rated output voltage (Note2)			Three Phase 380 ~ 480 V (Corresponding to Input Voltage)					
Rated output current(A)		HD	14.8	18	24	32	39	45
		ND	17.5	23	31	38	44	58
Weight (Kg)			4.2	4.5	4.5	7	7	7.5
Protection Design			IP20					

Note 1: The applicable motor refers to HYUNDAI standard 3-phase motor (4-pole).
To use other motors, care must be taken to prevent the rated motor current (50/60Hz) from exceeding the rated output current of the inverter.

Note 2: The output voltage decreases as the main supply voltage decreases (except for use of the AVR function).
In any case, the output voltage cannot exceed the input power supply voltage.

Note 3: Ambient temperature is less or than 40℃, you can be used as a rated current within ().

Inverter model			300HF	370HF	450HF	550HF	750HF	900HF
Applicable motor (4P, kW) (Note1)		HD	30	37	45	55	75	90
		ND	37	45	55	75	90	110
Rated capacity (kVA)	HD	380V	40.1	49.4	59.9	72.4	98.1	115.8
		480V	50.7	62.4	75.7	91.5	123.9	146.3
	ND	380V	46.7	56.6	67.1	88.90	105.3	127.7
		480V	59.0	71.5	84.4	112.2	133.0	161.3
Rated input voltage			Three Phase 380 ~ 480 V +/- 10 %, 50/60 Hz +/- 5%					
Rated output voltage (Note2)			Three Phase 380 ~ 480 V (Corresponding to Input Voltage)					
Rated output current(A)		HD	61	75	91	110	149	176
		ND	71	86	102	135	160	194
Weight (Kg)			22	22	27	30	50	50
Protection Design			IP00					

Inverter model			1100HF	1320HF	1600HF
Applicable motor (4P, kW) (Note1)		HD	110	132	160
		ND	132	160	200
Rated capacity (kVA)	HD	380V	142.8	171.1	197.5
		480V	180.4	216.2	249.4
	ND	380V	152.0	182.3	213.3
		480V	192.0	230.3	269.4
Rated input voltage			Three Phase 380 ~ 480 V +/- 10 %, 50/60 Hz +/- 5%		
Rated output voltage (Note2)			Three Phase 380 ~ 480 V (Corresponding to Input Voltage)		
Rated output current(A)		HD	217	260	300
		ND	231	277	324
Weight (Kg)			60	60	60
Protection Design			IP00		

Inverter model			1850HF	2200HF	2800HF	3500HF
Applicable motor (4P, kW) (Note1)		HD	185	220	280	350
		ND	200	250	320	380
Rated capacity (kVA)	HD	380V	223.8	273.1	345.5	431.8
		480V	282.7	345	436.5	545.4
	ND	380V	250.8	296.1	394.9	447.6
		480V	316.8	374.1	498.8	565.3
Rated input voltage			Three Phase 380Y/220~480Y/277 Vac +/- 10 %, 50/60 Hz +/- 5%			
Rated output voltage (Note2)			Three Phase 380 ~ 480 V (Corresponding to Input Voltage)			
Rated output current(A)		HD	217	260	300	656
		ND	231	277	324	680
Weight (Kg)			60	60	60	170
Protection Design			IP00			

Note 1: The applicable motor refers to HYUNDAI standard 3-phase motor (4-pole).
To use other motors, care must be taken to prevent the rated motor current (50/60Hz) from exceeding the rated output current of the inverter.

Note 2: The output voltage decreases as the main supply voltage decreases (except for use of the AVR function).
In any case, the output voltage cannot exceed the input power supply voltage.

3.1.4 Performance specification

Features			Performance specification
Control method (Note1)			Space vector PWM
Output frequency range (Note2)			0.01～400Hz (Sensorless Vector Control, PMSM Control : 0.5 ～ 300Hz: 0.5 ～ 300Hz)
Frequency accuracy (Note3)			Digital command ±0.01% of Max Frequency / Analog Frequency ±0.1%
Frequency resolution			Digital setting: 0.01Hz (Under 100Hz), 0.1Hz (Over 100Hz) Analog setting: Max. frequency 500(DC5V), Max. setting frequency 1000 (DC 0 ~ 10V, 4~20mA)
Voltage/frequency characteristic			Base Frequency 0-400Hz setting
Overload current rate			Heavy Duty (150%, 60sec), Normal Duty (120%, 60sec)
Acceleration/deceleration			0.0~6,000 sec (Linear, S curve, U curve) Second acc/dcc can be set
DC injection braking			Operation level and time can be set when above the minimum frequency and below the braking set frequency
Input Signal	Frequency	Operator external signal	Set by Keypad (Potentiometer or Arrow Keys) Variable resistance 1W, 1kΩ~10kΩ DC 0～10V (Input impedance 10KΩ), DC 4～20mA (Input impedance 200Ω)
	Run/Stop	Operator external signal	Run/Stop key Forward run/stop Reverse operation/stop is possible for terminal assignment (select 1a, 1b)
	Intelligent input terminal		FW (Forward Run), RV (Reverse Run), CF1~4(Multi-speed Inputs 1~4), RS(Reset), AT (Analog input current/voltage selection signal), USP (Unattended Start Protection), EXT (External trip), FRS (Free-Run Stop), JG(Jogging), SFT (software lock), 2CH (2nd Acceleration / Deceleration), STA, STP, F/R, UP, DOWN(Up/down), UP/DOWN initial value clear O/R (Local Keypad Operation), T/R (Local Terminal Input Operation), PIDIR (PID Integral Reset), PIDD (PID Disabled), F.O (Add A11 to setting frequency), R.O (Cancel add A11), EXT2 (External trip2), EXT3 (External trip3), EXT4 (External trip4), EXT5 (External trip5) EXT6 (External trip6), Up/Down Value Clear
Output Signal	Intelligent output terminal		RUN (Run Status Signal), FA1 (Frequency Arrival Signal 1), FA2 (Frequency Arrival Signal 2), OL (Overload Alarm), OD (PID Error Deviation Signal), AL (Alarm signal), MO (Modbus communication),SOL (System Overload),SUL (System Underload), SOL/SUL(System Overload/Underload detection),AI_LOSS(Analog Input loss detection),KEY_LOSS(keypad loss detection),BRK(Control external braking)
	Alarm relay output terminal		
	FM output		Analog output meter (DC0~10V full scale. Max · 1mA) Output Frequency, Output Current, Output Voltage, Output Power, Output Torque, Operation by Communication, DC voltage
	AMI output		Analog output meter (4~20mA full scale. Max · 250Ω) Output Frequency, Output Current, Output Voltage, Output Power, Output Torque, Operation by Communication, DC voltage

Features		Performance specification
Application specification functions		Auto tuning, AVR function, V/F characteristic selection, Curved acceleration/deceleration, Upper and lower limiters, 16-stage speed profile, Fine adjustment of start frequency, Carrier frequency change (0.5~16kHz), PID, Frequency jump, Gain and Bias setting, Jogging, Electronic thermal level adjustment, Retry function, Automatic torque boost, Trip history monitor, Software lock, S-curved acc/dcc, Frequency conversion display, UPS, IOLT protection, Flying start, BRD
Protection functions		Over current, Over voltage, Communication error, Under voltage, Output short circuit detection, UPS error, EEPROM error, External trip1~6, Ground fault, Over temperature, Input phase loss, Overload, Inverter overload, Braking resistor overload, CPU error, Safety function, HW trip 1~2, Option trip 1~2, OVS fail, Fan fault
En vi r omen t	Ambient temperature	-10~50℃ (ND: 40℃)
	Storage temperature	-20~60℃
	Ambient humidity	Below 90%RH (Installed with no dew condensation)
	Vibration	5.9m/s^2(0.6G). 10~55Hz
	Location	Under 1000m above sea level, indoors (Installed away from corrosive gasses dust)
Option		Noise filter, DC reactor, AC reactor Remote operator, cable for remote operator, Braking resistor (Note4)

(Note1) Control method setting A31 to 2 (sensorless vector control) Selected, set carrier frequency more than 2.1kHz.
Sensorless vector performance will be reduced when using a motor less than half of the rated capacity of the inverter.
Multiple motors cannot be driven by sensorless vector control.

(Note2) To operate the motor over 50/60Hz, consult the motor manufacturer about the maximum allowable rotation speed.

(Note3) For motor stabilization control, the output frequency can exceed the maximum frequency set in [A04] up to 1.5 Hz.

(Note4) The inverter also has a regenerative braking circuit built in. However, if a large regenerative torque is required, use the optional braking resistance.

3.1.5 Braking resistor specification

- Resistor values in below table are calculated on the basis of 150% rated braking torque, 5% ED(Note1)
- Wattage rating of resistor should be doubled for 10% ED.

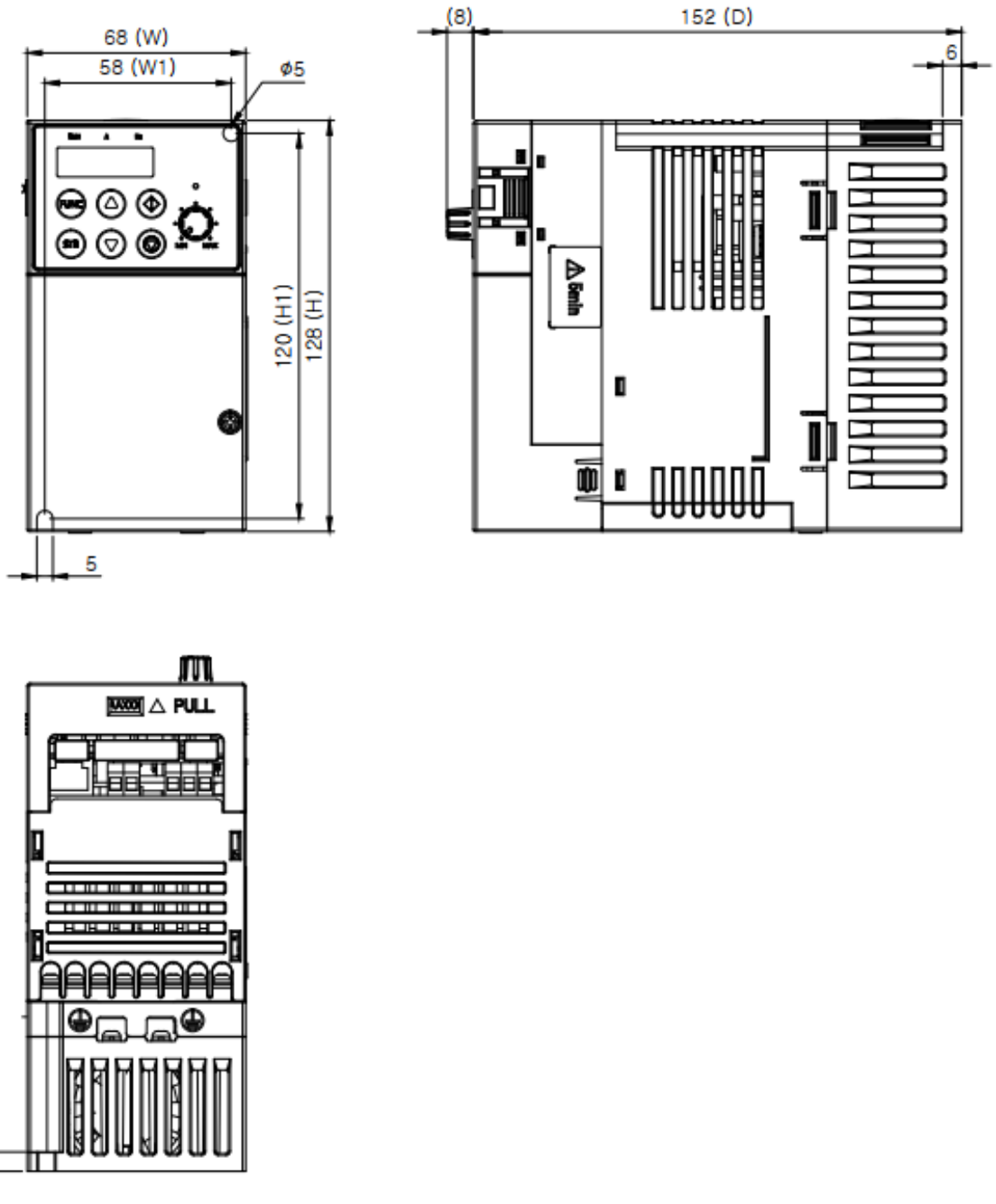
Recommended DB Resistors for the Rated Inverter Capacity (5% ED(Note1),(Note2))

Inverter capacity	Ohm [Ω]	Wattage [W](Note2)
004SF	50	300
007SF	50	300
015SF	50	300
022SF	50	300
004LF	50	300
007LF	50	300
015LF	50	300
022LF	50	300
037LF	35	600
055LF	17	1000
075LF	17	1000
110LF	17	1000
150LF	8.7	2500
004HF	180	300
007HF	180	300
015HF	180	300
022HF	100	600
037HF	100	600
055HF	70	1200
075HF	50	1200
110HF	50	2000
150HF	40	2500
185HF	20	3000
220HF	20	4000

(Note1) ED is duty cycle, 100sec based (5%ED = 5sec)
(Note2) In case of self-cooled DB

3.2 Dimension

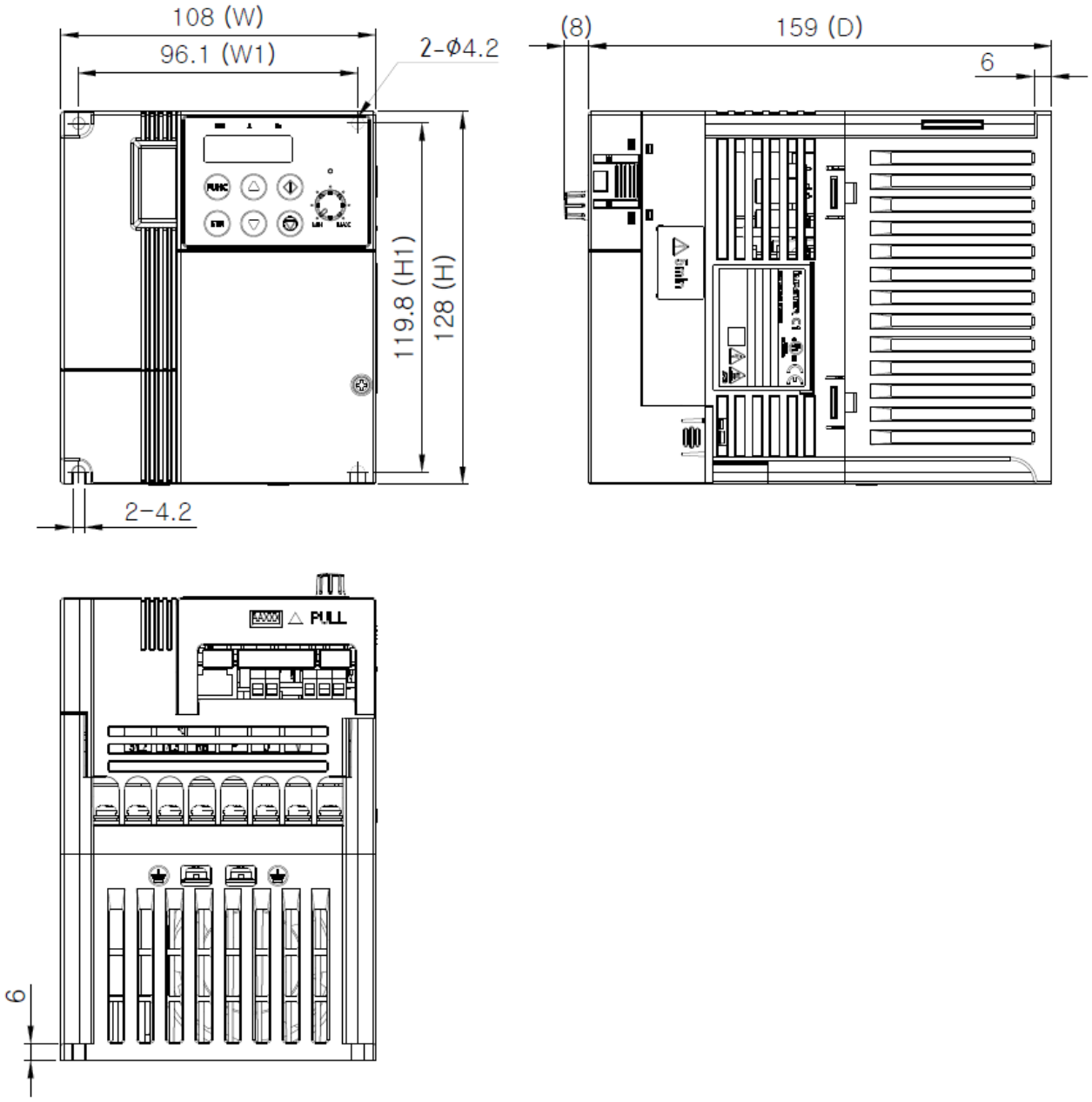
3.2.1 iMASTER C1-004SF~007SF, 004LF~015LF



Diemsions

Model	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]	ø [mm]	Weight [kg]
004SF ~ 007SF	68	58	128	120	152	5	0.76
004LF ~ 015LF	68	58	128	120	152	5	0.76

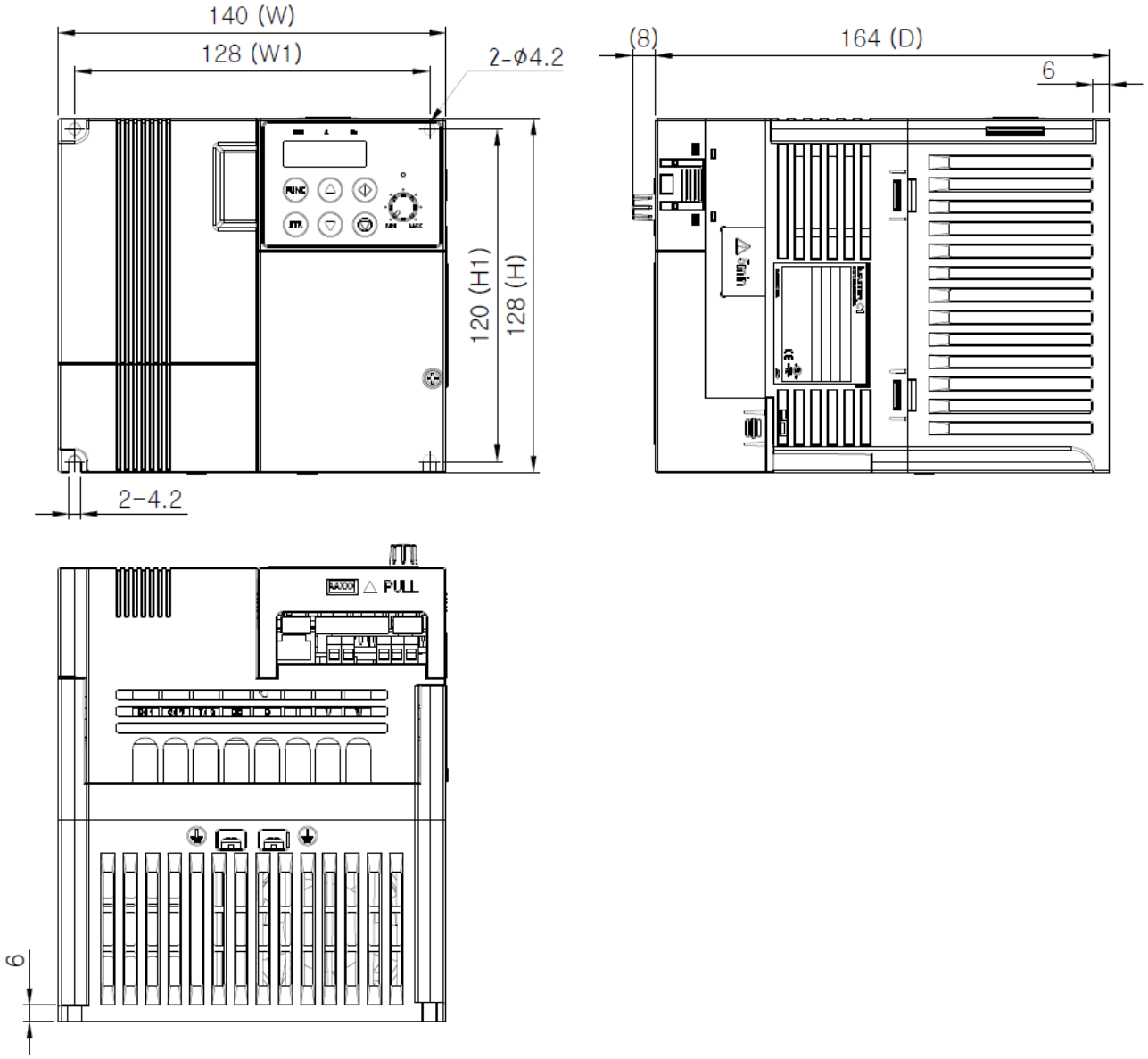
3.2.2 iMASTER C1-015SF~022SF, 022LF, 004HF~022HF



Diemsions

Model	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]	ø [mm]	Weight [kg]
015SF ~ 022SF	108	96.1	128	119.8	159	4.2	0.96
022LF	108	96.1	128	119.8	159	4.2	0.96
004HF ~ 022HF	108	96.1	128	119.8	159	4.2	0.96

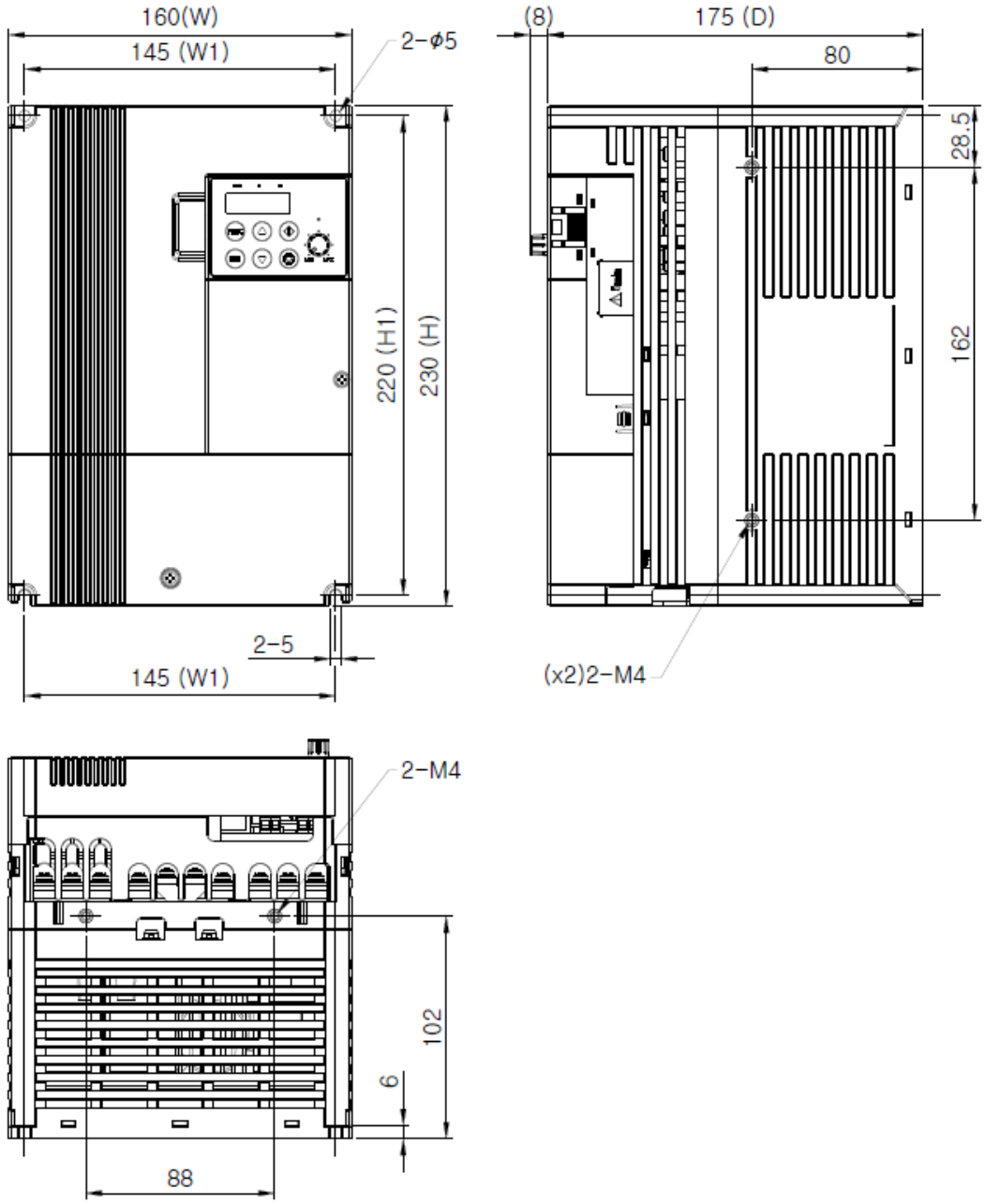
3.2.3 iMASTER C1-037LF, 037HF



Diemsions

Model	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]	ø [mm]	Weight [kg]
037LF	140	128	128	120	164	4.2	1.34
037HF	140	128	128	120	164	4.2	1.34

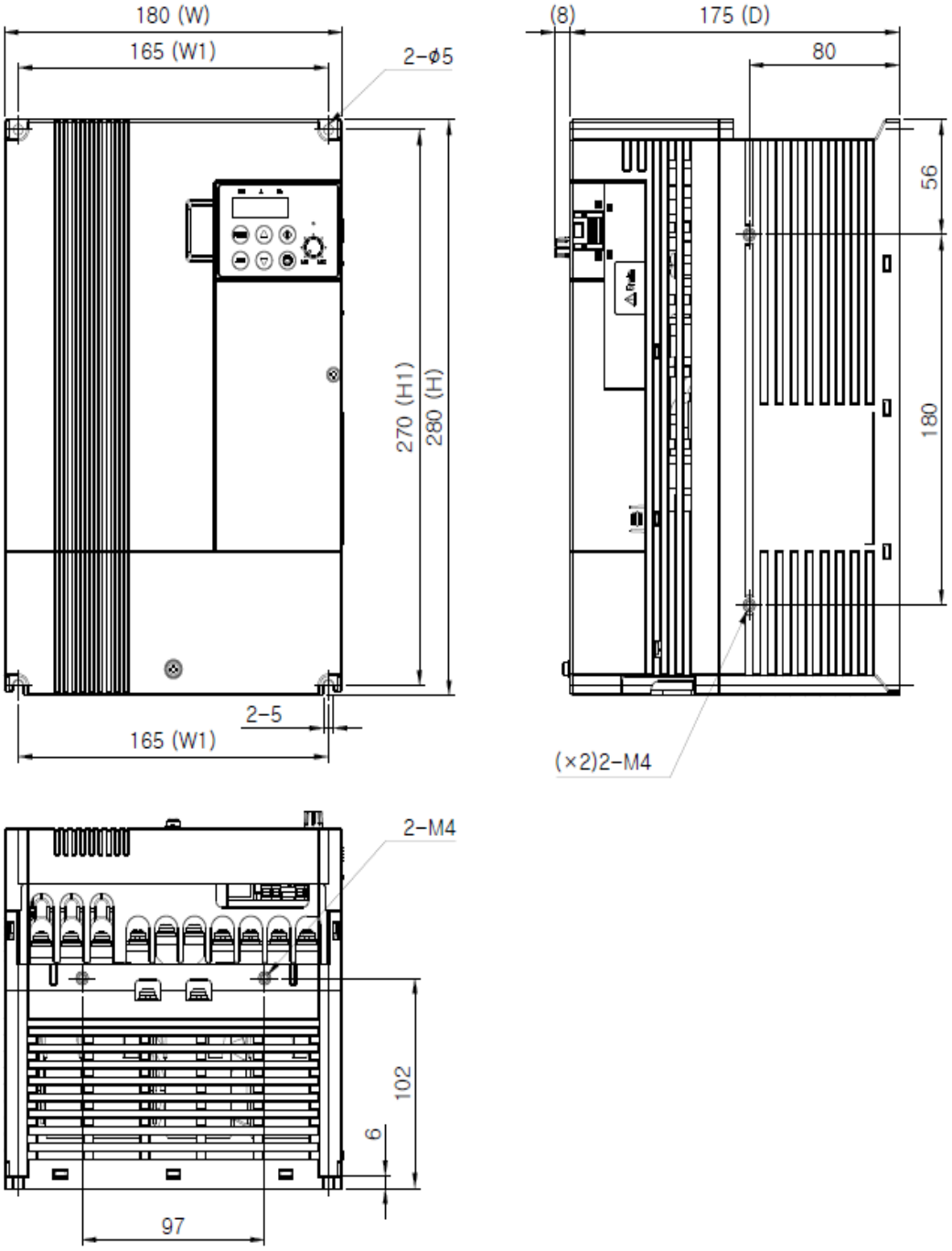
3.2.4 iMASTER C1-055LF~075LF, 055HF~075HF



Diemsions

Model	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]	ø [mm]	Weight [kg]
055LF	160	145	230	220	175	5	4.2
075LF	160	145	230	220	175	5	4.5
055HF(FLT)	160	145	230	220	175	5	4.5
075HF(FLT)	160	145	230	220	175	5	4.5

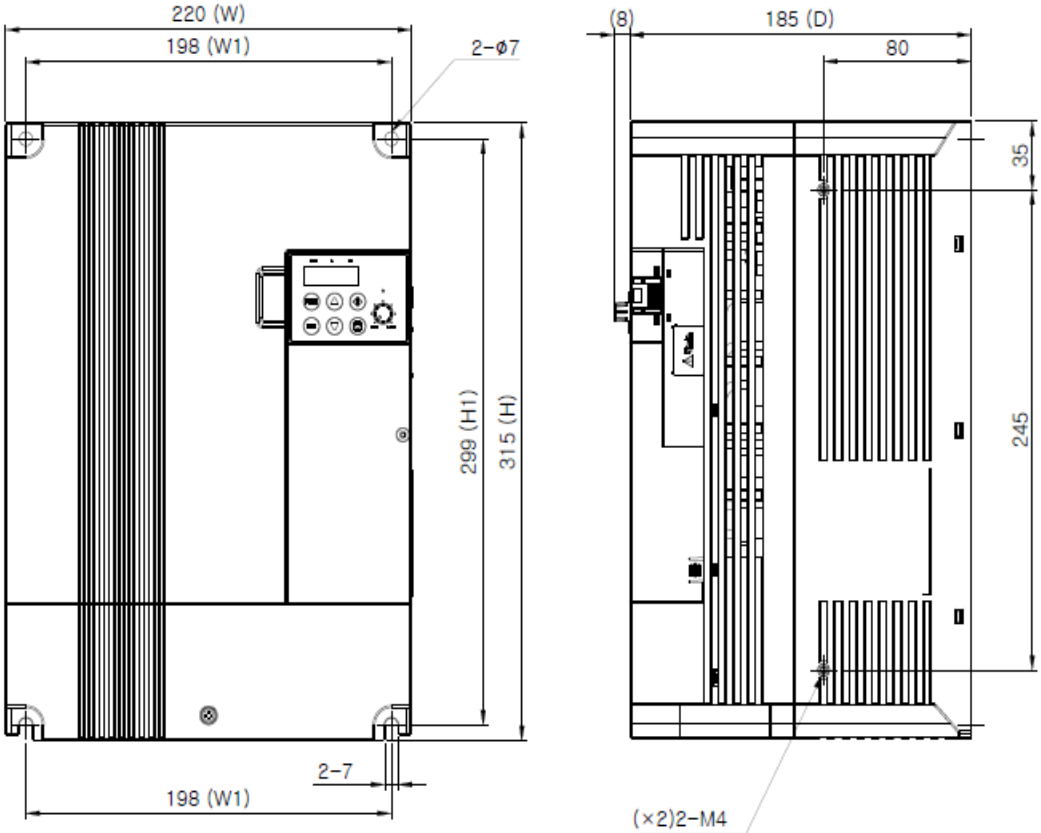
3.2.5 iMASTER C1-110LF, 110HF~150HF



Diemsions

Model	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]	ø [mm]	Weight [kg]
110LF	180	165	280	270	175	5	4.5
110HF(FLT)	180	165	280	270	175	5	4.5
150HF(FLT)	180	165	280	270	175	5	7

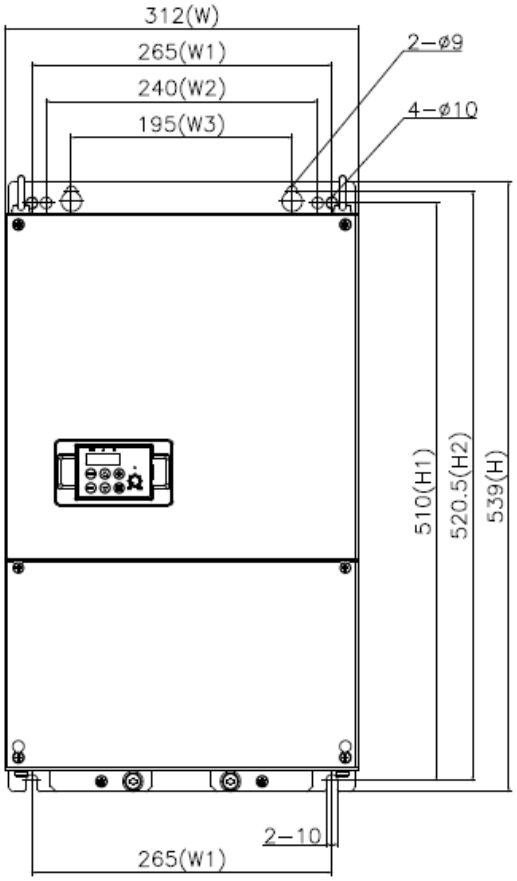
3.2.6 iMASTER C1-150LF, 185HF~220HF

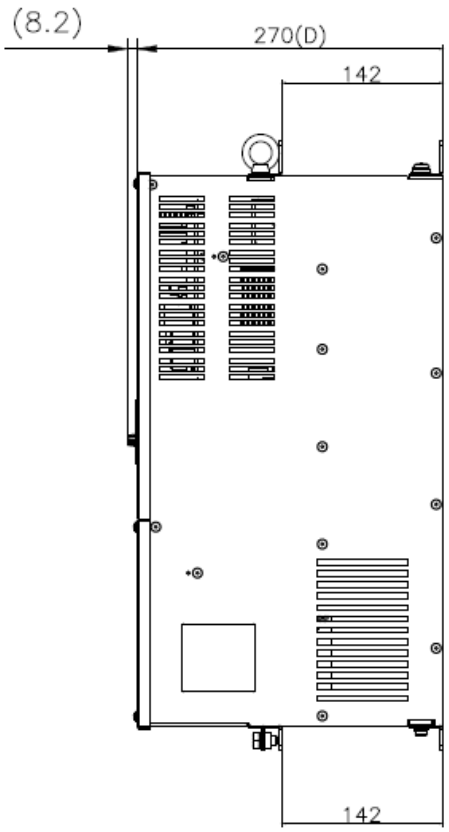


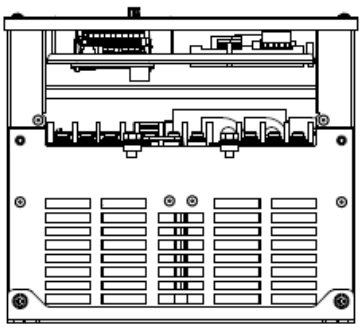
Diemsions

Model	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]	ø [mm]	Weight [kg]
150LF	220	198	315	299	185	7	6.5
185HF(FLT)	220	198	315	299	185	7	7
220HF(FLT)	220	198	315	299	185	7	7.5

3.2.7 iMASTER C1-300HF~370HF



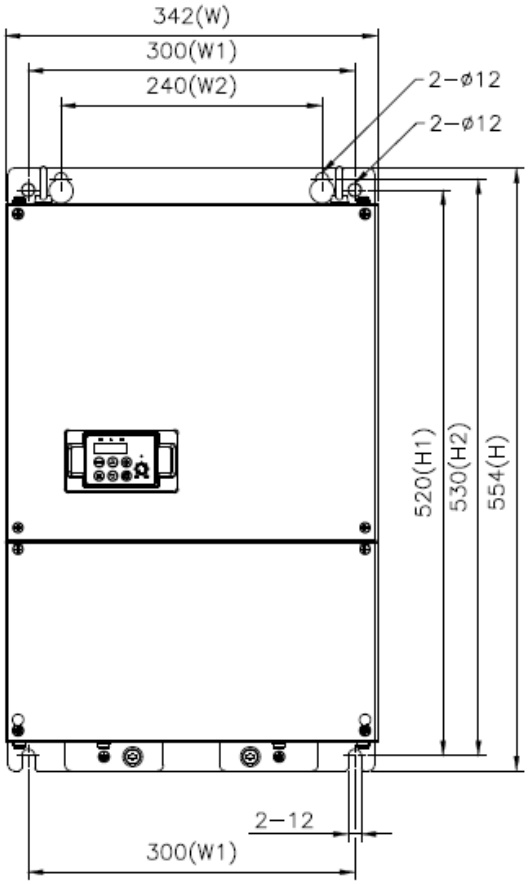


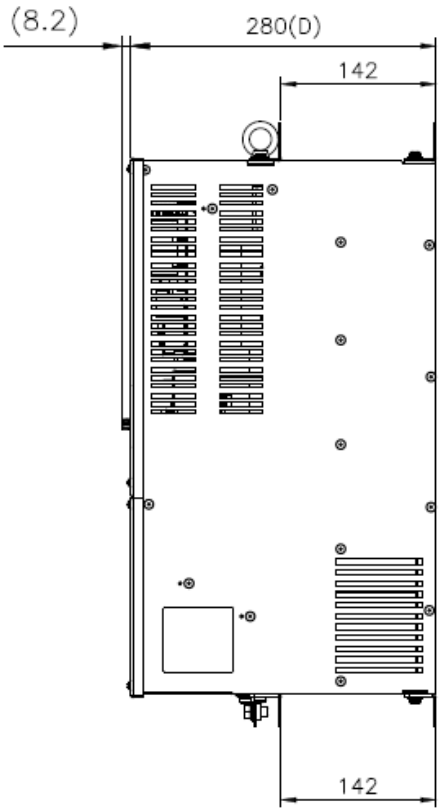


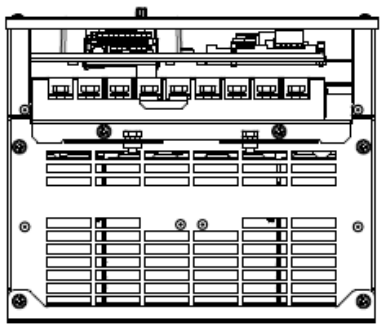
Diemsions

Model	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]	Ø [mm]	Weight [kg]
300HF	306	265	539	519.5	270	9	22
370HF	306	265	539	519.5	270	9	22

3.2.8 iMASTER C1-450HF~550HF



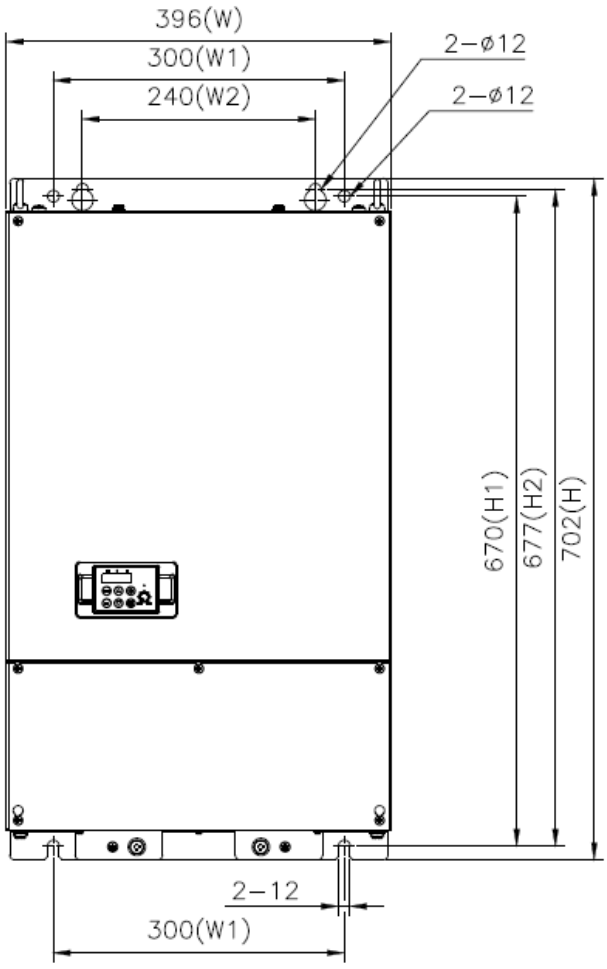


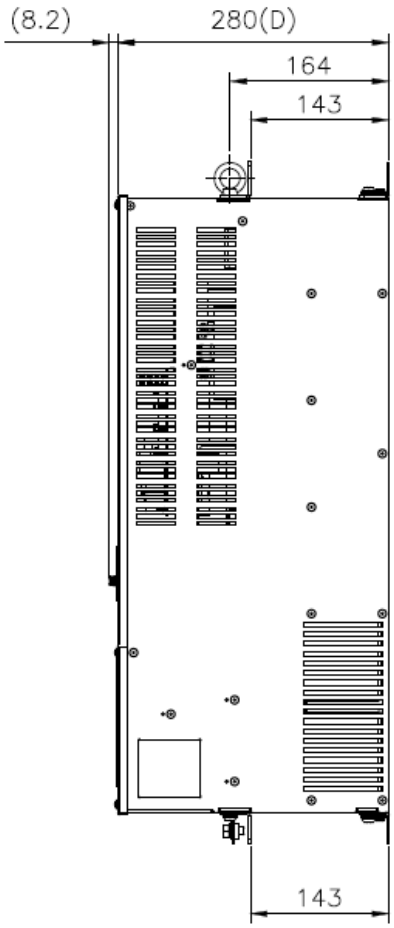


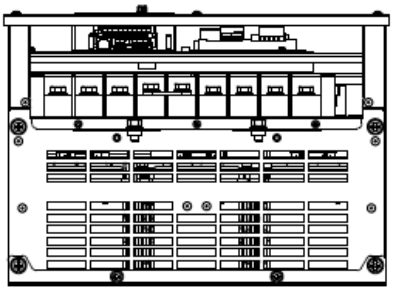
Diemsions

Model	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]	Ø [mm]	Weight [kg]
450HF	342	240	555	530	280	12	27
550HF	342	240	555	530	280	12	30

3.2.9 iMASTER C1-750HF~900HF



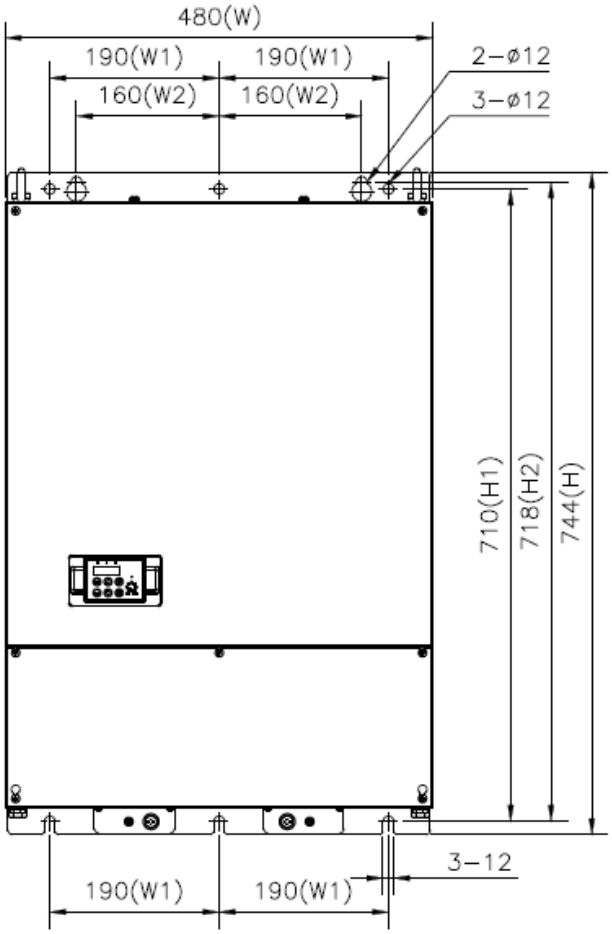


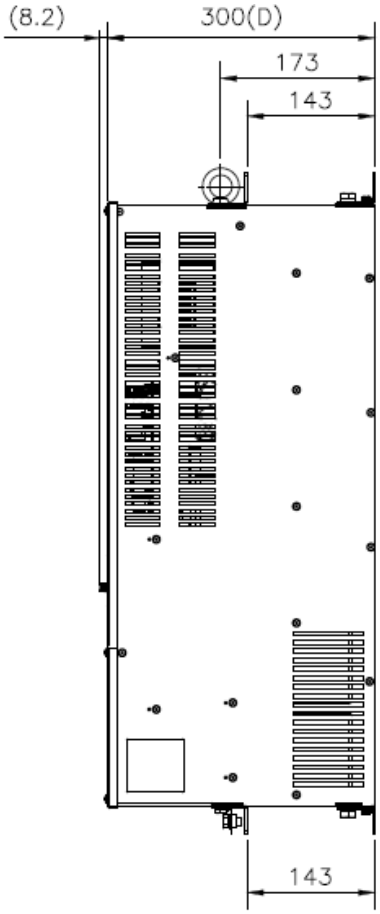


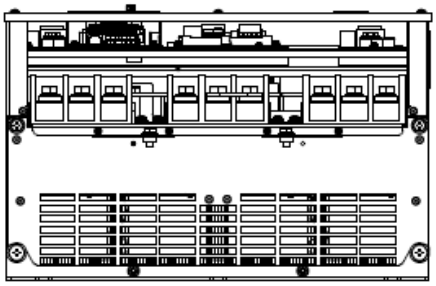
Diemsions

Model	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]	Ø [mm]	Weight [kg]
750HF	396	300	703.4	678.4	80	12	50
900HF	396	300	703.4	678.4	80	12	50

3.2.10 iMASTER C1-1100HF~1600HF



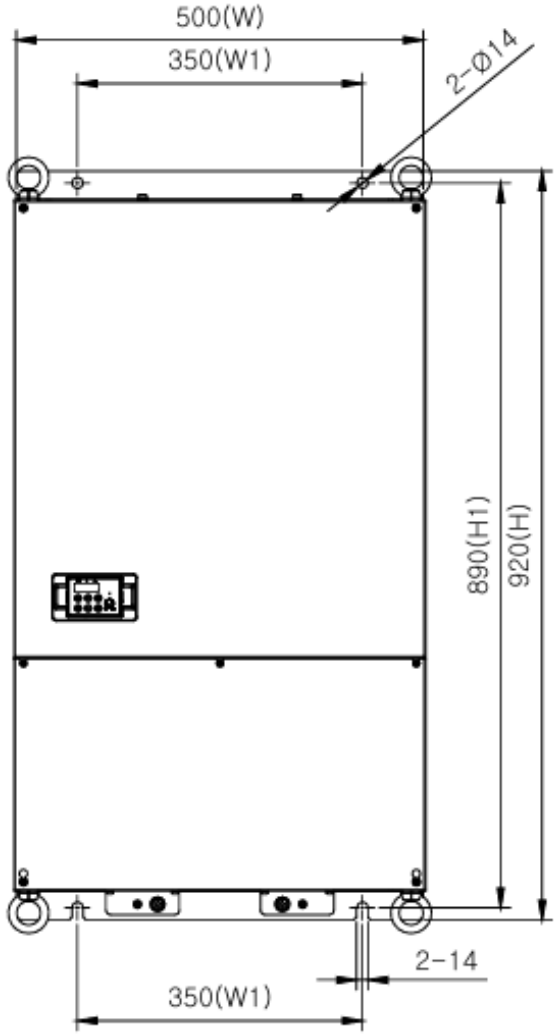


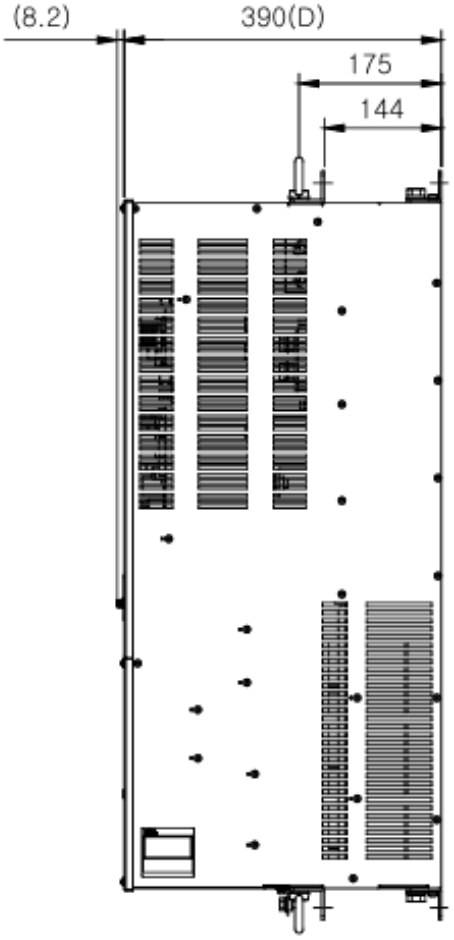


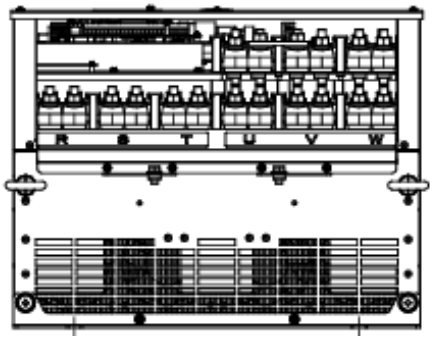
Diemsions

Model	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]	Ø [mm]	Weight [kg]
1100HF	480	190	744	718	300	12	60
1320HF	480	190	744	718	300	12	60
1600HF	480	190	744	718	300	12	60

3.2.11 iMASTER C1-1850HF~2200HF



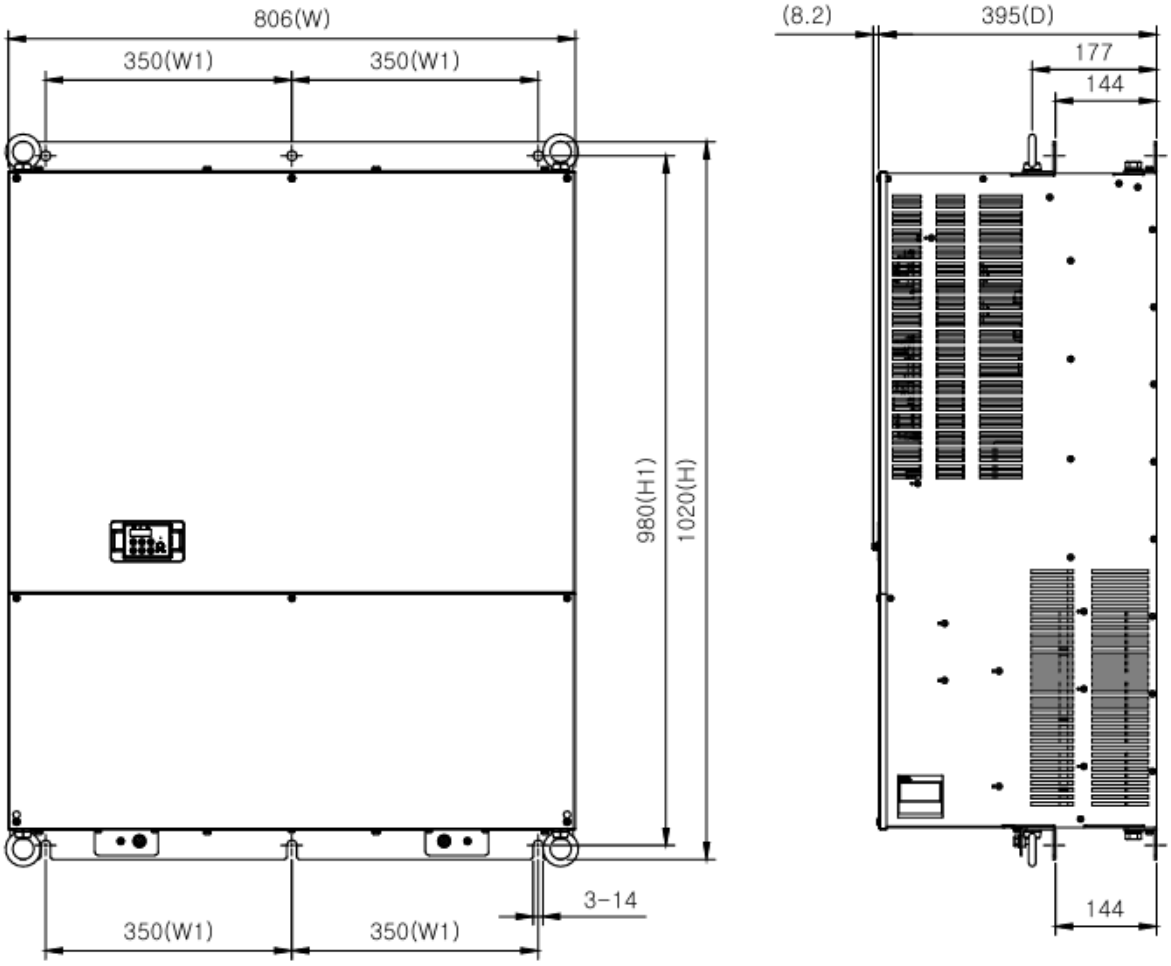


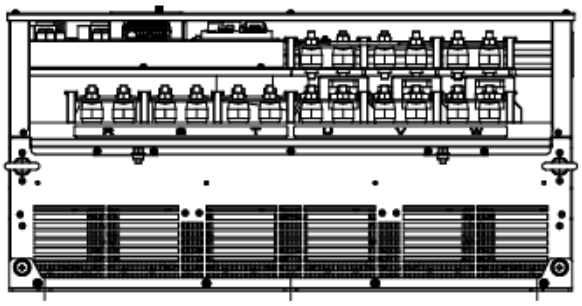


Diemsions

Model	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]	Ø [mm]	Weight [kg]
1850HF	500	350	920	890	390	14	110
2200HF	500	350	920	890	390	14	110

3.2.12 iMASTER C1-2800HF~3500HF





Diemsions

Model	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]	Ø [mm]	Weight [kg]
2800HF	806	350	1020	980	395	14	170
3500HF	806	350	1020	980	395	14	170

4. OPERATION

⚠ DANGER

- Be sure not to touch the main terminal or to check the signal add or remove wires and/or connectors.
- Be sure not to turn the input power supply on until after front case is closed.
  While the inverter is energized, be sure not to remove the front cover.
- Be sure not to operate the switches with wet hands.
- While the inverter is energized, be sure not to touch the inverter terminals even while the unit is not running.
- If the retry mode is selected, it may suddenly restart during the trip stop.
  Be sure not to approach the equipment. (Be sure) to design the equipment so that personnel safety will be secured even if equipment restarts.
- Even if the power supply is cut for a short period of time, the inverter may restart operation after the power supply is restored if the operation command is given.
  If a restart may incur danger to personnel, be sure to make a circuit so that it will not restart after power recovery.
- The stop key is valid only when a function is on. Ensure that there is a hardware emergency stop that is separate from the stop key of the inverter.
- With the operation command on, if the alarm reset is ordered, the inverter can restart suddenly. Be sure to set the alarm reset after checking the operation command is off.
- Be sure not to touch the inside of the energized inverter or to put a bar into it.

⚠ CAUTION

- The cooling fins will have high temperature. Be sure not to touch them.
- Low to high speed operation of the inverter can be easily set. Be sure to operate it after checking the tolerance of the motor and machine.
- Install an external braking system if needed.
- If a motor is operated at a frequency higher than standard setting value(50Hz/60Hz), be sure to check the speeds of the motor and the machine from their manufacturers. After getting their consent, operate them.

4.1 Keypad overview

iMASTER C1 inverter's digital operator is LED type. Please use attached LED operator for running.

4.1.1 Keypad description

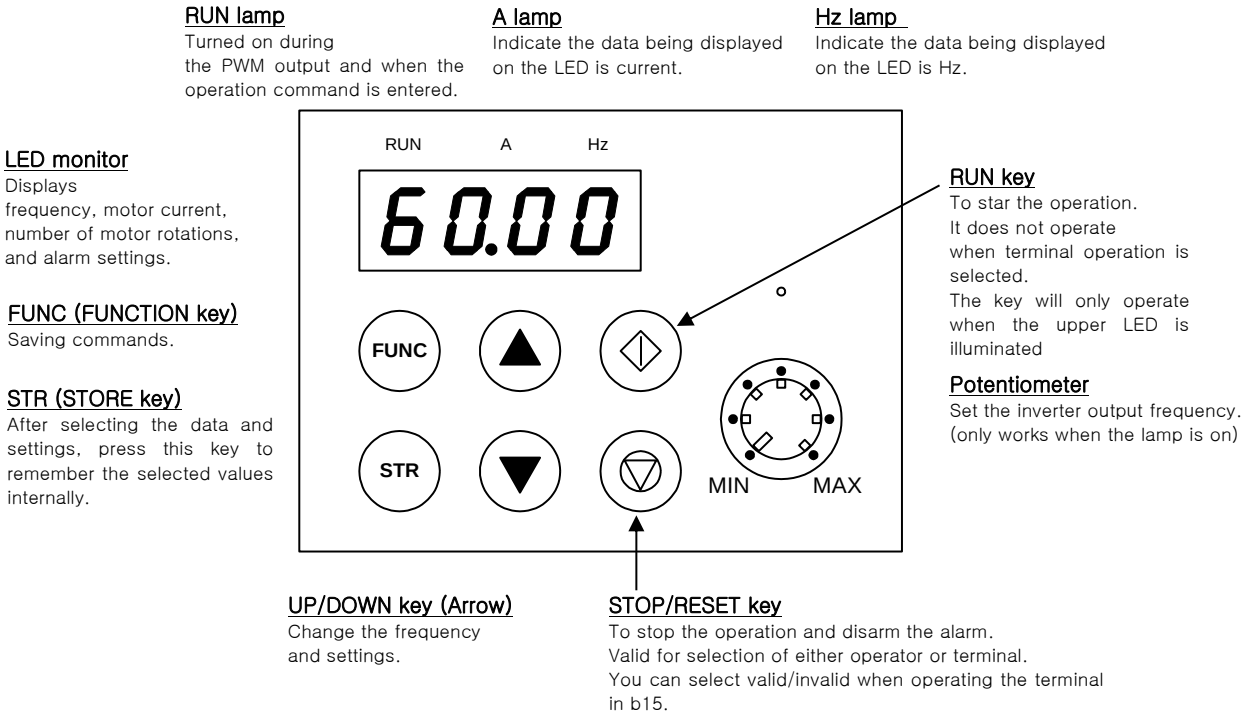


Figure 4-1 LED Keypad description

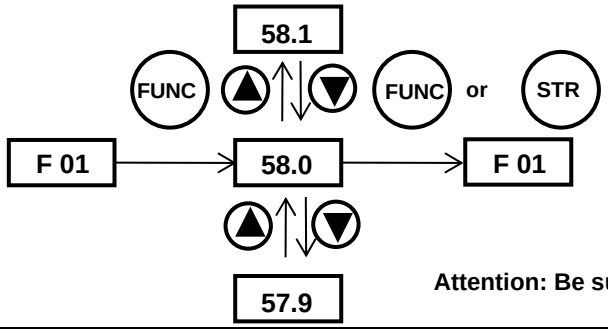
Initial keypad display description

Default mode of keypad display is d01 – output frequency of inverter.
Enter b30, you can set the mode of display: d01~d13.

4.1.2 Keypad navigation

1) Keypad navigation

Table 4-1 Keypad navigation

Key	Function description
FUNC	**[FUNC(FUNCTION key)] : Use to switch mode to command saving, data setting, extension function and default mode. Pressing this key will change the display to the following at any time.**  **Attention: Be sure press STR for saving.**
RUN	**[RUN key] : It executes the inverter to running.** **F 04 determines a forward run or reverse run.**
STOP/ RESET	**[STOP/RESET key] : It executes the inverter to stop. For trips, it reset the inverter.**
▲▼	**[UP key, DOWN key)] : Select the value of setting or command by moving key.**

※ Attention for STR key

If you want to store the data using STR key, please stay at least 6sec without any change or moving up/down key.

If you change anything such as key operations, reset operations, and power down before 6 seconds, the correct data may not be stored.

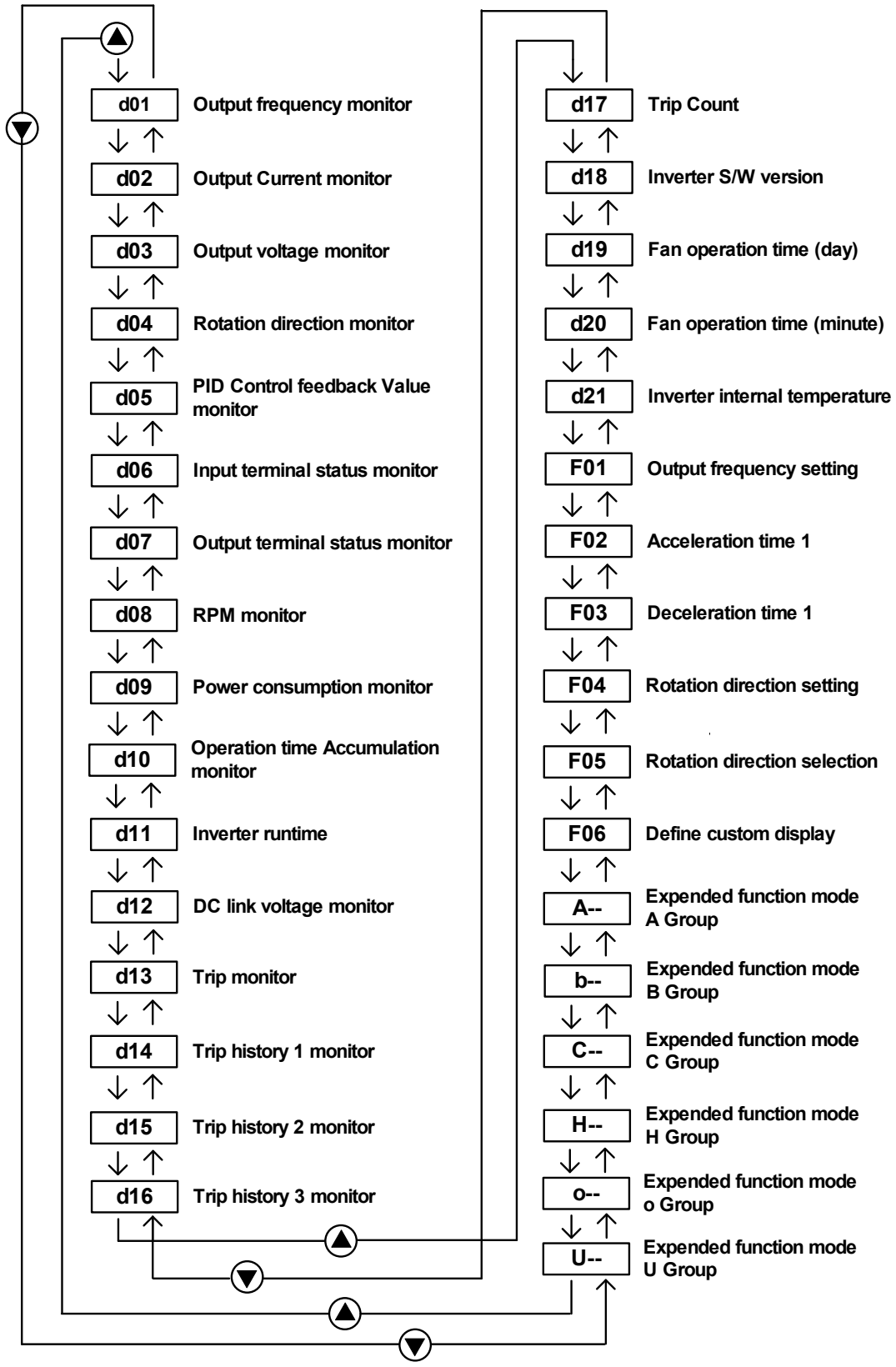


Figure 4-2 Up/Down key basic operation

2) Expended function mode navigation

Using the ▲ / ▼ key to enter the expanded function mode, select expanded Function command NO. in A-- b-- C-- H-- o-- and U-- mode.

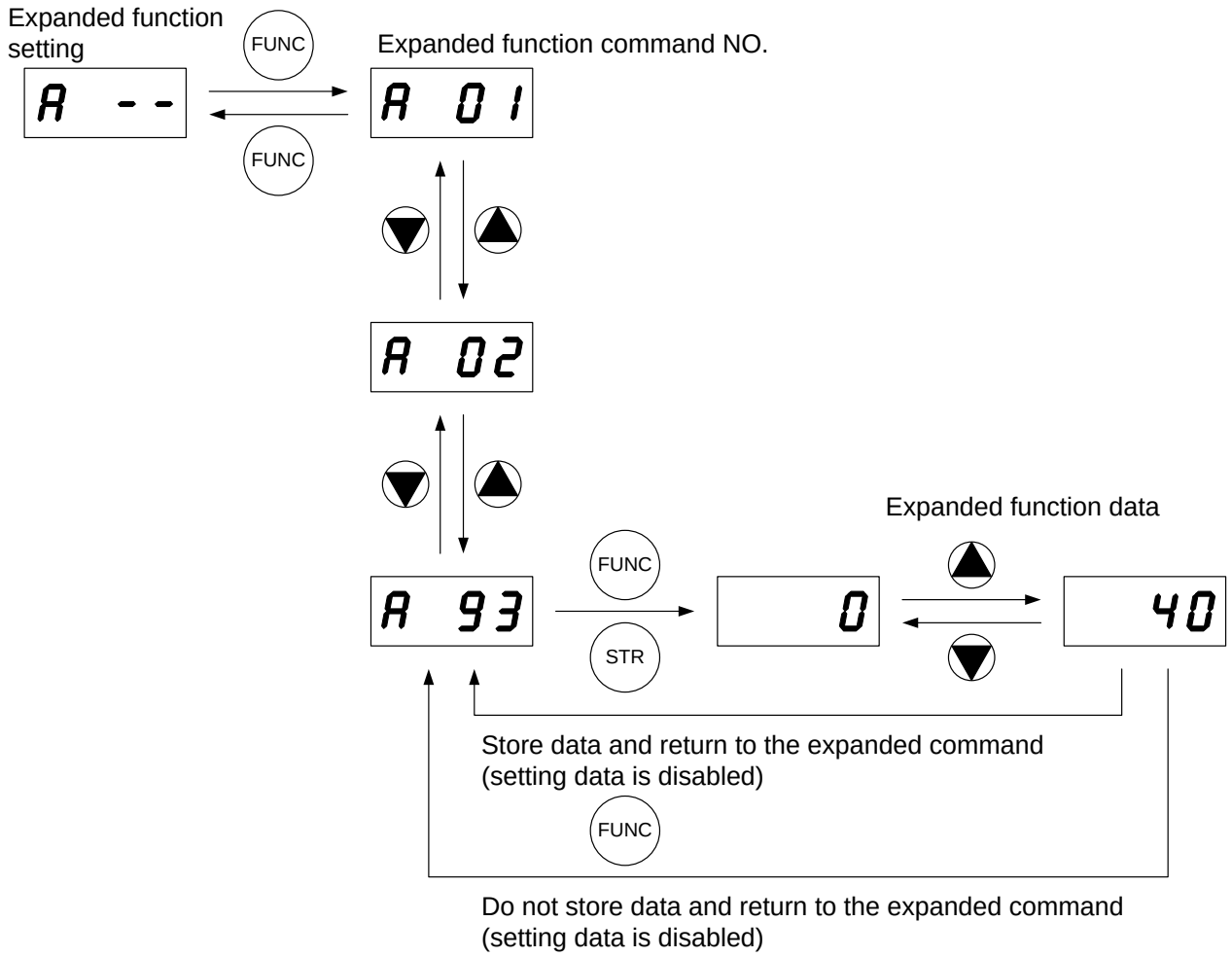


Figure 4-3 Expended function mode navigation

3) Navigation example: Mode change with arrow keypad

(Change the way of frequency setting from potentiometer to up/down key.
Running the inverter by up/down key operation)

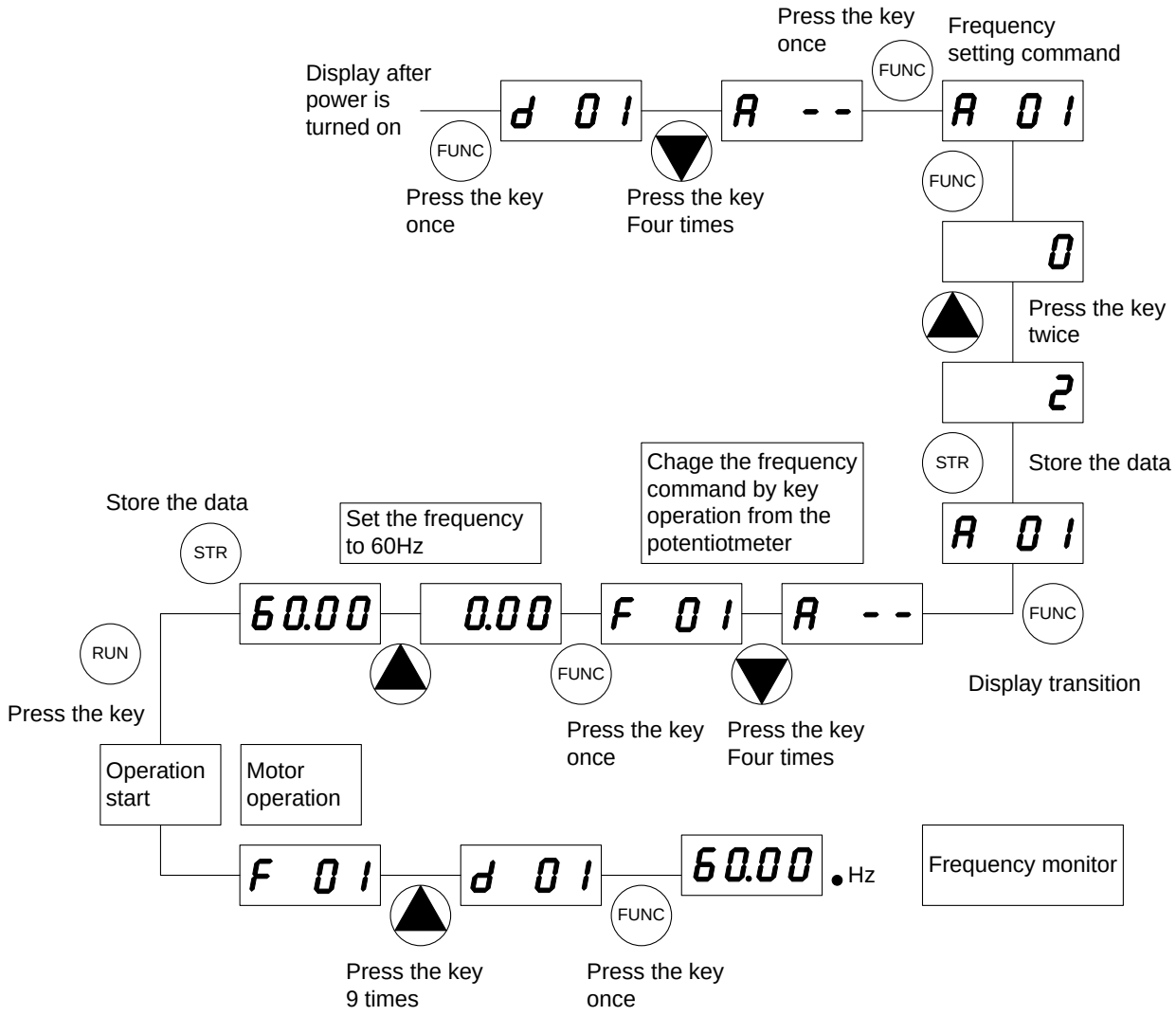


Figure 4-4 Navigation example: Mode change with arrow keypad

4.1.3 Shift key function

The “SHIFT” function is enabled to press both up and down key simultaneously. The left segment digit is blinked and if press store key, the blinked segment moves to the right digit.
When the ‘store’ key is pressed, it moved to the right digits again.
When the right most digit is blinked and press the ‘store’ key, it turned back to the function code display.

1. Display digit movement

- Press the UP key and Down key at the same time in data setting mode.
  → Change scroll mode to shift mode.

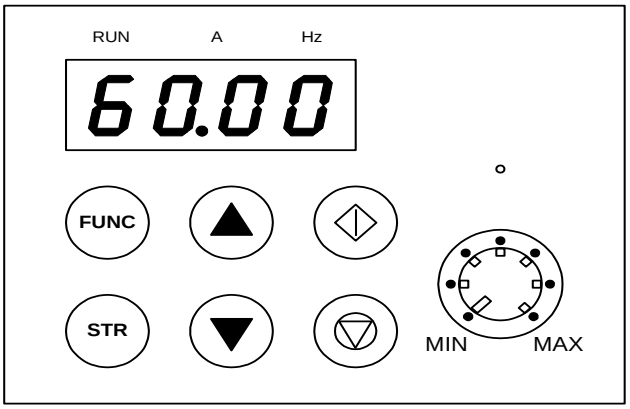


Figure 4-5 How to use Shift key

2. Data setting method

Stop in target group using UP/DOWN key → Press the function key, Change to data setting mode.

1) Press the UP key and DOWN key at the same time. → First number is flashing on the left
2) Change the data using UP/DOWN key → Press the Store-key → Third number is flashing.
3) Change the data using UP/DOWN key → Press the Store-key → Second number is flashing
4) Change the data using UP/DOWN key → Press the Store-key → First number is flashing
5) Change the data using UP/DOWN key → Press the Store-key → Target function code is setting

4.2 Frequency and run sources

In order to run the inverter, the run command source and frequency command source must be determined. Select one frequency command source and one run command source from list below and follow the instruction in the section referenced

4.2.1 Control terminal operation

Connect external signal to control terminal then running the inverter with this signal.
Start operation by operation command (FW, RV) after inverter turning on.
However, there are 2 ways for setting the terminal frequency – run or frequency command, please select for each system.

For detailed specifications, refer to the control circuit terminal description (required for operation)

1) Run command: The inverter is run/stop by external signal inputs such as switches and relays.
(Please refer 4-3)

2) Frequency command: Operating frequency is determined external signals 0 to 10V or 4 to 20mA.
(Please refer 4-3)

4.2.2 Digital keypad operation

Operation the inverter with mounted keypad – arrow key and potentiometer.

<Operation navigation>
1. Set frequency command source to potentiometer (A01=0)
2. Set run command source to standard operator (A02=0)
3. Press RUN button on the mounted operator, inverter will be run.
4. Change frequency using potentiometer.
(If set A01=2, can change frequency with up/down key ▲▼.)

4.2.3 Combination control terminal and digital keypad

Operation the inverter with combined way.
You can select the way of setting for frequency command and run command each.

4.2.4 Communication (RS-485) operation

The inverter can be driven by a communication command from an external control device, such as a PLC.
You can also control the inverter through the optional Remote Operator (ROP).
See '6. Communication Functions' for details.

4.3 Test run

This is an example of a common connection. If you prefer to use digital operator, please refer to detailed use of the digital operator.

4.3.1 To input the operation setting and the frequency setting from the terminal

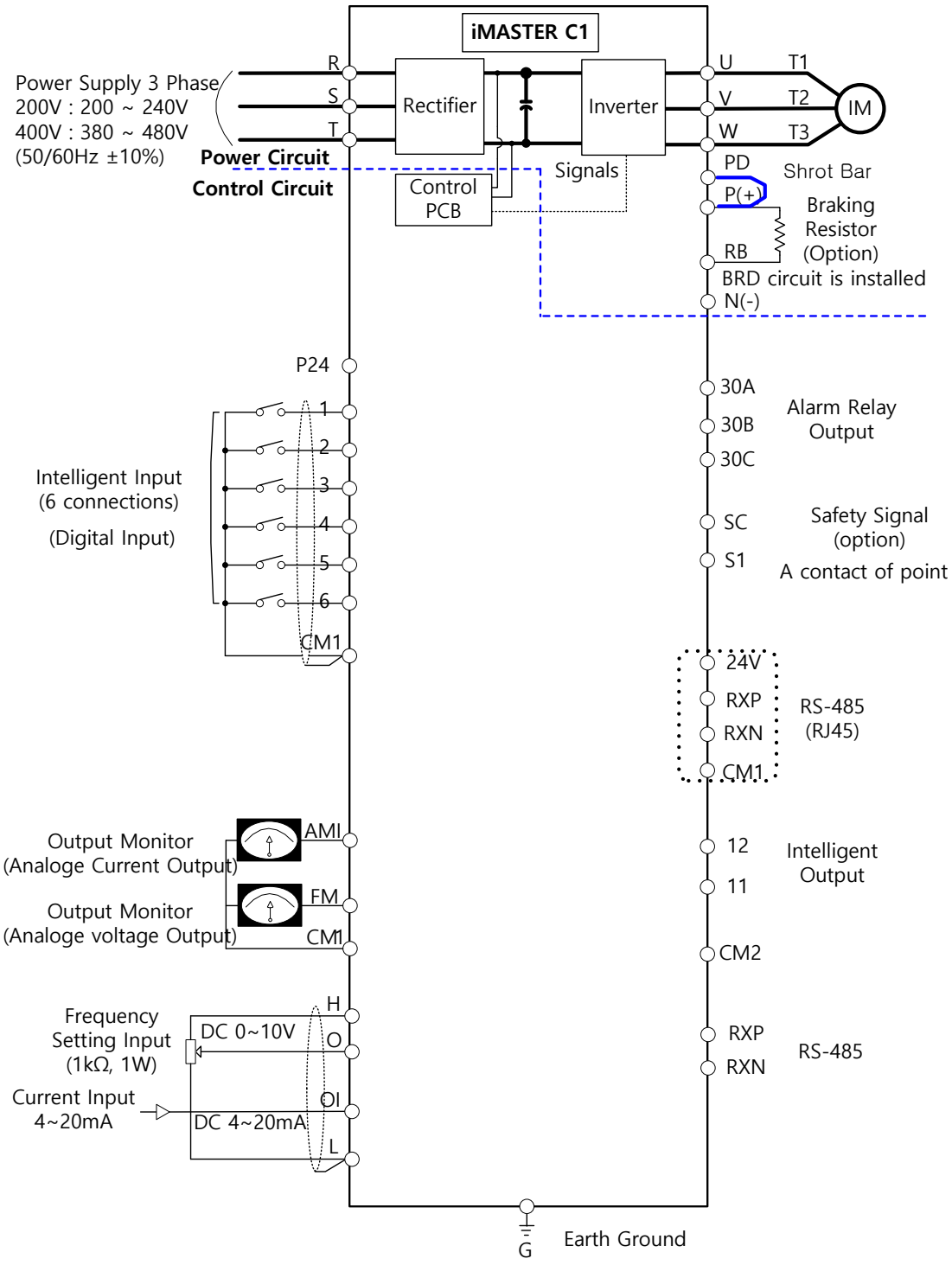


Figure 4-6 Setting diagram from the terminal

<Procedure>

(1) Please make sure that the connections are secured correctly.
- Connect the power supply to R(L1), S(L2), T(L3)
- Connect the motor to U(T1), V(T2), W(T3)

(2) Turn on power supply to the inverter
- Please make sure the operator should illuminate.

(3) Set the terminal with the frequency setting selection.
- Set A01 as the indication code, press the FUNC once. (Code values are shown)
- Set 1 with ∧, press the STR once to set the operation setting for the operator.
  (Indication code turns back to A01)

(4) Set terminal with the operation setting selection.
- Set A02 as indication code, press the FUNC once.
- Set 1 with the ∧ ∨ key, press the STR key once to set the operation setting for the operator.
  (Indication code turns back to A02.)

(5) Set monitor mode
- When monitoring the output frequency, set indication code to d01.
  Or when monitoring the operation direction, set indication code to d04.

(6) Input start operation setting
- Turn on between [FW] and [CM1] of terminal.
  (Run command to the inverter)
- Apply voltage [O] and [L] of terminal to start operation.
  (Frequency command to the inverter)

(7) Input stop operation setting.
- Turn OFF between [FW (1)] and [CM1] to slowly stop.

4.3.2 Operation setting and the frequency setting from the digital operator

(Remote operator is also same use.)

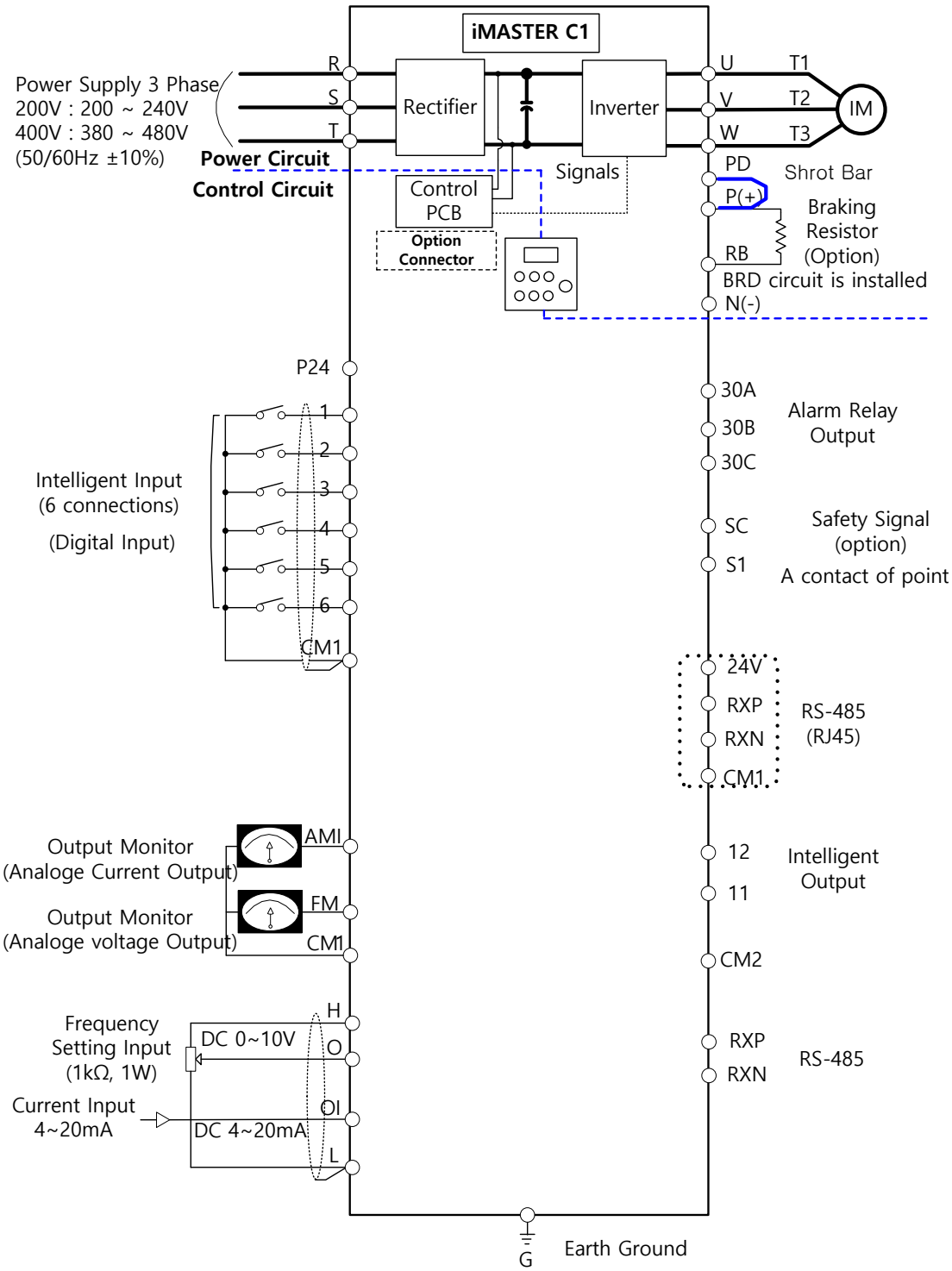


Figure 4-7 Setting diagram from the digital operator

<Procedure>

(1) Please make sure that the connections are secured correctly.
- Connect the power supply to R(L1), S(L2), T(L3)
- Connect the motor to U(T1), V(T2), W(T3)

(2) Turn on power supply to the inverter.
- Please make sure the operator should illuminate.

(3) Set the operator with the frequency setting selection.
- Set A01 as indication code, press the FUNC key once. (Code values are shown.)
- Set 2 with ∧ key (In case of remote is 3), press STR key once to set the operation setting for the operator. (Indication code turns back to A01.)

(4) Set the operator with the operation setting selection.
- Set A02 as the indication code, and set 0. Press STR key to set the operation setting.

(5) Set the output frequency.
- Set F01 as indication code, and pressing FUNC key once. (Code values are shown.)
- Set to the desired output frequency with ∧, ∨ key, press STR key once to store it.

(6) Set Monitor mode.
- When monitoring the output frequency, set indication code to d01. Or when monitoring the operation direction, set indication code to d04.

(7) Press the RUN key to start operating.
- “Run” lamp turns on a light.

(8) Press the STOP key to decelerate to a stop.
- When the frequency returns to 0, the RUN lamp light will switch off.

• Check whether there is no trip, number of turns, and frequency meter are correct during operation.
• Set the accel/decel time longer, when an over-current trip or over-voltage trip occurs.

5. PARAMETERS

5.1 Monitoring (d group)

Table 5-1 Monitor mode (d group)

Func-code	Name	Description	Page
d01	Output frequency monitor	Display of output frequency	6-1
d02	Output current monitor	Display of output current	
d03	Output voltage monitor	Display of output voltage	
d04	Rotation direction monitor	Display of direction of operation	
d05	PID feedback monitor	Displays the scaled PID process variable (%)	
d06	Intelligent input terminal monitor	Displays the state of the intelligent input terminals	
d07	Intelligent output terminal monitor	Displays the state of the intelligent output terminals	
d08	RPM monitor	Display of output RPM	6-2
d09	Power consumption monitor	Display of power consumption	
d10	Operation accumulated time(day)	Display of cumulative time (day)	
d11	Operation accumulated time (minute)	Display of cumulative time (minute)	
d12	DC ling voltage	Display of DC link voltage	

5.2 Trip monitor (d group)

Table 5-2 Trip monitor mode (d group)

Func-code	Name	Description	Page
d13	Trip event monitor	Display the current trip event	6-3
d14	Trip history 1 monitor	Display the previous first trip event	
d15	Trip history 2 monitor	Display the previous second trip event	
d16	Trip history 3 monitor	Display the previous third trip event	
d17	Trip count	Displays the trip accumulation count	
d18	Inverter S/W version	Display software version of inverter	6-4
d19	Fan operation time (day)	Display fan accumulation time (day)	
d20	Fan operation time (minute)	Display fan accumulation time (minute)	
d21	Inverter internal temperature	Display Inverter internal temperature (°C)	
d22	Encoder Speed	Display of encoder speed	

5.3 Basic function (F group)

Table 5-3 Basic function mode (F group)

Func-code	Name	Range	Defaults	Runtime edit	Page
F01	Output frequency setting	0.00~400.00[Hz] Sensorless 0.00~300.00 [Hz]	0.00Hz	O	6-5
F02	Acceleration time 1 setting	0.1 ~ 6000.0 [sec]	(Note1)	O	
F03	Deceleration time 1 setting	0.1 ~ 6000.0 [sec]	(Note1)	O	
F04	Rotation direction setting	0 - Forward 1 - Reverse	0	X	
F05	Rotation direction selection	0 - Enable both way (FW and RV) 1 - Disable forward 2 - Disable reverse	0	X	6-6
F06	Define custom display	0 ~ 65535	1.0	O	

(Note1) When the switching frequency is set to less than 2 kHz, the acceleration/deceleration time is delayed by about 500 msec.

The initial value of acceleration/deceleration time depending on the capacity.

Accel time initial value - 22kW or less: 5.0 s, 30kW or more: 30.0 s
Decel time initial value - 22kW or less: 10.0 s, 30kW or more: 30.0 s

5.4 Extended function A mode (A group)

Table 5-4 Extended function A mode (A group)

Func-code	Name	Range	Defaults	Runtime edit	Page
Basic parameter setting					
A01	Frequency command (Multi-speed command method)	0 - Keypad potentiometer 1 - Control terminal input 2 - Standard operator 3 - Remote operator (1st communication -RJ45) 4 - Remote operator (2nd communication - terminal) 5 - Option(reserved) 6 - Potentiometer and remote	1	X	6-7
A02	Run command	0 - Standard operator 1 - Control terminal input 2 - Remote operator (RJ45) 3 - Remote operator (Terminal) 4 - Option(reserved)	1	X	
A03	Base frequency setting	0.00 ~ Max. frequency(A04) [Hz]	60.00Hz	X	
A04	Maximum frequency setting	Base frequency (A03) ~ 400 [Hz] In case of sensorless vector (A31=2), Base frequency (A03) ~ 300 [Hz]	60.00Hz	X	
Analog Input Settings (External frequency setting)					
A05	External frequency setting start (O, OI)	0.00 ~ Max. frequency (A04) [Hz]	0.00Hz	X	6-8
A06	External frequency Setting end (O, OI)	0.00 ~ Max. frequency (A04) [Hz]	0.00Hz	X	
A07	External frequency start rate setting (O, OI)	0.0~100.0 [%]	0.0%	X	
A08	External frequency end rate setting (O, OI)	0.0~100.0 [%]	100.0%	X	
A09	External frequency start pattern setting	0 - Start at start frequency (A05) 1 - Start at 0 Hz	0	X	
A10	External frequency sampling setting	0.1~500.0 [ms]	1.0ms	X	6-9

Func-code	Name	Range	Defaults	Runtime edit	Page
Multi-speed Frequency Setting					
A11 ~ A25	Multi-speed frequency setting	0.00 ~ Max. frequency (A04) [Hz]	speed1:5Hz speed2:10Hz speed3:15Hz speed4:20Hz speed5:30Hz speed6:40Hz speed7:50Hz speed8:60Hz etc. 0Hz	O	6-9
A26	Jogging frequency setting	0.50~10.00 [Hz]	0.50Hz	O	6-10
A27	Jogging stop operation selection	0 - Free-run stop 1 - Deceleration stop (depending on deceleration time) 2 - DC injection braking stop (necessary to set DC injection braking)	0	X	
V/F Characteristics					
A28	Torque boost mode selection	0 - Manual torque boost 1 - Automatic torque boost * For use automatic torque boost, Need to set for motor (H group)	0	X	6-11
A29	Manual torque boost setting (forward)	0.0~50.0 [%]	(Note 1)	O	
A30	Manual torque boost Frequency setting (forward)	0.0~100.0 [%]	100.0%	O	
A31	V/F characteristic curve selection	0 - Constant torque 1 - Reduced torque (reduction of the 1.7thpower) 2 - Sensorless vector control 3 - VF_USER 4 - VF_ Permanent magnet synchronous motor control 5 – Vector (Encoder Option)	0	X	6-12
A32	V/F gain setting	20.0~110.0 [%]	100.0%	O	6-13

(Note 1) Depends on inverter power range
200V Class
3.7kW or less:2.0[%], 5.5kW:2.3[%], 7.5kW:2.1[%], 11kW:1.9[%], 15kW:1.7[%]
400V Class
3.7kW or less: 2.0[%], 5.5kW:2.3[%], 7.5kW:2.1[%], 11kW:1.9[%], 15kW:1.7[%], 18.5kW:1.6[%], 22kW~160kW:1.5[%], 185kW~280kW:1.4[%], 350kW:1.3[%]

Func-code	Name	Range	Defaults	Runtime edit	Page
DC Injection Braking Settings					
A33	DC injection braking function selection	0 - Disable 1 - Enable	0	X	6-13
A34	DC injection braking Frequency setting	0.50~10.00 [Hz]	0.50Hz	X	
A35	DC injection braking output delay time setting	0.0~5.0 [sec]	0.0 sec	X	
A36	DC injection braking force setting	0.0~100.0 [%]	~22kW:50.0% 30~132kW:10.0% 160kW~:7.0%	X	
A37	DC injection braking time setting	0.0~10.0 [sec]	0.0 sec	X	6-14
Frequency-related Functions					
A38	Frequency upper limit setting	Frequency lower limit (A39) ~ Max. frequency (A04) [Hz]	0.00Hz	X	6-14
A39	Frequency lower limit setting	0.00~Frequency upper limit (A38) [Hz]	0.00Hz	X	
A40 A42 A44	Jump(center)frequency setting	0.00~ Max. frequency (A04) [Hz]	0.00Hz	X	6-15
A41 A43 A45	Jump(hysteresis) frequency width setting	0.00~10.00 [Hz]	0.00Hz	X	
A46	Manual torque boost setting (Reverse)	0.0~50.0 [%]	(Note 1)	O	
A47	Manual torque boost Frequency setting (Reverse)	0.0~100.0 [%]	100.0%	O	6-16
A48	Auto Torque Boost Gain	0.00~2.50 [x1]	x1.00	O	
A49	Auto Torque Boost filter tow	0.1~999.9 [ms]	80.0 ms	O	

(Note 1) Depends on inverter power range
200V Class
3.7kW or less:2.0[%], 5.5kW:2.3[%], 7.5kW:2.1[%], 11kW:1.9[%], 15kW:1.7[%]
400V Class
3.7kW or less: 2.0[%], 5.5kW:2.3[%], 7.5kW:2.1[%], 11kW:1.9[%], 15kW:1.7[%], 18.5kW:1.6[%], 22kW~160kW:1.5[%], 185kW~280kW:1.4[%], 350kW:1.3[%]

Func-code	Name	Range	Defaults	Runtime edit	Page
Automatic Voltage Regulation (AVR) Function					
A52	AVR function selection	0 - Constant ON 1 - Constant OFF 2 - OFF during deceleration	2	X	6-16
A53	Motor input voltage setting	200V Class -80~240V 400V Class -160~500V	(Note 2)	X	
Second Acceleration and Deceleration Functions					
A54	Second acceleration time setting	0.0~6000.0 [sec]	5.0 sec	O	6-17
A55	Second deceleration time setting	0.0~6000.0 [sec]	10.0 sec	O	
A56	Two stageacce1/dece1 switching method selection	0 - 2CH input from terminal 1 - Transition frequency from acc/dec1 to acc/dec2	0	X	
A57	Acc1 to Acc2frequency transition point note3	0.00~Max.freqeuncy (A04) [Hz]	0.00Hz	X	
A58	Decel 1 to Decel 2 frequency transition point note3	0.00~Max.freqeuncy (A04) [Hz]	0.00Hz	X	
A59	Acceleration curve selection	0 - Linear 1 - S curve 2 - U curve	0	X	6-18
A60	Deceleration curve setting	0 - Linear 1 - S curve 2 - U curve	0	X	
Others					
A61	Input voltage offset setting	-100.0~100.0 [%]	0.0%	O	6-9
A62	Input voltage gain setting	-200.0~200.0 [%]	100.0%	O	
A63	Input current offset setting	-100.0~100.0 [%]	0.0%	O	
A64	Input current gain setting	-200.0~200.0 [%]	100.0%	O	
A65	FAN operation mode	0 - Always ON 1 - ON in the run time 2 - ON in Case Inverter internal temperature(d21) is More than 70°C	0	X	6-18

(Note 2) SF/LF : 220V, HF: 380V

(Note 3) If the acceleration and deceleration times are set to a value less than or equal to 1 second, the saving frequency will be inaccurate.

Func-code	Name	Range	Defaults	Runtime edit	Page
S curve ratio setting					
A66	S curve start ratio setting of acceleration	0.0~100.0[%]	50.0%	O	6-18
A67	S curve stop ratio setting of acceleration	0.0~100.0[%]	50.0%	O	
A68	S curve start ratio setting of deceleration	0.0~100.0[%]	50.0%	O	6-19
A69	S curve stop ratio setting of deceleration	0.0~100.0[%]	50.0%	O	
PID Control					
A70	PID Function selection	0 - PID control disable 1 - PID control enable 2 - F/F control enable 3 - PID control enable at Stop 4 - PID,F/F control enable at Stop	0	X	6-19
A71	PID Reference	0.00 ~ 100.00 [%]	0.00%	O	
A72	PID Reference source	0 - Keypad potentiometer 1 - Control terminal input 2 - Standard operator 3 - Remote operator (RJ45) 4 - Remote operator (Terminal) 5 - Option(reserved) 6 - Potentiometer and RJ45	2	X	6-20
A73	PID Feed-back source	0 - Current input (OI) 1 - Voltage input (O)	0	X	
A74	PID P gain	0.1 ~ 1000.0 [%]	100.0%	O	
A75	PID I gain	0.0 ~ 3600.0 [sec]	1.0sec	O	
A76	PID D gain	0.00 ~ 10.00 [sec]	0.00sec	O	
A77	PID Err limit	0.0 ~ 100.0 [%]	100.0%	O	6-21
A78	PID Output high limit	PID Output low limit (A79)~100.0 [%]	100.0%	O	
A79	PID Output low limit	-100.0~PID Output high limit (A78) [%]	0.0%	O	
A80	PID Output reverse	0 - PID output reverse disable 1 - PID output reverse enable	0	X	
A81	PID scale factor	0.1 ~ 1000.0 [%]	100.0%	X	
A82	Pre PID frequency	0.00 ~ Max. frequency(A04) [Hz]	0.00Hz	X	6-22
A83	Sleep frequency	0.00 ~ Max. frequency(A04) [Hz]	0.00Hz	X	
A84	Sleep/wake up delay time	0.0 ~ 30.0 [sec]	0.0sec	X	
A85	Wake up frequency	0.00 ~ Max. frequency(A04) [Hz]	0.00Hz	X	6-23

Func-code	Name	Range	Defaults	Runtime edit	Page
Set user V/F pattern ratio					
A86	User V/F setting frequency 1	0 ~ V/F setting frequency 2 (A88)	15.00Hz	X	6-26
A87	User V/F setting voltage 1	0 ~ V/F setting voltage 2 (A89)	25.0%	X	
A88	User V/F setting frequency 2	V/F setting frequency 1 (A86) ~ V/F setting frequency 3 (A90)	30.00Hz	X	
A89	User V/F setting voltage 2	V/F setting voltage 1 (A87) ~ V/F setting voltage 3 (A91)	50.0%	X	
A90	User V/F setting frequency 3	V/F setting frequency 2 (A88) ~ V/F setting frequency 4 (A92)	45.00Hz	X	
A91	User V/F setting voltage 3	V/F setting voltage 2 (A89) ~ V/F setting voltage 4 (A93)	75.0%	X	
A92	User V/F setting frequency 4	V/F setting frequency 3 (A90) ~ Max. frequency (A04)	60.00Hz	X	
A93	User V/F setting voltage 4	V/F setting voltage 3 (A91) ~ 100.0 [%]	100.0%	X	
A94	FAN fault Detection	0 - Ignore in case of FAN fault 1 - Display FAN fault 2 - Display Alarm	1	X	6-27
A95	Deceleration time after DC injection braking	0.0 ~ 1.0 [sec]	0.00	O	

5.5 Extended function b mode (b group)

Table 5-5 Extended function b mode (b group)

Func-code	Name	Range	Defaults	Runtime edit	Page
Restart Mode					
b01	Selection of restart mode	0 - Alarm output after trip 1 - Restart at 0Hz 2 - Resume operation after frequency matching 3 - Resume previous freq. after freq. matching,then decelerate to stop. And display trip info.	0	X	6-28
b02	Allowable instantaneous power failure time setting	0.3~10.0 [sec]	1.0 sec (Note 1)	X	
b03	Reclosing standby after Instantaneous power failure recovered	0.3~10.0 [sec]	1.0 sec	X	
Electronic Thermal Setting					
b04	Electronic thermal level setting	Motor rated current x 20.0%~ 120.0%	100.0%	X	6-31
b05	Electronic thermal characteristic, selection	0 - Cooling fan is mounted on the motor shaft (Self-cool) 1 - Cooling fan is powered by external source (Forced-cool)	1	X	
Overload Restriction					
b06	Overload Restriction mode selection	0 - Overload restriction mode OFF 1 - Maintain Output frequency in case of overload 2 - In case of overload Operate according to b08 setting 3 - In case of overload, operates at a maximum of 20% of the acceleration time setting. * Overvoltage setting is b67	2	X.	6-32
b07	Overload restriction level setting (constant speed)	Set Between 20%~200% of rated current of inverter HD: 20.0%~ 200.0% ND: 20.0%~ 165.0% * If there is speed change, you can set at b49	Note5	X	
b08	Overload restriction constant setting	0.1~10.0 [sec]	10.0 sec	X	6-33

(Note 1) Allowable instantaneous power failure time is depending on machine or load conditions, So, please check and verification test before using.

Func-code	Name	Range	Defaults	Runtime edit	Page
Others					
b09	Software lock mode selection	0 - All parameters locked (Except b09, when SFT from terminal is on) 1 - All parameters locked (Except b09 and F01, when SFT from terminal is ON) 2 - All parameters locked (Except b09, when function set) 3 - All parameters locked (Except b09 and F01, when function set) 4 - All parameters locked (Except b09, F01, F02, F03, when function set)	0	X	6-33
b10	Start frequency Adjustment	0.10~ Maximum frequency Setting(A04) [Hz]	0.50Hz	X	6-34
b11	Carrier frequency setting	0.75~16.0[kHz] (0.4kW~3.7kW) 0.75~10.0[kHz] (5.5kW~22kW) 0.75~4[kHz] (160kW~)	Note3	O	
b12	Initialization mode	0 - Trip history clear 1 - Parameter initialization	0	X	
b13	Country code for initialization	0 - Korean version 1 - Europe version 2 - US version	0	X	
b14	RPM conversion factor setting	0.01~99.99	1.00	O	6-35
b15	STOP key validity during terminal operation	0 - STOP enable 1 - STOP disable	0	X	
b16	Resume on FRS cancellation mode	0 - Restart from 0Hz 1 - Restart from frequency detected from real speed of motor	0	X	
b17	Communication number	1~32 [count]	1	X	
b18	Ground fault setting (Note2)	0.0~100.0 [%] 0 - Do not detect ground fault.	0.0%	X	

(Note 2) Ground fault detection cannot be set under 22kW (fixed to 0).
Above 30kW, the customer can set and use it arbitrarily.
(Note 3) The initial value differs depending on the HD / ND and capacity. 22kW or less: 5kHz (HD)/2kHz (ND)
30kW~132kW : 3kHz(HD)/2kHZ(ND)
160kW or more: 2kHz(HD)/2kHZ(ND)

Func-code	Name	Range	Defaults	Runtime edit	Page
b19	Speed Search Delay Time	0.1~30.0[sec]	2.0 sec	O	6-36
b20	Voltage increase Time during Speed Search	0.1~10.0[sec]	1.0 sec	O	
b21	Current limit level of Speed search	50.0~180.0[%]	100.0 %	O	
b22	Deceleration time at FRS (Free Run Stop Command)	0.0 ~ 6000.0 [sec]	0.0	O	
b23	Frequency match operation selection	0 - 0Hz Starting operation 1 - Frequency matching & start operation	0	O	
b24	Failure status output selection by relay in case of failure	0 - Inactive at low voltage failure 1 - Active at voltage failure (Inactive at restart mode) 2 - Active of all failure occurred 3 - Active at voltage failure (For low voltage failure, automatic restart)	0	O	6-29
b25	Stop method selection	0 - Decelerating stop 1 - Free run stop 2 – Decelerating stop & Nonstop reset 3 – Free run stop & Nonstop reset	0	O	6-37
b26	Inverter type change to HD / ND[Note4]	0 - Heavy Duty (HD) (Note8) 1 - Normal Duty (ND)	0	X	6-37
b27	Input phase loss	0~30 [sec] 0 - Disable	10 sec	O	
b28	Communication time out setting	0~60 [sec] 0 - Disable	0 sec	O	
b29	Communication time out operation mode	0 - Always active & RESET alarm enabled 1 - Active in case of inverter is running & RESET alarm enabled 2 – Always active & RESET alarm disabled 3 – Active in case of inverter is running & RESET alarm disabled	0	O	
b30	Display code setting	1~13	1	O	
b31	2nd communication channel 485 communication speed setting	1 - 2400 [bps] 2 - 4800 [bps] 3 - 9600 [bps] 4 - 19200 [bps] 5 - 38400 [bps]	3	O	6-38

(Note 4) Below 3.7kW, value is always 0
Upper 5.5kW, able to use as above range.

Func-code	Name	Range	Defaults	Runtime edit	Page
BRD (Dynamic braking) Function					
b32	BRD selection	0 - Disable 1 - Enable only during inverter running 2 - Enable	1	X	6-38
b33	BRD using ratio	0~10 [%] (0.4kW~3.7kW) 0~50 [%] (5.5kW~22kW)	10%	X	
Overvoltage Suppression (OVS) Function					
b34	Maximum OVS output frequency	0.00~300.0 [Hz]	20.00Hz	O	6-40
b35	OVS P gain	0~10000	1000	O	
b36	OVS I gain	0~10000	100	O	6-41
b37	OVS D gain	0~10000	100	O	
b38	Q axis reference	-100~100.0	0.0	O	
b39	Filter bandwidth	0~1000	1	O	6-42
b40	Overvoltage suppression	0 - Disable 1 - Enable for current 2 - Enable for voltage	0	O	
b41	Limit Time	0.0~100.0 [sec]	0.5 sec	O	
DC Injection Braking					
b42	VFD start delay time after DC Injection braking	0.0~60.0 [sec]	0.0 sec	X	6-43
b43	DC Injection braking time at start	0.0~6000[sec]	0.0 sec	O	
b44	Current controller P gain in DC braking	1~10000	500	O	
b45	Current controller I Gain time in DC braking	0~10000	500	O	
b46	DC Injection braking force	0.0~100.0[%] of inverter rated current	50.0%	O	6-44

Func-code	Name	Range	Defaults	Runtime edit	Page
Overload Restriction					
b49	Overload restriction level at acceleration & deceleration	HD: 20.0%~ 200.0% ND: 20.0%~ 165.0%	Note5	X	6-44

(Note 5) The initial value differs depending on the ND / HD setting and capacity.
~ 132kW: HD-180%, ND-150% / 160kW~350kW: HD-150%, ND-120%

Func-code	Name	Range	Defaults	Runtime edit	Page
Droop Control function					
b50	Droop control start freq.	0.00 ~ Max. frequency (A04) [Hz]	0.00Hz	O	6-44
b51	Droop control standard freq.	10.00 ~ Max. frequency (A04) [Hz]	60.00Hz	O	
b52	Droop control gain	0.00~50.00 [%]	5.00%	O	
b53	Droop star torque	0.0~100.0 [%]	0.0%	O	6-45
b54	Droop acceleration time	1.0~100.0 [sec]	20.0sec	O	
b55	Droop control mode	0 - Disable 1 - Enable	0	O	
Motor Load Detection Function					
b56	Motor load detection selection	0 - Disable 1 - Overload detection 2 - Underload detection 3 - Overload/Underload detection 4 - Overload detection with fault (E23) 5 - Underload detection with fault (E24) 6 - Overload/Underload detection with fault (E23, E24)	0	X	6-46
b57	Motor overload detection level	20.0~200.0 [%] of motor rated current	100.0%	X	
b58	Motor underload detection level	20.0~200.0 [%] of motor rated current	100.0%	X	6-47
b59	Overload/Underload detection time	0.0~60.0 [sec]	10.0sec	X	
b60	Overload/Underload detection safe zone	0.00 ~ Max. frequency (A04) [Hz]	0.00Hz	X	

Func-code	Name	Range	Defaults	Runtime edit	Page
Dwell Function					
b61	Dwell frequency at start	0.00 ~ Max. frequency (A04) [Hz]	0.00Hz	O	6-48
b62	Dwell time at start	0.0~10.0 [sec]	0.0sec	O	
b63	Dwell frequency at stop	0.00 ~ Max. frequency (A04) [Hz]	0.00Hz	O	
b64	Dwell time at stop	0.0~10.0 [sec]	0.0sec	O	
KEB Function					
b65	KEB control selection	0 - Disable 1 - Enable(According to b66 Setting) 2 - Enable(DC Link Control)	0	X	6-49
b66	KEB control gain	0.1~100.0[%]	10.0%	X	
Overcurrent Restriction					
b67	Overcurrent selection	0 - Disable 1 - Enable	1	X	6-50
b68	Hold time at running	0.0~60.0 [sec]	0.0sec	O	
b69	Stop frequency setting	0.00 ~ Max. frequency (A04) [Hz]	0.00Hz	O	
b70	Hold time at stop	0.0~60.0 [sec]	0.0sec	O	

Func-code	Name	Range	Defaults	Runtime edit	Page
Display Function					
b71	Unser parameter setting	1 - Output frequency monitor 2 - Output current monitor 3 - Output voltage monitor 4 - Rotation direction monitor 5 - PID feedback monitor 6 - Intelligent terminal input monitor 7 - Intelligent terminal output monitor 8 - RPM monitor 9 - Power consumption monitor 10 - Display of cumulative time (day) 11 - Display of cumulative time (minute) 12 - DC link voltage	1	O	6-51
b72	User mathematical sign	0 - '+' calculation 1 - '-' calculation 2 - 'X' calculation 3 - '/' calculation	0	O	
b73	Define user setting	0.01~600.00	1.00	O	

5.6 Extended function C mode (C group)

Table 5-6 Extended function C mode (C group)

Func-code	Name	Range	Defaults	Runtime edit	Page
Input Terminal Function					
C01	Intelligent input terminal 1 setting	0 - FW (Forward run command) 1 - RV (Reverse run command) 2 - CF1 (1st multi speed command) 3 - CF2 (2nd multi speed command) 4 - CF3 (3rd multi speed command) 5 - CF4 (4th multi speed command) 6 - JG (Jogging operation command) 7 – ZERO (Zero speed command) 8 - 2CH (2 stage accel/decel command) 9 - FRS (Free run stop command) 10 - EXT (External trip) 11 - USP (Unattended Start Protection) 12 - SFT (Software lock) 13 - AT (Analog input current/voltage selection signal) 14 - RS (Reset) 15 - STA (Start) 16 - STP (Keep) 17 - F/R (Forward/Reverse) 18 - UP (Remote control UP) 19 - DOWN (Remote control DOWN) 20 - O/R (Local keypad operation) 21 - T/R (Local terminal input operation) 22 - PIDIR (PID Integral reset) 23 - PIDD (PID Disable) 24 - Add A11 to setting frequency(F.O) 25 - Cancel add A11(R.O) 26 - EXT2 (External trip2) 27 - EXT3 (External trip3) 28 - EXT4 (External trip4) 29 - EXT5 (External trip5) 30 - EXT6 (External trip6) 31 - Up/Down Value Clear	0	X	6-52
C02	Intelligent input terminal 2 setting		1	X	
C03	Intelligent input terminal 3 setting		2	X	
C04	Intelligent input terminal 4 setting		3	X	
C05	Intelligent input terminal 5 setting		13	X	
C06	Intelligent input terminal 6 setting		14	X	

Func-code	Name	Range	Defaults	Runtime edit	Page
Input Terminal Status					
C07	Input terminal 1 a/b contact setting (NO/NC)	0 - a contact (Normal open) [NO] 1 - b contact (Normal close) [NC]	0	X	6-53
C08	Input terminal 2 a/b contact setting (NO/NC)		0	X	
C09	Input terminal 3 a/b contact setting (NO/NC)		0	X	
C10	Input terminal 4 a/b contact setting (NO/NC)		0	X	
C11	Input terminal 5 a/b contact setting (NO/NC)		0	X	
C12	Input terminal 6 a/b contact setting (NO/NC)		0	X	
Output Terminal and Related Function					
C13	Replay output(30A/30B/30C) terminal setting	0 - RUN (Run signal) 1 - FA1 (Frequency command arrival) 2 - FA2 (Setting frequency or more) 3 - OL (Overload advance notice) 4 - OD (Output deviation for PID) 5 - AL (Alarm signal) 6 - MO (Modbus communication) 7 - SOL (System Overload) 8 - SUL (System Underload) 9 - SOL/SUL (System Overload/Underload detection) 10 - AI_LOSS(Analog Input loss detection) 11 - KEY_LOSS(keypad loss detection) 12 - BRK(Control external braking)	5	X	6-75
C14	Open collector output (11-CM2) terminal setting		1	X	6-76
C15	Open collector output (12-CM2) terminal setting		0	X	
C16	Output terminal 11 - CM2 a/b contact setting	0 - a contact (Normal open) [NO] 1 - b contact (Normal close) [NC]	0	X	
C17	Output terminal 12 - CM2 a/b contact setting		0	X	
C18	FM output selection	0 - Output frequency monitor 1 - Output current monitor 2 - Output voltage monitor 3 - Output electric power monitor 4 - Output torque monitor 5 - Control by Modbus communication 6 - DC voltage	0	X	6-83
C19	FM gain adjustment	0~250.0 [%]	100.0%	O	6-84
C20	FM offset adjustment	-3.0~10.0 [%]	0.0%	O	

Func-code	Name	Range	Defaults	Runtime edit	Page
C21	Overload advance notice signal level setting	10.0~200.0 [%] of rated current	100.0%	X	6-84
C22	Acceleration arrival signal frequency setting	0.00~Max. frequency (A04) [Hz]	0.00Hz	X	
C23	Deceleration arrival signal frequency setting	0.00~Max. frequency (A04) [Hz]	0.00Hz	X	
C24	PID deviation level setting	0.0~100.0 [%]	10.0%	X	
C25	AMI output selection	0 – Output frequency monitor 1 – Output current monitor 2 – Output voltage monitor 3 – Output electric power monitor 4 – Output torque monitor 5 – Control by Modbus communication 6 – DC voltage	1	X	
C26	AMI gain adjustment	0 ~ 250.0%	100.0%	O	6-85
C27	AMI offset adjustment	-99.9 ~ 100.0%	0.0%	O	
Up/Down Function					
C28	UP/Down value saving selection	0 - Disable 1 - Enable	0	X	6-68
C29	Up/Down initial value setting	0 ~ Max. frequency [A04]	0.00Hz	O	
C30	Up/Down Target Frequency Acc/decel time setting	0.1~3000.0[sec]	10.0sec	O	
C31	Up/Down function selection	0 - Disable 1 - Enable	0	X	
C32	Up/Down value setting	0.00~400.00[%]	0	O	6-69
Keypad/Communication fault					
C33	Decel time at fault occur	0.0~6000.0[sec]	10.0sec	O	6-81
C34	Selection of running state when keypad connection failed	0 - Run 1 - Stop	0	X	
C35	Selection of keypad detection	0 - Disable 1 - Abnormal move detection 2 - Detect keypad fault and occur E61 3 - Detect abnormal move and occur E61	0	O	

Func-code	Name	Range	Defaults	Runtime edit	Page
C36	Selection of communication or analog speed command failure detection	0 – Disable 1 – Loss frequency (50%) (Less than 50% of A07) 2 – Loss frequency (100%) (Under than A07) 3 – Loss frequency when speed command by RS485	0	O	6-81
C37	Selection of run command when speed losing	0 – Disable 1 – Free run stop (Output block) 2 – Stop 3 – Run by C38 frequency	0	O	
C38	Waiting time in case of frequency command loss	0.0~120.0[sec]	1.0sec	O	
C39	Frequency setting in case of analog command loss	0.00 ~ Max. frequency [A04]	30.00Hz	O	
Overload Caution Time					
C40	Overload caution time	Detection time of overload advance notice signal level (C21) 0.0~30.0[sec]	10.0sec	O	
External Brake Function					
C41	Current of external brake	0.0~200.0 [%] of rated current	100.0%	O	6-82
C42	Frequency of external brake	0.00 ~ 25.00[Hz]	10.00Hz	X	
C43	Timer of external brake	0.0 ~ 5.0[sec]	1.0sec	O	
C44	Stop frequency of external brake	0.00 ~ 25.00[Hz]	10.00Hz	X	
C45	Stop timer of external brake	0.0 ~ 5.0[sec]	1.0sec	O	
C46	Changed Parameter Check	0 - Disable 1 - Enable	0	O	6-85

5.7 Motor (H group)

Table 5-7 Motor setting (H group)

Func-code	Name	Runtime edit	Range			Default
H01	Auto-tuning mode selection	X	0 - Auto-tuning OFF 1 - Auto-tuning ON			0
H02	Motor data selection	X	0 - Standard motor data 1 - Use auto-tuning data			0
H03	Motor capacity	X	0:MOT_004LF 1:MOT_007LF 2:MOT_015LF 3:MOT_022LF 4:MOT_037LF 5:MOT_055LF 6:MOT_075LF 7:MOT_110LF 8:MOT_150LF 9:MOT_185LF 10:MOT_220LF 11:MOT_300LF	12:MOT_004HF 13:MOT_007HF 14:MOT_015HF 15:MOT_022HF 16:MOT_037HF 17:MOT_055HF 18:MOT_075HF 19:MOT_110HF 20:MOT_150HF 21:MOT_185HF 22:MOT_220HF 23:MOT_300HF	24:MOT_370HF 25:MOT_450HF 26:MOT_550HF 27:MOT_750HF 28:MOT_900HF 29:MOT_1100HF 30:MOT_1320HF 31:MOT_1600HF 32:MOT_2200HF 33:MOT_2800HF 34:MOT_3500HF 35:MOT_3800HF	-
H04	Motor poles setting	X	2~48[P]			4
H05	Motor rated current	X	Range is 0.1~800.0 [A]			-
H06	Motor no-load current (Io)	X	Range is 0.1~400.0 [A]			-
H07	Motor rated slip	X	Range is 0.01~20.0 [Hz]			-
H08	Motor Resistance R1	X	Range is 0.1~3000 [mΩ]			-
H09	Transient Inductance	X	Range is 0.001~30.00 [mH]			-
H10	Motor ResistanceR1	X	Range is 0.1~3000 [mΩ]			-
H11	Transient Inductance auto tuning data	X	Range is 0.001~30.00 [mH]			-
H12	State of Auto-tuning	O	0 - AT_READY 1 - AT_RSTUNE 2 - AT_LSIGMATUNE 3 - AT_TRTUNE 4 - AT_LSTUNE 5 - AT_ENDING 6 - AT_ENDAT			0

Func-code	Name	Range	Default	Runtime edit	Page
Permanent magnet synchronous motor control					
H13	Control switching start level	0 ~ 50 [%] ※ Base frequency reference	10	O	6-91
H14	Control switching completion level	0 ~ 200 [%] ※ Base Control switching start level	100	O	
H15	d-axis current controller P gain	0 ~ 10000	50	O	
H16	d-axis current controller I gain	0 ~ 10000	5	O	
H17	q-axis Stabilization Controller gain	0 ~ 1000	10	O	
H18	d-axis Stabilization Controller gain	0 ~ 1000	0	O	
H19	High Efficiency Controller P Gain	0 ~ 10000	400	O	
H20	High Efficiency Controller I Gain	0 ~ 10000	400	O	
Output frequency holding function					
H21	Holding frequency	0.00 ~ Maximum frequency (A04) [Hz]	60.00Hz	X	6-92
H22	Holding time	0.0 ~600.0 [sec]	0.0sec	O	
Vector Control (Encoder Option)					
H23	Vector control speed controller P gain	0 ~ 1000	100	O	6-92
H24	Vector control speed controller I gain	0 ~ 1000	100	O	6-93
H25	Forward torque limit	0.0 ~ 200.0 [%]	150.0 %	O	
H26	Forward regeneration torque limit	0.0 ~ 200.0 [%]	150.0 %	O	
H27	Reverse torque limit	0.0 ~ 200.0 [%]	150.0 %	O	
H28	Reverse regeneration torque limit	0.0 ~ 200.0 [%]	150.0 %	O	
H29	Zero speed torque limit	0.0 ~ 200.0 [%]	150.0 %	O	

Func-code	Name	Range	Default	Runtime edit	Page
H30	Zero speed regeneration torque limit	0.0 ~ 200.0 [%]	150.0 %	O	6-93
H31	Torque limit setting method	0 - Keypad potentiometer 1 - Control terminal input (O) 2 - Control terminal input (OI) 3 - Standard operator 4 - Remote operator (1st communication -RJ45) 5 – Fieldbus Option 6 – Up/Down function	3	O	6-94
H32	Speed controller output low pass filter time constant	0 ~ 100 [msec]	0 msec	O	
H38	Speed/Torque mode select	0 – Speed control 1 – Torque control (without speed control)	0	O	6-95
H43	Speed limit bias in torque mode	0.00 ~ 20.00 [Hz]	1.50 Hz	O	
H44	Encoder PPR	0 ~ 9999	1024	O	
H45	Encoder direction setting	0 – Counterclockwise 1 – Clockwise	0	O	6-96
H46	Encoder low pass filter time constant	0 ~ 10000 [msec]	0 msec	O	
H47	Encoder frequency deviation error frequency	0.00 ~ 10.00 [Hz]	3.00 Hz	X	
H48	Encoder frequency deviation error detection time	0.0 ~ 10.0 [Sec]	0.0 Sec	X	
H49	Overspeed error detection level	100.0 ~ 120.0 [%]	110.0 %	X	
H50	Overspeed error detection time	0.0 ~ 3.0 [Sec]	0.0 Sec	X	
H51	Torque rise time in torque mode	0.0 ~ 3000.0 [Sec]	0.0 Sec	O	
H52	Torque fall time in torque mode	0.0 ~ 3000.0 [Sec]	0.0 Sec	O	6-97
H53	Encoder pulse error detection method select	0 – Disable detection 1 – Detect all encoder error 2 – A and B all pulse error 3 – A or B pulse error	0	X	
H54	Encoder pulse error detection time	0.0 ~ 60.0 [sec]	3.0 sec	O	

5.8 Extended function o mode (o group)

* Option card is an additional purchase option. For more information, see the additional documentation of the relevant option.

Table 5-9 Extended function o mode (o group)

Func-code	Name	Runtime edit	Range	Default
O01	Fieldbus Option Type	X	0 - Modbus 1 - ProfibusDP 2 - DeviceNet 3 - Ethernet Series 4 - CC-LINK	0
O02	Fieldbus Station Number	X	Modbus:1~32 Profibus DP:1~125 DeviceNet:1~63 Ethernet Series:1~63 CC-LINK:1~63	1
O03	Fieldbus Byte Swap	X	0 - Normal 1 - Swap	0
O04	Fieldbus Communication Speed.	X	1 ~ 5	3
O05	Set number of fieldbus Input data	O	1 ~ 12	12
O06	Set number of fieldbus Output data	O	1 ~ 12	12
O08	Fieldbus Input Address 1	X	0x0000~0xFFFF	0x0603
O09	Fieldbus Input Address 2	X	0x0000~0xFFFF	0x0001
O10	Fieldbus Input Address 3	X	0x0000~0xFFFF	0x0202
O11	Fieldbus Input Address 4	X	0x0000~0xFFFF	0x0203
O12	Fieldbus Input Address 5	X	0x0000~0xFFFF	0x0201
O13	Fieldbus Input Address 6	X	0x0000~0xFFFF	0x0101
O14	Fieldbus Input Address 7	X	0x0000~0xFFFF	0x0102
O15	Fieldbus Input Address 8	X	0x0000~0xFFFF	0x010C
O16	Fieldbus Input Address 9	X	0x0000~0xFFFF	0x010D
O17	Fieldbus Input Address 10	X	0x0000~0xFFFF	0x0111
O18	Fieldbus Input Address 11	X	0x0000~0xFFFF	0x0115
O19	Fieldbus Input Address 12	X	0x0000~0xFFFF	0x0000
O20	Fieldbus Output Address 1	X	0x0000~0xFFFF	0x0202
O21	Fieldbus Output Address 2	X	0x0000~0xFFFF	0x0203
O22	Fieldbus Output Address 3	X	0x0000~0xFFFF	0x0004
O23	Fieldbus Output Address 4	X	0x0000~0xFFFF	0x0002
O24	Fieldbus Output Address 5	X	0x0000~0xFFFF	0x0000
O25	Fieldbus Output Address 6	X	0x0000~0xFFFF	0x0000
O26	Fieldbus Output Address 7	X	0x0000~0xFFFF	0x0000
O27	Fieldbus Output Address 8	X	0x0000~0xFFFF	0x0000
O28	Fieldbus Output Address 9	X	0x0000~0xFFFF	0x0000
O29	Fieldbus Output Address 10	X	0x0000~0xFFFF	0x0000
O30	Fieldbus Output Address 11	X	0x0000~0xFFFF	0x0000
O31	Fieldbus Output Address 12	X	0x0000~0xFFFF	0x0000

Func-code	Name	Runtime edit	Range	Default
O32	Fieldbus Status	X	0x0000~0xFFFF	0x0000
O33	Fieldbus Version	X	0x0000~0xFFFF	0x0000
O34	Fieldbus communication speed setting	X	1 - 156 [kbps] 2 - 625 [kbps] 3 - 2.5 [Mbps] 4 - 5 [Mbps] 5 - 10 [Mbps]	0
O36	TCP IP Addr 1	X	0 ~ 255	192
O37	TCP IP Addr 2	X	0 ~ 255	168
O38	TCP IP Addr 3	X	0 ~ 255	10
O39	TCP IP Addr 4	X	0 ~ 255	100
O40	TCP IP Port ID	X	0 ~ 65535	502

5.9 Extended function U mode (U group)

Table 5-10 Extended function U mode (U group)

Func-code	Name	Range	Defaults	Runtime edit	Page
A01	Frequency command (Multi-speed command method)	0 - Keypad potentiometer 1 - Control terminal input 2 - Standard operator 3 - Remote operator (1st communication -RJ45) 4 - Remote operator (2nd communication - terminal) 5 – Option(reserved) 6 - Potentiometer and remote	1	X	6-7
A02	Run command	0 - Standard operator 1 - Control terminal input 2 - Remote operator (RJ45) 3 - Remote operator (Terminal) 4 - Option(reserved)	1	X	
F01	Output frequency setting	0.00~400.00[Hz] Sensorless 0.00~300.00 [Hz]	0.00Hz	O	6-5
F02	Acceleration time 1 setting	0.1 ~ 6000.0 [sec]	(Note1)	O	
F03	Deceleration time 1 setting	0.1 ~ 6000.0 [sec]	(Note1)	O	
A53	Motor input voltage setting	200V Class -80~240V 400V Class -160~500V	SF/LF:220V, HF:380V	X	6-16
H03	Motor capacity	0:MOT_004LF / 12:MOT_004HF / 24:MOT_370HF 1:MOT_007LF / 13:MOT_007HF / 25:MOT_450HF 2:MOT_015LF / 14:MOT_015HF / 26:MOT_550HF 3:MOT_022LF / 15:MOT_022HF / 27:MOT_750HF 4:MOT_037LF / 16:MOT_037HF / 28:MOT_900HF 5:MOT_055LF / 17:MOT_055HF / 29:MOT_1100HF 6:MOT_075LF / 18:MOT_075HF / 30:MOT_1320HF 7:MOT_110LF / 19:MOT_110HF / 31:MOT_1600HF 8:MOT_150LF / 20:MOT_150HF / 32:MOT_2200HF 9:MOT_185LF / 21:MOT_185HF / 33:MOT_2800HF 10:MOT_220LF / 22:MOT_220HF / 34:MOT_3500HF 11:MOT_300LF / 23:MOT_300HF / 35:MOT_3800HF	-	X	6-86
H05	Motor poles setting	2~48[P]	4	X	6-87
A03	Base frequency setting	0.00 ~ Max. frequency(A04) [Hz]	60.00Hz	X	6-7
A04	Maximum frequency setting	Base frequency (A03) ~ 400 [Hz] In case of sensorless vector (A31=2), Base frequency (A03) ~ 300 [Hz]	60.00Hz	X	

(Note1) When the switching frequency is set to less than 2 kHz, the acceleration/deceleration time is delayed by about 500 msec.
The initial value of acceleration/deceleration time depending on the capacity.
Accel time initial value - 22kW or less: 5.0 s, 30kW or more: 30.0 s
Decel time initial value - 22kW or less: 10.0 s, 30kW or more: 30.0 s

6. Basic FUNCTION

6.1 d Group Parameters

- **d01 Output Frequency Monitor**
  - Range: 0.00 ~ 400.00 Hz

  Real time display of output frequency of the VFD

- **d02 Output Current Monitor**
  - Range: 0.0 ~ 9999 Amps

  Real time display of output current of the VFD

- **d03 Output Voltage Monitor**
  - Range: 0 ~ VFD rated voltage

  Real time display of output voltage of the VFD

- **d04 Rotation Direction**
  - F: Forward Run
  - □: Stop
  - r: Reverse Run

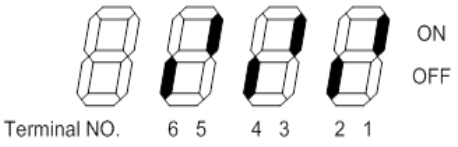
  Real time display of rotation of the VFD

- **d05 PID Feedback**
  - Range: 0.00 ~ 100.0 %

  Scaled PID process variable – feedback value

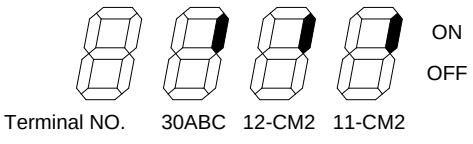
- **d06 Intelligent Input Terminal Status**
  - Show the Intelligent Input Terminal Status

  Meaning: T1 is On, T2 is Off
  T3 is On, T4 is Off
  T5 is On, T6 is Off



- **d07 Intelligent Output Terminal Status**
  - Show the Intelligent Output Terminal Status

  Meaning: 11 – 1 is On
  12 – 3 is On
  30C – 30A is On



- **d08 RPM Output**
  - Range: 0 ~ 65,540 RPM

  Scaled RPM Output determined by equation: (120* d01 * b14) / H04

- **d09 Power Consumption**
  - Range: 0 ~ 999.9 kW

- **d10 VFD Runtime (Day)**
  - Range: 0 ~ 9999 Day

  Accumulated VFD runtime in Days.

- **d11 VFD Runtime (Minutes)**
  - Range: 0 ~ 59 Min

  Accumulated VFD runtime in minutes
  *** Total run time is a combination of d10 and d11.

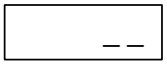
- **d12 DC Bus Voltage**
  - Range: 0 ~ 999 V

  Real time voltage on DC bus.

- **d13 Current Fault**

When fault occurs, the VFD automatically displays this parameter.
Additional information of the fault can be accessed by using up arrow key.

Fault Code
↓ Press the UP key
Output frequency at time of fault
↕ Press the UP.DOWN key
Output current at time of fault
↕ Press the UP.DOWN key
DC bus voltage at time of fault
↕ Press the UP.DOWN key
Output voltage at time of fault
↕ Press the UP.DOWN key
Output torque at time of fault
↕ Press the UP.DOWN key
Reference frequency at time of fault
↕ Press the UP.DOWN key
Run direction at time of fault
↕ Press the UP.DOWN key
Run Status at time of fault
↕ Press the UP.DOWN key
Module Temperature at time of fault
↕ Press the UP.DOWN key
I/O Terminal Status at time of fault
↕ Press the UP.DOWN key
I/O Comm Status at time of fault
↕ Press the UP.DOWN key
Run Time at time of fault
↕ Press the FUNC key
Back to d13 display
↓
• No trip history



• Press the reset key to initialize the trip history.

- **d14 Previous Fault 1**

Displays last fault that occurred. Additional information can be accessed as shown above in d13.

- **d15 Previous Fault 2**

Displays Fault 2 that occurred. Additional information can be accessed as shown above in d13.

- **d16 Previous Fault 3**

Displays Fault 3 that occurred. Additional information can be accessed as shown above in d13.

- **d17 Fault Count**

Displays accumulated fault count.

- **d18 Inverter S/W version**

  Displays software version of inverter.

- **d19 Fan operation time(day)**

  Displays fan accumulation time (day).

- **d20 Fan operation time(minute)**

  Displays fan accumulation time (minute).

- **d21 Inverter internal temperature(°C)**

  Display Inverter internal temperature (°C)

- **d22 Encoder Speed(RPM)**

  - Range: 0 ~ 60000 RPM

  Display of encoder speed

6.2 F Group Parameters

F group holds very basic frequency related parameter values to operate the iMASTER C1 VFD.

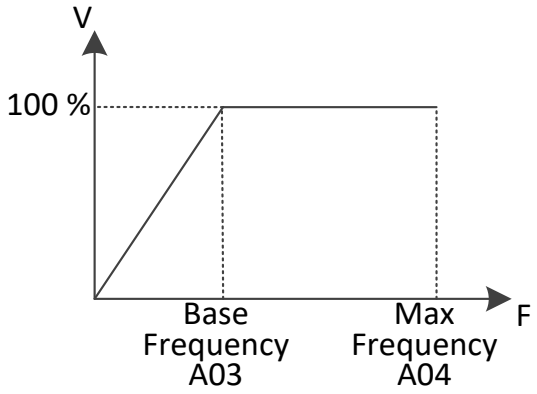
- **F01 Output frequency setting**

  - Range: 0.00 ~ 400.00 Hz in 0.01 Hz
  - Range: 0.00 ~ 300.00 Hz in 0.01 Hz for Sensor-less Vector Control (A31=2)

  This parameter displays the frequency setpoint for the VFD.
  VFD Frequency can be controlled by various sources set in A01.

  - If A01=0: Use the Volume Key on the panel
  - If A01=1: Use the Terminal (O-L, OI-L)
  - If A01=2: Use Up/Down Keys
  - If A01=3: Use Control Terminal Input (RJ45)
  - If A01=4: Use Control Terminal Input,(RXP-RXN)
  - if A01=5: Fieldbus (option)
  - if A01=6: Potentiometer and remote

  ❖ Related Parameters: A01



- **F02 Acceleration time 1 setting**

  - Range: 0.1 ~ 999.9 Sec in 0.1 Sec
    1000 ~ 6000 Sec in 1 Sec

  Acceleration time from 0Hz to Maximum Frequency (A04)
  ❖ Related Parameters: A54, A56, A57,A59

- **F03 Deceleration time 1 setting**

  - Range: 0.1 ~ 999.9 Sec in 0.1 Sec
    1000 ~ 6000 Sec in 1 Sec

  Deceleration time from Maximum Frequency (A04) to 0Hz
  ❖ Related Parameters: A55, A56, A58, A60

- **F04 Rotation direction setting**

  - 0: Forward Run
  - 1: Reverse Run

  Sets the direction of VFD to forward or reverse at keypad operation only
  ❖ Related Parameters: A02

- **F05 Rotation direction selection**

  - 0: Enable both way (FW and RV)
  - 1: Disable forward
  - 2: Disable reverse

  Sets allow or prohibit forward/reverse rotation.

- **F06 Define custom display**

  - Range: 0 ~ 65535 in 1

  Display various parameters.
  - ❖ Related Parameters: b71~b73

6.3 A Group Parameters

A group holds extended frequency control Parameters and VFD operational Parameters.

- **A01 Frequency command (Multi-speed command method)**

  - 0: Keypad potentiometer
  - 1: Control terminal input (O-L: Voltage, OI-L: Current)
  - 2: Standard operator
  - 3: Remote Operator 1 (1st communication -RJ45)
  - 4: Remote Operator 2 (2nd communication - terminal)
  - 5: Fieldbus (option)
  - 6:Potentiometer and remote

  Determined the source of the frequency command.
  - ❖ Related Parameters: F01, A05~A10, A61~A64, b17, b28~b29, b31

- **A02 Run command**

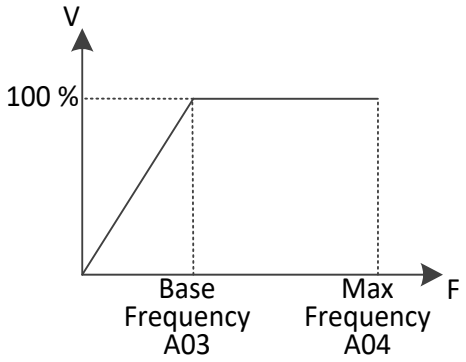
  - 0: Run/Stop Key on keypads
  - 1: Control Terminal Input ((FW, RV Connect)
  - 2: Remote Operator 1 (RJ45 Port, RS485 Communication),
  - 3: Remote Operator 2 (RXP-RXN, RS485 Communication)
  - 4: Fieldbus (option)

  Determined the source of the run command.
  - ❖ Related Parameters: F04, d06, C1~C12, b17, b28~b29, b31

- **A03 Base frequency setting**

  - Range: 0.00 ~ Maximum Frequency(A04) in 0.01 Hz

  Frequency at which the maximum voltage is reached.
  Should be set to the motor rated frequency.
  - ❖ Related Parameters: None



- **A04 Maximum Frequency setting**

  - Range: A03 ~ 400.00 Hz in 0.01 Hz
  - If Sensorless Vector Control (A31=2): Base Frequency (A03) ~ 300 Hz in 0.01 Hz

  Maximum frequency the VFD will output.
  - ❖ Related Parameters: F02, F03

- **A05 External frequency setting start (O, OI)**

  - Range: 0.00 ~ Maximum Frequency(A04) in 0.01 Hz

  When Frequency Command Source is set to the terminal input (A01=1), this parameter determines the Frequency Setpoint (F01) at minimum analog input current, 4mA (or voltage, 0 V)

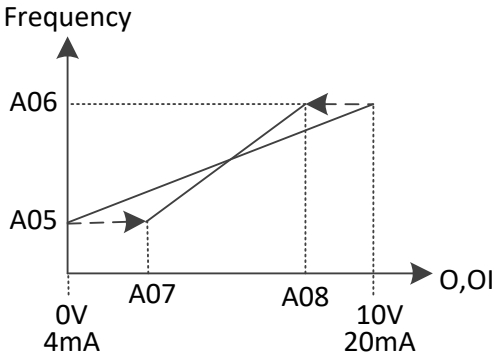
  - ❖ Related Parameters: A01, A07

- **A06 External frequency setting end (O, OI)**

  - Range: 0.00 ~ Maximum Frequency(A04) in 0.01 Hz

  When Frequency Command Source is set to the terminal input (A01=1), this parameter determines the Frequency Setpoint (F01) at maximum analog input current, 20mA (or voltage, 10 V)

  - ❖ Related Parameters: A01, A08



- **A07 External frequency start rate setting(O, OI)**

  - Range: 0.0 ~ 100.0 % in 0.1 %

  Offsets the minimum analog input reference corresponding to A05.
  Example: if set to 10%, minimum analog current value becomes 5.6mA (or 1 V).

  - ❖ Related Parameters: A01, A05, A09

- **A08 External frequency end rate setting(O, OI)**

  - Range: 0.00 ~ 100.0 % in 0.1 %

  Offsets the maximum analog input reference corresponding to A06.
  Example: if set to 90%, maximum analog current value becomes 18.4mA (or 9V)
  For any reference above A08, VFD holds the value in A06.

  - ❖ Related Parameters: A01, A06

- **A09 External frequency start pattern setting**

  - 0: Start at start frequency (A05)
  - 1: Start at 0 Hz

  Determines the Frequency Setpoint (F01) for any analog reference below A05.

  - ❖ Related Parameters: F01, A05, A07

- **A10 External frequency sampling setting**

  - Range: 0.1~500.0

  Filter on analog input to help reduce noise on signal.
  - ❖ Related Parameters: None

- **A61 Input voltage offset setting**

  - Range: -10.0 ~ 10.0 % in 0.1%

  Real time editable offset factor for analog input voltage.
  - ❖ Related Parameters: A05~A08

- **A62 Input voltage gain setting**

  - Range: 0.0 ~ 200.0 % in 0.1%

  Real time editable gain factor for analog input voltage
  - ❖ Related Parameters: A05~A08

- **A63 Input current offset setting**

  - Range: -10.0 ~ 10.0 % in 0.1%

  Real time editable offset factor for analog input current.
  - ❖ Related Parameters: A05~A08

- **A64 Input current gain setting**

  - Range: 0.0 ~ 200.0 % in 0.1%

  Real time editable gain factor for analog input current
  - ❖ Related Parameters: A05~A08

- **A11~A25 Multi-speed frequency setting**

  - Range: 0.01 ~ Max Frequency (A04)

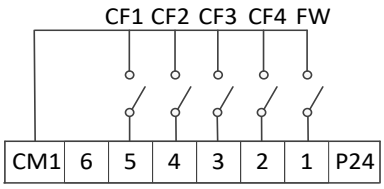
  Programming 15 different frequency values to Parameters, A11~A25: and select by a combination of 4 terminal inputs, CF4~CF1, will further discuss in C group.

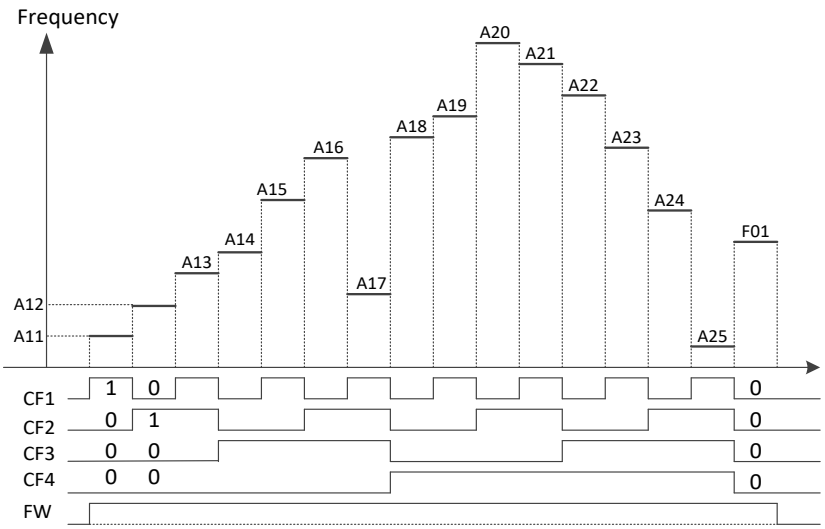
  For HVAC system, often multiple heating temperature setting is desired.
  For instance, @ 7 am, set to 65 ^{0}F,
  @ 12 pm, set to 68 ^{0}F
  @ 3 pm, set to 70 ^{0}F
  @ 6 pm, set to 72 ^{0}F
  @ 9 pm, set to 75 ^{0}F, etc.

  - ❖ Related Parameters: F01, C01~C12

Programming Example:

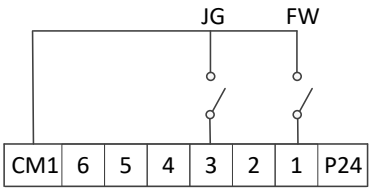
- A02 = 1; run by keypad (or A02=2; by Terminal)
- F01 = Frequency Number @ CF4:CF1 = 0000
- C01 ~ C05 (Assign to FW, Multi Frequency Pointers)
- C07 ~ C12 (Assign Close/Open Polarity)
- A11 ~ A25 (Frequency Values)





- **A26 Jog frequency setting**
  - Range: 0.50 ~ 10.00 Hz in 0.01 Hz

Jogging frequency is used to move/rotate the motor in small increment at low frequency. It is selected using input terminal.



  - ❖ Related Parameters: C01~ C12

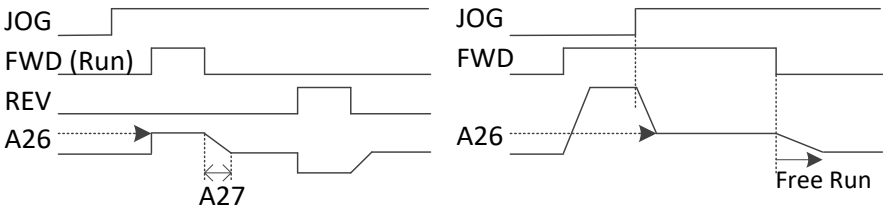
- **A27 Jog stop operation selection**
  - 0: Free Run to Stop (Coast to Stop)
  - 1: Deceleration to Stop
  - 2: DC Injection Braking to Stop

Jogging frequency is used to move/rotate the motor in small increment at low frequency. It is selected using input terminal.

  - ❖ Related Parameters: C01~C12

Programming Example:

- A02 = 1; run by keypad (or A02=2; by Terminal)
- F01 = Frequency Number @ CF4:CF1 = 0000
- C01 ~ C05 (Assign to FW, JOG)
- C07 ~ C12 (Assign Close/Open Polarity)
- A11 ~ A25 (Frequency Values)



- **A28 Torque boost mode selection**

  - 0: Manual Torque Boost (A29, A30)
  - 1: Automatic Torque Boost (H02)

  Select a torque boost mode. For V/F Control, compensate a beginning torque by increasing the output voltage.
  If selected Automatic Torque Boost mode, recommended the following
  1. Run “Auto Tuning”
  2. Use an auto tuning data(H02=1)
     - ❖ Related Parameters: H1~H11

- **A29 Manual torque boost setting(forward)**

  - Range: 0.0 ~ 50.0 % in 0.1 %

  For Manual Torque Boost mode, program the value in % of an output voltage.

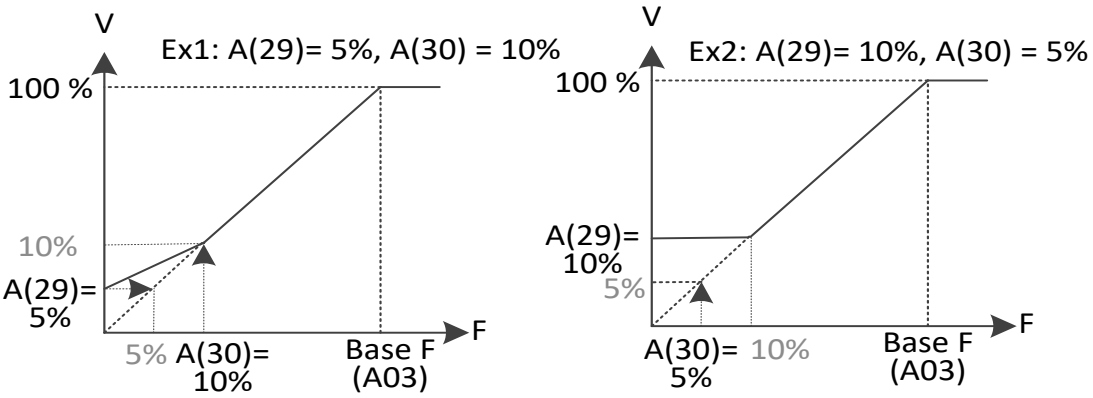
  - Initial Value
    [200V]
    ~ 3.7kW : 2.0[%], 5.5kW : 2.3[%], 7.5kW : 2.1[%], 11kW : 1.9[%], 15kW : 1.7[%]
    [400V]
    ~ 3.7kW : 2.0[%], 5.5kW : 2.3[%], 7.5kW : 2.1[%], 11kW : 1.9[%], 15kW : 1.7[%], 18.5kW : 1.6[%], 22kW~160kW : 1.5[%], 185kW~280kW : 1.4[%], 350kW : 1.3[%]

    - ❖ Related Parameters: A30

- **A30 Manual torque boost Frequency setting (forward)**

  - Range: 0.0 ~ 100.0 % in 0.1 %

  Program the frequency breakpoint
  - ❖ Related Parameters: A29



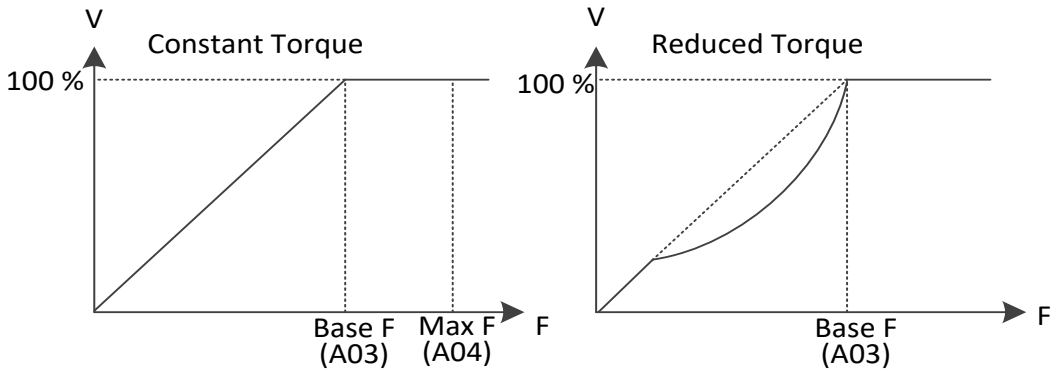
- **A31 V/F characteristic curve selection**

  - 0: Constant Torque
  - 1: Reduced Torque (Variable Torque)
  - 2: Sensorless Vector Control
  - 3: VF_USER
  - 4: VF_ Permanent magnet synchronous motor control
  - 5: Vector (Encoder Option)

  Reduced torque is effective for fan or pump application which do not require high torque at low frequency. By reducing the output voltage, increased efficiency, lower noise, and lower vibration.

  For Sensorless Vector method, per specified output voltage, current, motor parameters, motor rpm, the corresponding torque value is calculated. At very low frequency up to 0.5 Hz, high torque operation is possible

  - Related Parameters: A29~A30, H01~H11
  -



For VF_USER method, V / F ratio required for special motors can be set arbitrarily.

- Related Parameters: A86 ~ A93

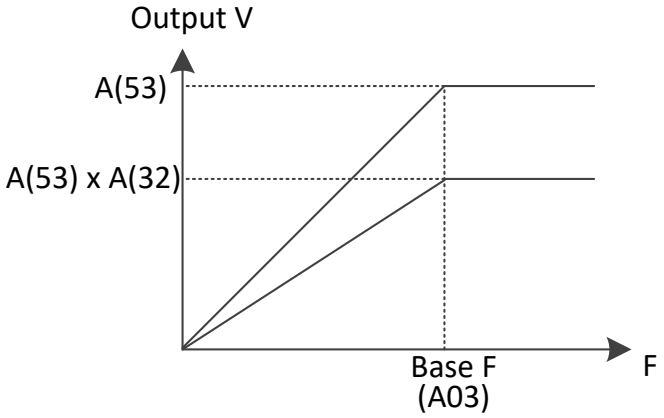
For VF_ Permanent magnet synchronous motor control method, the inverter drives a permanent magnet synchronous motor (PMSM). Refer to Section 5.3 "Notes in Driving PMSM" for details.

For Vector control method, you can control the motor speed and instantaneous torque by using the encoder option. The encoder option is mandatory,

- **A32 V/F gain setting**

  - Range: 20.0 ~ 110.0 % in 0.1 %

  The output voltage cannot exceed the input voltage
  - ❖ Related Parameters: A53, A03



- **A33 DC injection braking function selection**

  - 0: Disabled
  - 1: Enabled

  Enable or Disable DC Injection Braking Function
  By adding the force to the rotor, slowing the motor to stop.
  - ❖ Related Parameters: A33~A37

- **A34 DC injection braking frequency settin**

  - Range: 0.50 ~ 10.00 Hz in 0.01 Hz

  Program the VFD frequency out when DC injection braking function kicks in. If set A34 to 0.5Hz, when VFD frequency out reaches to 0.5 Hz, DC braking function is activated.
  - ❖ Related Parameters: A33~A37

- **A35 DC injection braking output delay time setting**

  - Range: 0.0 ~ 5.0 Sec in 0.1 Sec

  Program the delay time when the DC braking function actually starts form when VFD out is the frequency value in A34.
  - ❖ Related Parameters: A33~A37

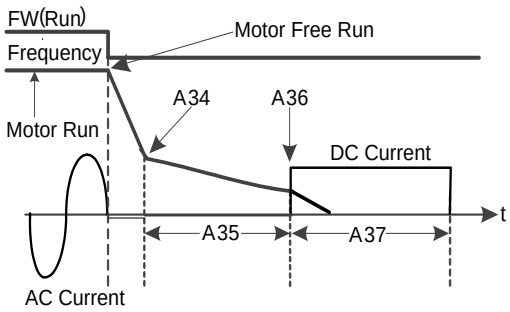
- **A36 DC injection braking force setting**

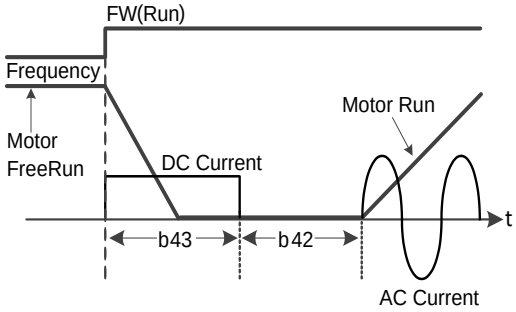
  - Range: 0.0 ~ 100.0 % in 0.1 %

- **A37 DC injection braking time setting**

  - Range: 0.0 ~ 10.0 Sec in 0.1 Sec

  Program the DC injection braking duration
  - ❖ Related Parameters: A33~A37





- **A38 Frequency upper limit**

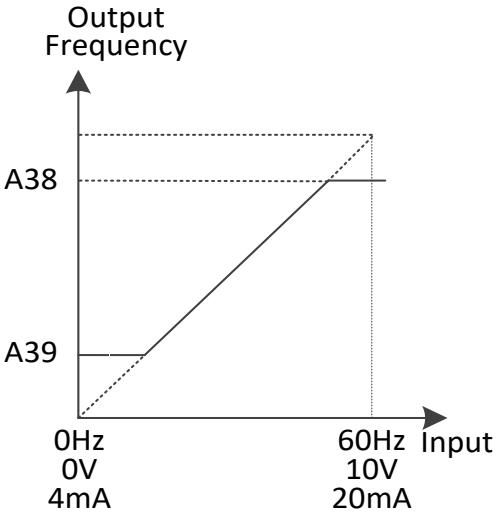
  If 0 disable Frequency Limit Function
  - Range: Frequency Lower Limit(A39) ~ Max Frequency(A04) in 0.01 Hz

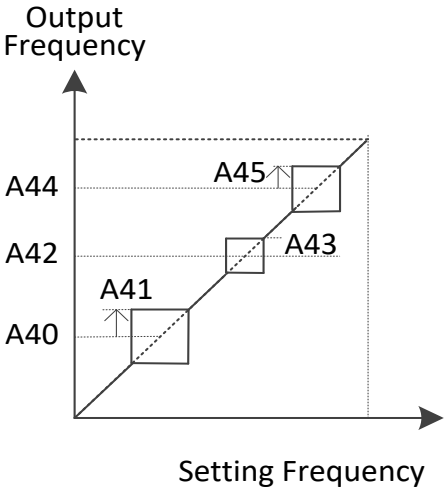
  Program upper limit of an output frequency
  - ❖ Related Parameters:

- **A39 Frequency lower limit**

  - Range: 0.00 ~ A38 Hz in 0.01 Hz

  Program lower limit
  - ❖ Related Parameters:





- **A40, 42, 44 Jump(center) frequency setting**

  - Range: 0.00 ~ Max Frequency(A04) Hz in 0.01 Hz

  Program 3 output frequency values to mitigate different resonance points at which vibration can cause damages to the equipment such as fans or pumps.

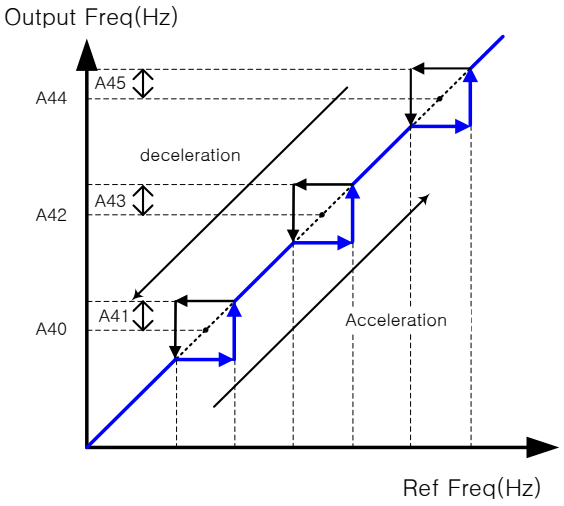
  - ❖ Related Parameters: A41, A43, A45

- **A41, 43, 45 Jump(hysteresis) frequency setting**

  - Range: 0.00 ~ 10.00 Hz in 0.01 Hz

  Program skip frequency ranges for A40, A42, and A44 respectively.

  - ❖ Related Parameters:



- **A46 Manual torque boost(Reverse)**

  - Range: 0.0 ~ 50.0 % in 0.1 %

  For Manual Torque Boost mode, program the value in % of an output voltage.

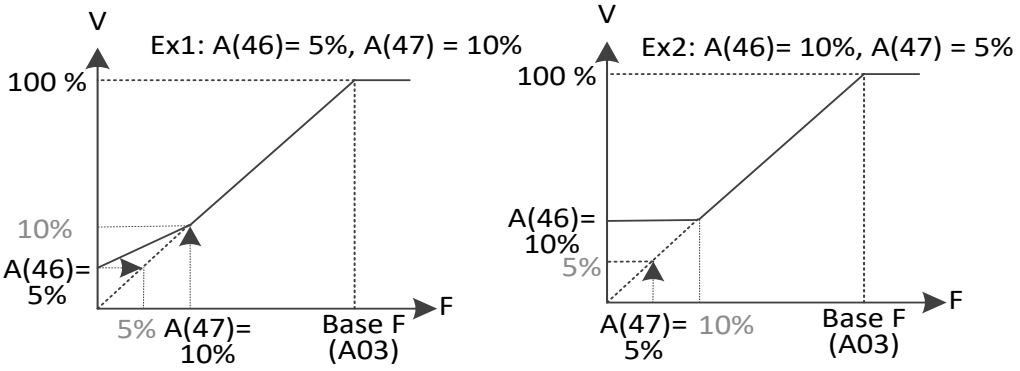
  - Initial Value
    [200V]
    ~ 3.7kW : 2.0[%], 5.5kW : 2.3[%], 7.5kW : 2.1[%], 11kW : 1.9[%], 15kW : 1.7[%]
    [400V]
    ~ 3.7kW : 2.0[%], 5.5kW : 2.3[%], 7.5kW : 2.1[%], 11kW : 1.9[%], 15kW : 1.7[%], 18.5kW : 1.6[%], 22kW~160kW : 1.5[%], 185kW~280kW : 1.4[%], 350kW : 1.3[%]

  - ❖ Related Parameters: A47

- **A47 Manual torque Frequency setting (Reverse)**

  - Range: 0.0 ~ 100.0 % in 0.1 %

  Program the frequency breakpoint
  - ❖ Related Parameters: A46



- **A48 Auto Torque Boost Gain**

  - Range: 0.00 ~ 2.50 [x1], in [x1.00]

- **A49 Auto torque boost filter tow**

  - Range: 0.1 ~ 999.9 [ms], in 80.0 ms

- **A52 AVR function selection**

  - 0: Constant ON
  - 1: Constant OFF
  - 2: OFF During Deceleration (On otherwise)

  AVR enables the constant output regardless input power fluctuation.
  - ❖ Related Parameters:

- **A53 Motor input voltage setting**

  - 200V – 80[V]~240[V]
  - 400V – 160[V]~500[V]

  - Initial value

Country[b13]	SF/LF	HF
Domestic	220[V]	380[V]
Europe	230[V]	400[V]
USA	230[V]	460[V]

  The value of A53 code does not change when it is initialized.
  Select input voltage for respective iMASTER C1 VFD Models
  - ❖ Related Parameters:

- **A54 Second acceleration time setting**

  - Range: 0 .1 ~ 999.9 Sec in 0.1 Sec
  - Range: 1000.0 ~ 6000.0 Sec in 1.0 Sec

  In addition to Acceleration Time 1 in F02, Second acceleration time can be specified. Its value can also be entered by input terminal 2CH
  - ❖ Related Parameters:

- **A55 Second deceleration time setting**

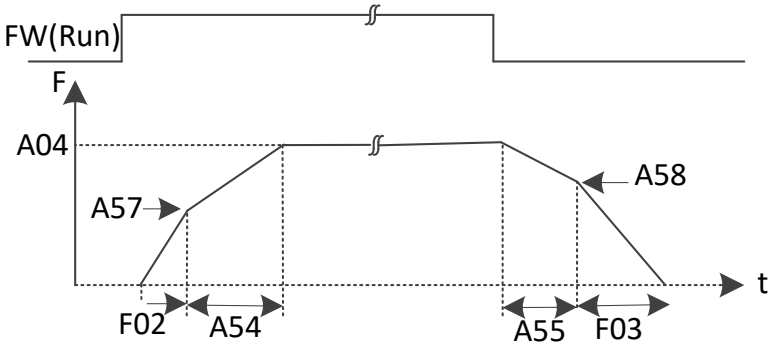
  - Range: 0 .1 ~ 999.9 Sec in 0.1 Sec
  - Range: 1000.0 ~ 6000.0 Sec in 1.0 Sec

  In addition to deceleration Time 1 in F03, Second acceleration time can be specified. Its value can also be entered by input terminal 2CH
  - ❖ Related Parameters:

- **A56 Two stageacce1/dece1 switching method selection**

  - 0: 2CH input from terminal
  - 1: Parameters (A54,A55, A57,A58)

  Select the transition frequency point about acceleration/deceleration by input terminal or frequency
  - ❖ Related Parameters: C01~C12, A57~A60



- **A57 Acc1 to Acc2frequency transition point**

  - Range: 0 .00 ~ Max Frequency(A04) in 0.01Hz

  In addition to Acceleration Time 1 in F02, Acceleration Time 2 can be specified. Its value can also be entered by input terminal 2CH
  - ❖ Related Parameters:

- **A58 Decel 1 to Decel 2 frequency transition point**

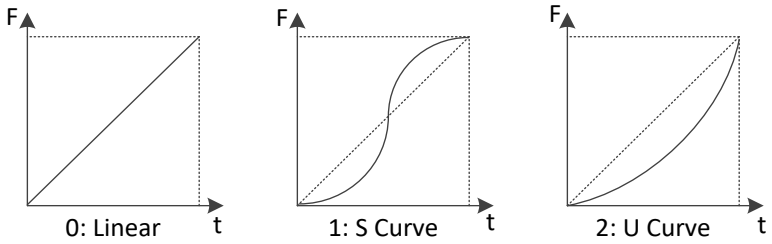
  - Range: 0 .00 ~ Max Frequency(A04) in 0.01Hz

  In addition to Deceleration Time 1 in F03, Deceleration Time 2 can be specified. Its value can also be entered by input terminal 2CH
  - ❖ Related Parameters:

- **A59 Acceleration curve select**

  - 0: Linear
  - 1: S Curve
  - 2: U Curve

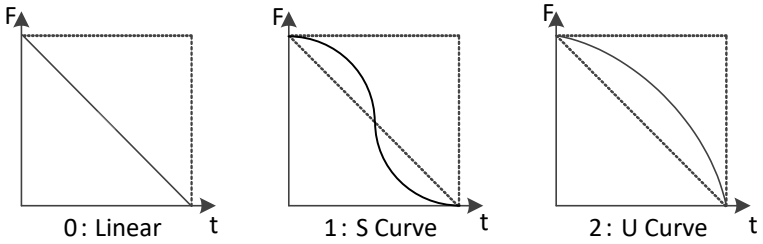
  Select Acceleration Curve Type
  - ❖ Related Parameters:



- **A60 Deceleration curve setting**

  - 0: Linear
  - 1: S Curve
  - 2: U Curve

  Select Deceleration Curve Type
  - ❖ Related Parameters:



- **A65 FAN operation mode**

  - 0: Always On
  - 1: ON in the run time
  - 2: On in Case Inverter internal temperature(d21) is More than 70°C

  Select fan operation
  - ❖ Related Parameters: d21

- **A66 S curve start ratio setting of acceleration**

  - Range: 0.0 ~ 100.0 % in 0.1%

  When S-curve is selected for A59 and A60, the acceleration pattern can be made into a curve.
  - ❖ Related Parameters: A59,A60,A66~A69

- **A67 S curve stop ratio setting of acceleration**

  - Range: 0.0 ~ 100.0 % in 0.1%

  When S-curve is selected for A59 and A60, the acceleration pattern can be made into a curve.
  - ❖ Related Parameters: A59,A60,A66~A69

- **A68 S curve start ratio setting of deceleration**

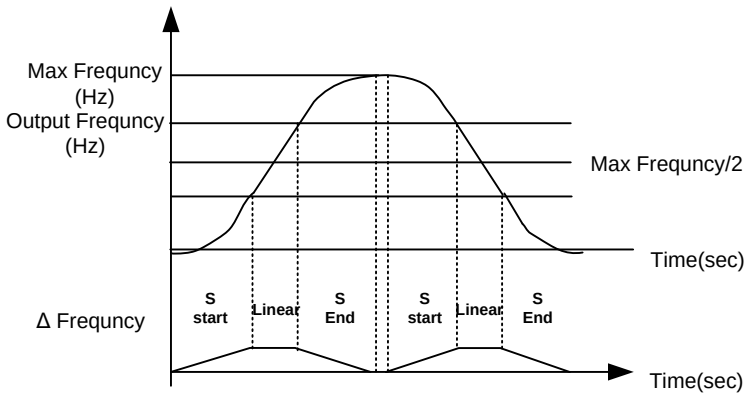
  - Range: 0.0 ~ 100.0 % in 0.1%

  When S-curve is selected for A59 and A60, the deceleration pattern can be made into a curve.
  - ❖ Related Parameters: A59,A60,A66~A69

- **A69 S curve stop ratio setting of deceleration**

  - Range: 0.0 ~ 100.0 % in 0.1%

  When S-curve is selected for A59 and A60, the deceleration pattern can be made into a curve.
  - ❖ Related Parameters: A59,A60,A66~A69



◆ **A70 ~ A85 Proportional, Integral, Differential (PID) Function**

The PID function enables the system running at the set point automatically by regulating the process using the system feedback, error term. It is used for Cubic Feet of Air it moves per minute (CFM) for fan application, Gallons per minute (GPM) for pump application, pressure control, heating application, etc.

- **A70 PID function select**

  - 0: PID Control Disabled
  - 1: PID Control Enabled
  - 2: Forward Feed Enabled
  - 3: PID control enable at Stop
  - 4: PID,F/F control enable at Stop

  Select PID function type
  - ❖ Related Parameters: A70~A85

- **A71 PID Reference**

  - Range: 0.00 ~ 100.00 % in 0.01 %

  PID target value setpoint
  - ❖ Related Parameters: A70~A85

- **A72 PID Reference source**

  - 0: Keypad Potentiometer
  - 1: Control terminal input
  - 2: Standard operator
  - 3: Remote Control (RJ45)
  - 4: Remote operator (Terminal)
  - 5: Option
  - 6: Potentiometer and RJ45

  Select PID Setpoint Source
  - ❖ Related Parameters: A70~A85

- **A73 PID Feed-back source**

  - 0: “OI” Current Input (DC 4~20mA)
  - 1: “O” Voltage Input (DC 0~10V)

  Select the source how to enter the PID set point in A72.
  - ❖ Related Parameters: A70~A85

- **A74 PID P Gain**

  - Range: 0.1 ~ 1000.0 % in 0.1 %

  Select the PID P gain value
  - ➢ It sets the output rate of error between set point value and the feedback value
  - ➢ For faster response speed, enlarge the P gain value
  - ➢ If P gain is set too large, oscillation or over shooting may occur
  - ❖ Related Parameters: A70~A85

[Input method of target value signal and feedback signal]
Set the reference signal according to the PID reference setting method (A72).
Set the feedback signal according to the PID feedback source (A73)
If A73=0, input terminal being set [AT] has to be ON.

- **A75 PID I Gain Time**

  - Range: 0.0 ~ 3600.0 Sec in 0.1 Sec

  Select the integral time to accumulate PID error value
  - ➢ For faster response speed, shorten the accumulate time
  - ➢ If I Gain time is set too short, oscillation or over shooting may occur

  - ❖ Related Parameters:

- **A76 PID D Gain Time**

  - Range: 0.0 ~ 10.00 Sec in 0.01 Sec

  Program the derivative time for PID function
  - ➢ For faster response speed, lengthen the D gain time
  - ➢ If D gain time is set too long, system may become unstable

  - ❖ Related Parameters:

- **A77 PID Error limit**

  - Range: 0.0 ~ 100.0 % in 0.1 %

  Program error limit level, ratio to the maximum error

  - ❖ Related Parameters:

- **A78 PID Output high limit**

  - Range: A79 ~ 100.0 % in 0.1 %

  Program the maximum PID output as a percentage of the maximum output frequency
  - ❖ Related Parameters: A04

- **A79 PID Output low limit**

  - 0.00: Disabled the Low Limit
  - Range: -100.0 ~ A78 % in 0.1 %

  Program the minimum PID output as a percentage of the maximum output frequency
  - ❖ Related Parameters: A04

- **A80 PID Output Invert**

  - 0: PID Output Invert Disabled
  - 1: PID Output Invert Enabled

  Program to enable the PID Output Invert
  - ❖ Related Parameters:

- **A81 PID Scale Factor**

  - Range: 0.1~ 1000.0 % in 0.1 %

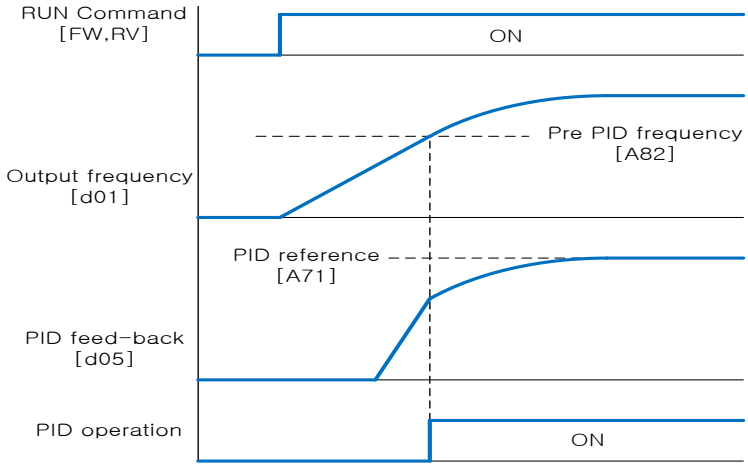
  Program the minimum PID output as a percentage of the maximum output frequency(A04)
  - ❖ Related Parameters: A04

- **A82 Pre PID frequency**

  - 0.00: Disabled Pre PID Function
  - Range: 0.00 ~ Max Frequency(A04) in 0.01 Hz

  Program the frequency setpoint when PID function is activated. Once the VFD frequency out reaches this value in A82, PID control function is enabled and the VFD is operated in closed loop control.

  ❖ Related Parameters: A04



Pre-PID

- **A83 Sleep frequency**

  - Range: 0.00 ~ Max Frequency(A04) in 0.01 Hz

  Program the frequency setpoint when the VFD goes to Sleep.

  ❖ Related Parameters:

- **A84 Sleep/wake up delay time**

  - Range: 0.0 ~ 30.0 Sec in 0.1 Sec

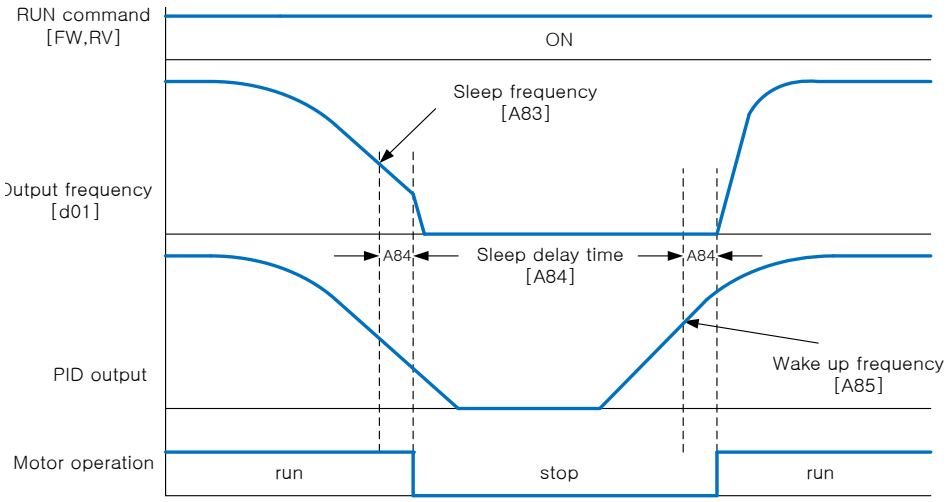
  Program the delay time when the VFD actually goes to Sleep/Wake from reaching the sleep frequency or wake frequency.

  ❖ Related Parameters: A04

- **A85 Wake up frequency**
  - Range: Sleep Frequency (A83) ~ Max Frequency (A04) in 0.01 Hz

Program the frequency setpoint when the VFD wakes up from the Sleep mode for the specified operation.

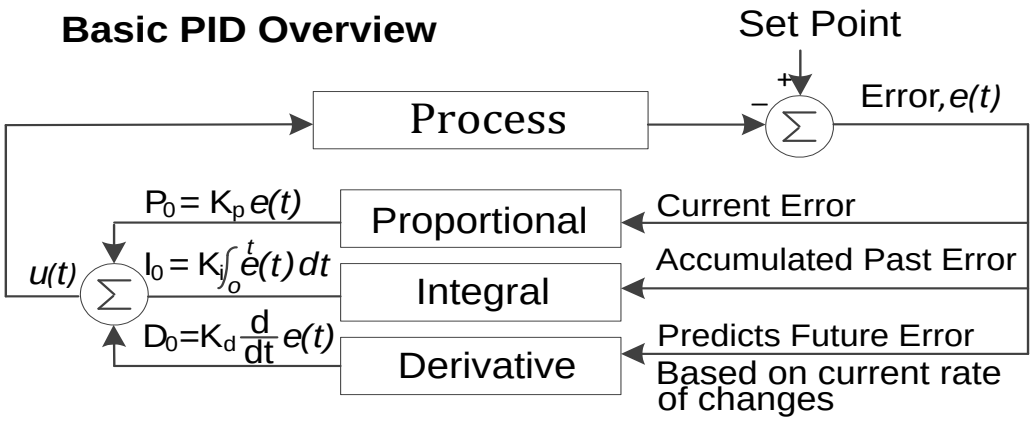
- ❖ Related Parameters:



Sleep and Wake Function

PID Functional Description

- Set Point: Desired System Output Value
- Error: Difference between System output and Set Point
- Proportional (P) Term: Current Error
- Integral (I) Term: Accumulated Past Error
- Derivative (D) Term: Predicted Future Error based on current rate of changes



$$u(t) = K_p e(t) + K_i \int_o^t e(t)\,dt + K_d \frac{d}{dt} e(t)$$

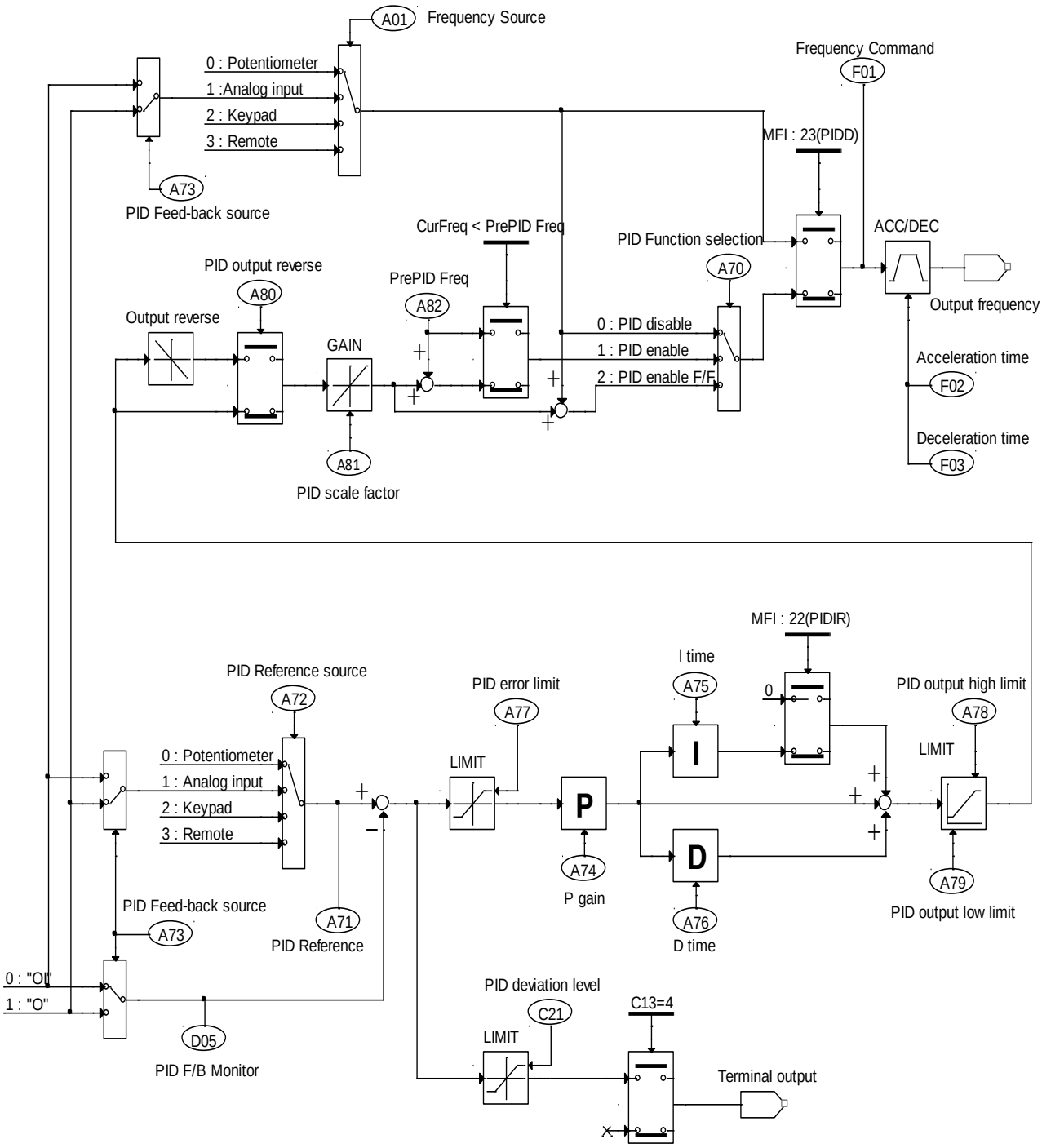
PID Gain Adjustment Example

If the response is not stabilized in a PID control operation, adjust the gains as follows according to the symptom

- The change of controlled variable is slow even when the target value is changed.
  ⇨ Increase P gain [A74]
- The change of controlled variable is fast, but not stable.
  ⇨ Decrease P gain[A74]
- It is difficult to make the target value match with the controlled variable.
  ⇨ Decrease I time [A75]
- Both the target value and the controlled variable are not stable.
  ⇨ Increase I time[A75]
- The response is slow even when the P gain is increased.
  ⇨ Increase D time[A76]
- The response is not stabilized due to oscillation even when the P gain is increased.
  ⇨ Decrease D time[A76]

PID Control Diagram

- The overall PID control diagram with respective parameters is shown.



- **A86 User V/F setting frequency 1**
  - Range: 0.0 ~ A88 Hz in 0.01 Hz

  When selecting VF_USER in A31, the user can set the V/F ratio required by special motor.
  - ❖ Related Parameters: A31, A86~A93
- **A87 User V/F setting voltage 1**
  - Range: 0.0 ~ A89 % in 0.1 %

  When selecting VF_USER in A31, the user can set the V/F ratio required by special motor.
  - ❖ Related Parameters: A31, A86~A93
- **A88 User V/F setting frequency 2**
  - Range: A86 ~ A90 Hz in 0.01 Hz

  When selecting VF_USER in A31, the user can set the V/F ratio required by special motor.
  - ❖ Related Parameters: A31, A86~A93
- **A89 User V/F setting voltage 2**
  - Range: A87 ~ A91 % in 0.1 %

  When selecting VF_USER in A31, the user can set the V/F ratio required by special motor.
  - ❖ Related Parameters: A31, A86~A93
- **A90 User V/F setting frequency 3**
  - Range: A88 ~ A92 Hz in 0.01 Hz

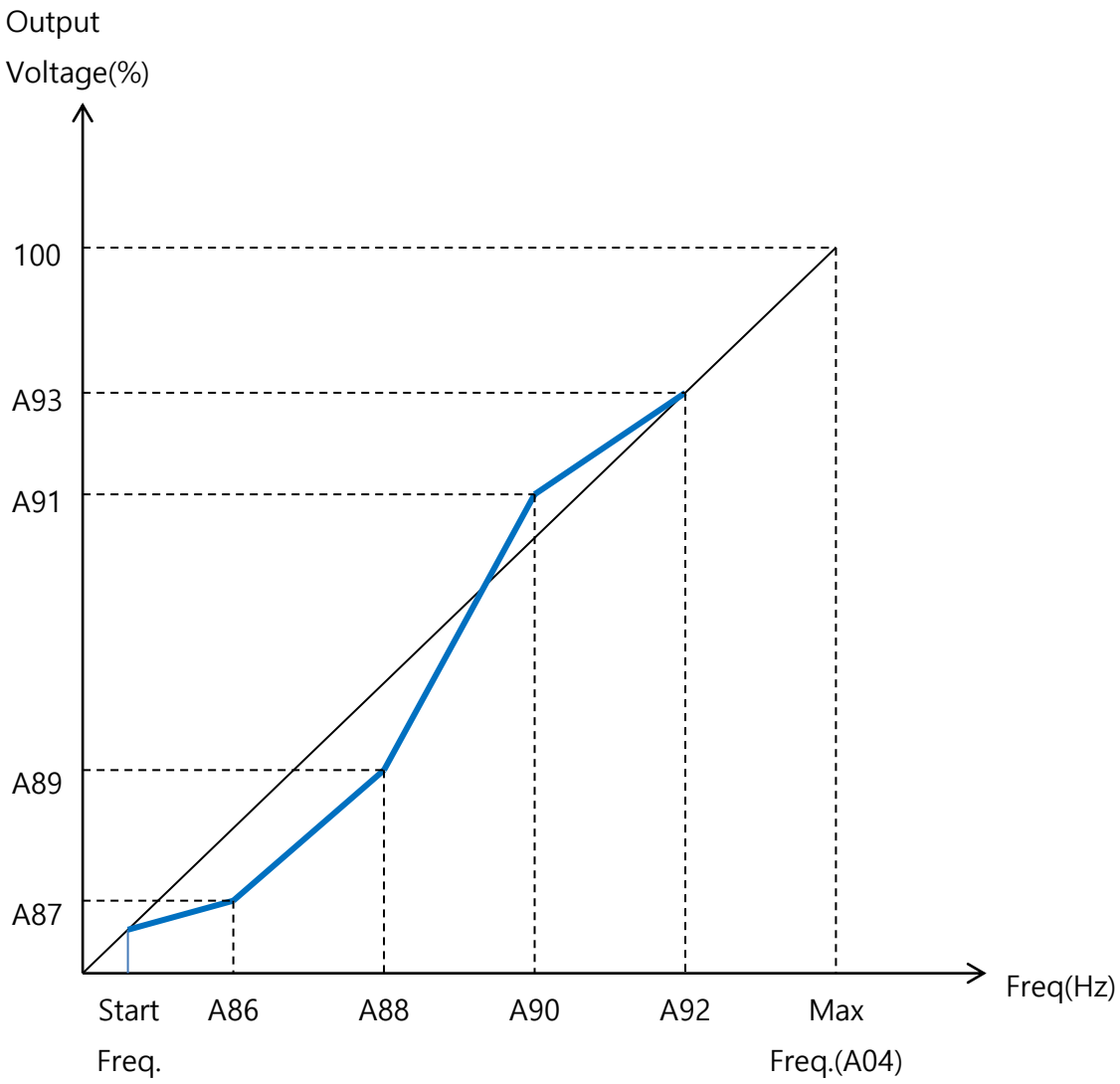
  When selecting VF_USER in A31, the user can set the V/F ratio required by special motor.
  - ❖ Related Parameters: A31, A86~A93
- **A91 User V/F setting voltage 3**
  - Range: A89 ~ A93 % in 0.1 %

  When selecting VF_USER in A31, the user can set the V/F ratio required by special motor.
  - ❖ Related Parameters: A31, A86~A93
- **A92 User V/F setting frequency 4**
  - Range: A90 ~ A04 Hz in 0.01 Hz

  When selecting VF_USER in A31, the user can set the V/F ratio required by special motor.
  - ❖ Related Parameters: A31, A86~A93
- **A93 User V/F setting voltage 4**
  - Range: A91 ~ 100.0 % in 0.1 %

When selecting VF_USER in A31, the user can set the V/F ratio required by special motor.

- ❖ Related Parameters: A31, A86~A93



- **A94 FAN fault Detection**

  - 0: Ignore in case of FAN fault (Alarm, fault not occurring, Inverter Run)
  - 1: Display E33 FAN fault (Inverter Stop)
  - 2: Display FAnt Alarm (Trip does not occur)

  - ❖ Related Parameters:

- **A95 Deceleration time after DC injection braking**

  - Range: 0.1 ~ 1.0 Sec in 0.1 Sec

  Deceleration time from Maximum Frequency (A04) to 0Hz

  - 0.0: Free Run to Stop (Coast to Stop)
  - 0.1 ~ 1.0: Deceleration to Stop

6.4 b Group Parameters

- **b01 Selection of restart mode**

  - 0: No Restart
  - 1: Restart from 0Hz
  - 2: Restart from the frequency at time of fault
  - 3: Restart from the frequency at time of fault; then slow down to stop

  Select what action to take when a trip occurs for Over current (OC), Overvoltage (OV), and Under voltage (UV). Restart attempts up to 3 times for OC and OV since there is liability issues to consider. However, in case of UV, it attempts 10 times. For trip count, if the consecutive trip does not occur within 60 seconds, an accumulated trip count is reset to 0. See b24 section.

  - Related Parameters: b24

- **b02 Allowable instantaneous power failure time setting**

  - Range: 0.3 ~ 10.0 Sec in 1.0 Sec

  Program the period for VFD go through under voltage condition without UV trip. This time varies depending upon the loading. Thus, a user must perform the test prior to entering the time value.

  - Related Parameters:

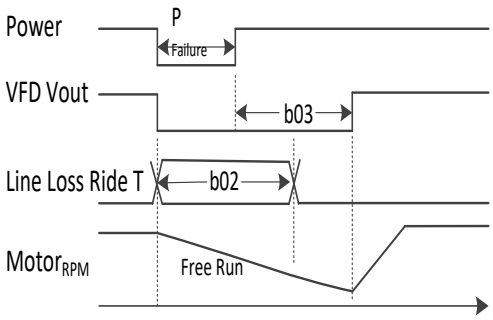
- **b03 Reclosing standby after Instantaneous power failure recovered**

  - Range: 0.3 ~ 10.0 Sec in 0.1 Sec

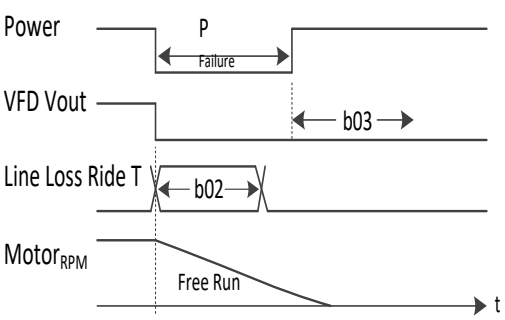
  Frequency value of VFD output Voltage.
  It is the value specified on the Motor nameplate.

  - Related Parameters:
  -

i) Momentary Power Failure Period < b02



ii) Momentary Power Failure Period > b02



- **b24 Failure status output selection by relay in case of failure**

  - 0: Inactive at low voltage failure
  - 1: Active at voltage failure(Inactive at restart mode)
  - 2: Active of all failure occurred
  - 3: Active at voltage failure(For low voltage failure, automatic restart)

  Combined with Restart, b01 select, various method can be selected as summarized for "Overvoltage and Over current" trip and "Under voltage" trip respectively.

  ❖ Related Parameters:

b24: Relay 1 Select / **b01: Restart Select**	**b24 = 0 *** No Relay 1 Activated originally, but, for OV & OC, Activated for Safety	**b24 = 1** Yes, Relay 1 is activated when long steady Trip signal	**b24 = 2** Yes, Relay 1 for every Trip signal	**b24 = 3 *** Relay 1 activated when long Trip signal Auto Reset to Restart is banned for safety
b01 = 0 No Restart	Trip (OV, OC) Relay 1	Trip (OV, OC) Relay 1	Trip (OV, OC) Relay 1	Trip (OV, OC) Relay 1
b01 = 1 Yes Restart @ 0 Hz	1st 2nd 3rd 4th Trip Restart Relay 1 @ 1st Trip, No Relay 1 but Restart from 0 Hz But if Trips Again @ 2nd Trip, No Relay 1 & Restart from 0 Hz @ 3rd Trip, No Relay 1 & Restart from 0 Hz @ 4th Trip, Yes Relay 1 & Wait for User Act	1st 2nd 3rd 4th Trip Restart Relay 1 @ 1st Trip, No Relay 1 but Restart from 0 Hz But if Trips Again @ 2nd Trip, No Relay 1 & Restart from 0 Hz @ 3rd Trip, No Relay 1 & Restart from 0 Hz @ 4th Trip, Relay 1 On & Wait for User Act	1st 2nd 3rd 4th Trip Restart Relay 1 @ 1st Trip, Relay 1 On & Restart from 0 Hz But if Trips Again @ 2nd Trip, Relay 1 On & Restart from 0 Hz @ 3rd Trip, Relay 1 On & Restart from 0 Hz @ 4th Trip, Relay 1 On & Wait for User Act	1st 2nd 3rd 4th Trip Restart Relay 1 @ 1st Trip, Relay 1 On & Restart from 0 Hz But if Trips Again @ 2nd Trip, Relay 1 On & Restart from 0 Hz @ 3rd Trip, Relay 1 On & Restart from 0 Hz @ 4th Trip, Relay 1 On & Wait for User Act
b01 = 2 Yes Restart @ M' Hz	1st 2nd 3rd 4th Trip Restart Relay 1 @ 1st Trip, No Relay 1 but Restart @ M' Hz But if Trips Again @ 2nd Trip, No Relay 1 & Restart @ M' Hz @ 3rd Trip, No Relay 1 & Restart @ M' Hz @ 4th Trip, Relay 1 On & Wait for User Act	1st 2nd 3rd 4th Trip Restart Relay 1 @ 1st Trip, No Relay 1 but Restart @ M' Hz But if Trips Again @ 2nd Trip, No Relay 1 & Restart @ M' Hz @ 3rd Trip, No Relay 1 & Restart @ M' Hz @ 4th Trip, Relay 1 On & Wait for User Act	1st 2nd 3rd 4th Trip Restart Relay 1 @ 1st Trip, Relay 1 On & Restart @ M' Hz But if Trips Again @ 2nd Trip, Relay 1 On & Restart @ M' Hz @ 3rd Trip, Relay 1 On & Restart @ M' Hz @ 4th Trip, Relay 1 On & Wait for User Act	1st 2nd 3rd 4th Trip Restart Relay 1 @ 1st Trip, Relay 1 On & Restart @ M' Hz But if Trips Again @ 2nd Trip, Relay 1 On & Restart @ M' Hz @ 3rd Trip, Relay 1 On & Restart @ M' Hz @ 4th Trip, Relay 1 On & Wait for User Act
b01 = 3 Yes Restart @ M' Hz & Stop	Trip Restart VFD to STOP Relay 1 @ 1st Trip, VFD Restart from M' Hz But Slow down to stop @ Stop, Trip goes back on and Relay 1 Activated	Trip Restart VFD to STOP Relay 1 @ 1st Trip, VFD Restart from M' Hz But Slow down to stop @ Stop, Trip goes back on and Relay 1 Activated	Trip Restart VFD to STOP Relay 1 @ 1st Trip, VFD Restart from M' Hz But Slow down to stop @ Stop, Trip goes back on and Relay 1 Activated	Trip Restart VFD to STOP Relay 1 @ 1st Trip, VFD Restart from M' Hz But Slow down to stop @ Stop, Trip goes back on and Relay 1 Activated

Restart and Relay 1 Operation When Over Voltage or Over Current Trip

* case (b24=0) & (b24=3) are modified from the original design concept shown in Under Voltage case due to the safety concerns Thus, both cases look

* exactly the same as (b24=1). A first user may be confused by many different cases show the same outcome.

b24: Relay 1 Select / **b01: Restart Select**	**b24 = 0** No Relay 1 Activated	**b24 = 1** Yes, Relay 1 is activated when long steady Trip signal	**b24 = 2** Yes, Relay 1 for every Trip signal	**b24 = 3** Relay 1 activated when long Trip signal then auto Reset to Restart
b01 = 0 No Restart	Trip (UV) Relay 1	Trip (UV) Relay 1	Trip (UV) Relay 1	Trip (UV) Relay 1
b01 = 1 Yes Restart @ 0 Hz	1^{st} 2^{nd} 10^{th} 11^{th} Trip Restart Relay 1 @ 1^{st} Trip, No Relay 1 but Restart from 0 Hz But if Trips Again @ 2^{nd} Trip, No Relay 1 & Restart from 0 Hz ⋮ @11^{th}Trip, No Relay 1 & Wait for User Act	1^{st} 2^{nd} 10^{th} 11^{th} Trip Restart Relay 1 @ 1^{st} Trip, No Relay 1 but Restart from 0 Hz @ 2^{nd} Trip, No Relay 1 & Restart from 0 Hz ⋮ @11^{th}Trip, No Relay 1 & Wait for User Act	1^{st} 2^{nd} 10^{th} 11^{th} Trip Restart Relay 1 @ 1^{st} Trip, Relay 1 On & Restart from 0 Hz @ 2^{nd} Trip, Relay 1 On & Restart from 0 Hz ⋮ @11^{th}Trip, Relay 1 On & Wait for User Act	1^{st} 2^{nd} 10^{th} 11^{th} Trip Restart Relay 1 @ 1^{st} Trip, No Relay 1 but Restart from 0 Hz @ 2^{nd} Trip, No Relay 1 & Restart from 0 Hz ⋮ @11^{th}Trip, Relay 1 On then Auto Reset and Restart from 0 Hz
b01 = 2 Yes Restart @ M' Hz	1^{st} 2^{nd} 10^{th} 11^{th} Trip Restart Relay 1 @ 1^{st} Trip, No Relay 1 but Restart @ M' Hz But if Trips Again @ 2^{nd} Trip, No Relay 1 & Restart @ M' Hz ⋮ @11^{th}Trip, No Relay 1 & Wait for User Act	1^{st} 2^{nd} 10^{th} 11^{th} Trip Restart Relay 1 @ 1^{st} Trip, No Relay 1 but Restart @ M' Hz But if Trips Again @ 2^{nd} Trip, No Relay 1 & Restart @ M' Hz ⋮ @11^{th}Trip, No Relay 1 & Wait for User Act	1^{st} 2^{nd} 10^{th} 11^{th} Trip Restart Relay 1 @ 1^{st} Trip, Relay 1 On & Restart @ M' Hz @ 2^{nd} Trip, Relay 1 On & Restart @ M' Hz ⋮ @11^{th}Trip, Relay 1 On & Wait for User Act	1^{st} 2^{nd} 10^{th} 11^{th} Trip Restart Relay 1 @ 1^{st} Trip, No Relay 1 but Restart @ M' Hz But if Trips Again @ 2^{nd} Trip, No Relay 1 & Restart @ M' Hz ⋮ @11^{th}Trip, Relay 1 On then Auto Reset and Restart from 0 Hz
b01 = 3 Yes Restart @ M' Hz & Stop	Trip Restart VFD to STOP Relay 1 @ 1^{st} Trip, VFD Restart from M' Hz But Slow down to stop @ Stop, Trip goes back on and Relay 1 NOT Activated	Trip Restart VFD to STOP Relay 1 @ 1^{st} Trip, VFD Restart from M' Hz But Slow down to stop @ Stop, Trip goes back on and Relay 1 Activated	Trip Restart VFD to STOP Relay 1 @ 1^{st} Trip, VFD Restart from M' Hz But Slow down to stop @ Stop, Trip goes back on and Relay 1 Activated	Trip Restart VFD to STOP Relay 1 @ 1^{st} Trip, VFD Restart from M' Hz But Slow down to stop @ Stop, Trip goes back on and Relay 1 Activated

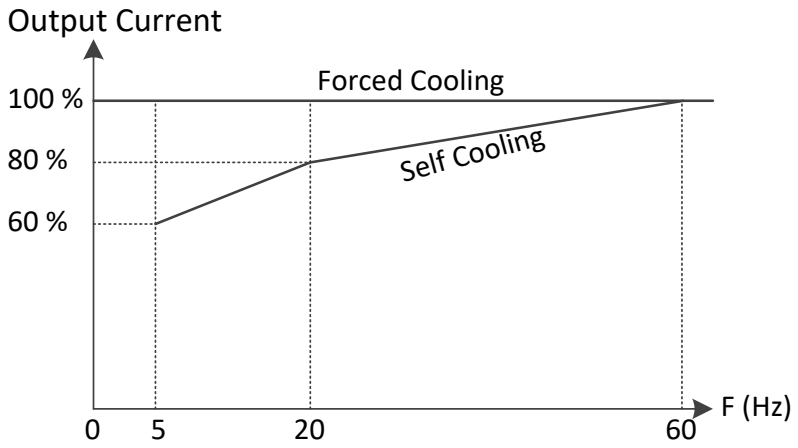
Restart and Relay 1 Operation When Under Voltage Trip

- **b04 Electronic thermal level setting**
  - Range: 20.0 ~120.0 % in 0.1 %

  Program a level of the rated motor current (Inverter Rated Current)

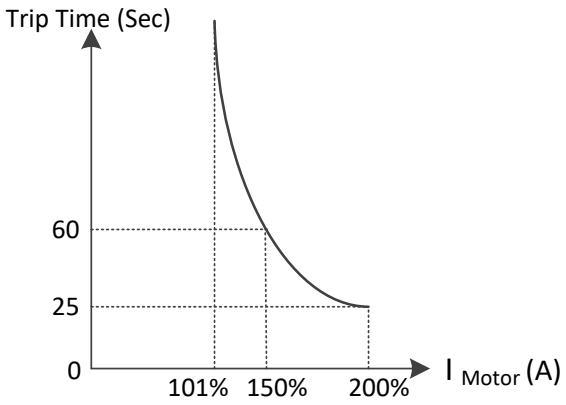
  - ❖ Related Parameters:

- **b05 Electronic thermal characteristic, selection**
  - 0: Self Cooling – Fan is mounted on the motor shaft
  - 1: Forced Cooling – Fan is powered by external power source

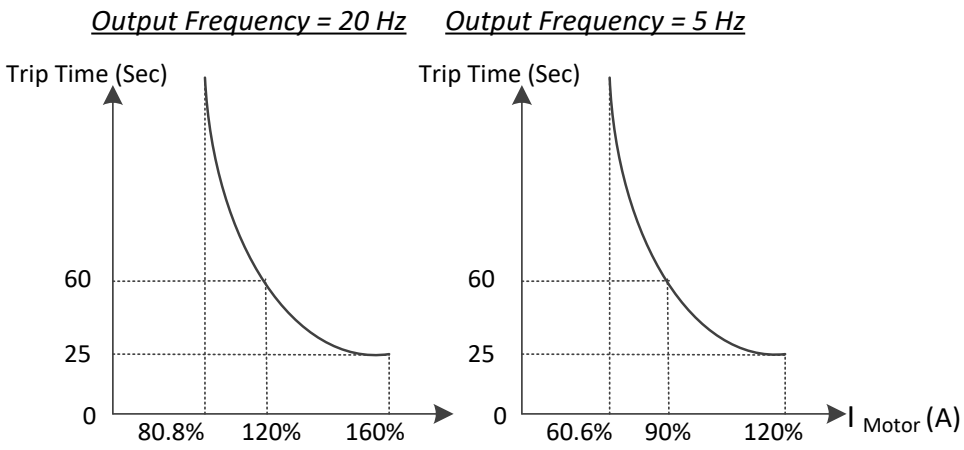


Select a cooling method

- ❖ Related Parameters:



b05 = 1: Trip Time vs. Motor Current



b05 = 0: Trip Time vs. Motor Current

- Ex) electronic thermal operation of iMASTER C1-037HF model
  - Rated current: 7.7A (Setting range: 1.54 ~ 9.24A)
  - When the electronic thermal level (b04) is 100% and the electronic thermal characteristic (b05) is set to 1, the motor current-trip time characteristic curve is as follows.
  - when 11.5A is held for 60 seconds occurs E05 (motor overload) trip.

- **b06 Overload overvoltage Restriction mode selection**

  - 0: Overload restriction mode OFF
  - 1: Maintain Output frequency in case of overload
  - 2: In case of overload Operate according to b08 setting
  - 3: In case of overload, operates at a maximum of 20% of the acceleration time setting.

  * Overvoltage setting is b67

  Select a overload or overvoltage restriction modes
  - Related Parameters: b08, b67

- **b07 Overload restriction level setting (constant speed)**

  - Range: Set Between 20%~200% of rated current of inverter

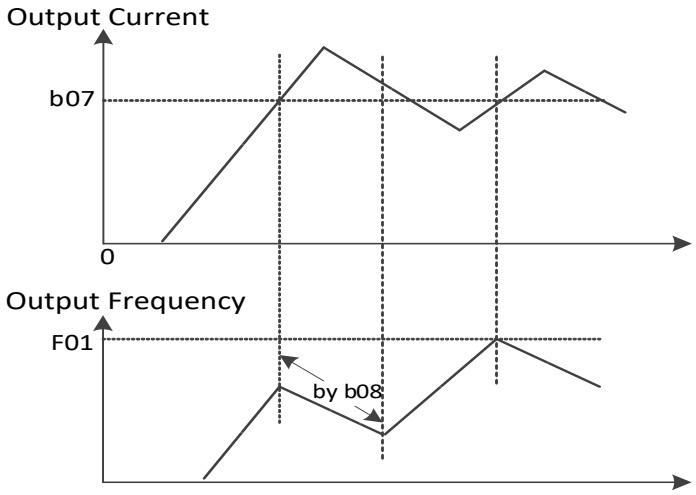
  HD: 20.0%~ 200.0%
  ND: 20.0%~ 165.0%
  * If there is speed change, you can set at b49

  Program the level for overload restriction % of the VFD rated current
  - Related Parameters: b49

- **b08 Overload restriction constant setting**

  - Range: 0.1~10.0 Sec in 0.1 Sec

  Program the deceleration time for the rate when the VFD detects the overload
  - ❖ Related Parameters:



Overload restriction function

- **b09 Software lock mode selection**

  - 0: All Parameters are locked except b09 when SFT terminal input is ON
  - 1: All Parameters are locked except b09 and F01 by SFT terminal Signal
  - 2: All Parameters are locked except b09
  - 3: All Parameters are locked except b09 and F01
  - 4: All parameters are locked except b09, F01, F02, and F03

  Software Lock mode to prevent any un-intentional modification of set parameter values
  - ❖ Related Parameters:

No.	Condition	Function	exception code
0	When the terminal is being input to [SFT]	All data cannot be changed	b09(soft lock function)
1			F01(Output Frequency Setpoint) b09(Software Lock Mode)
2	When setting the function,		b09(Software Lock Mode)
3			F01(Output Frequency Setpoint) b09(Software Lock Mode)
4			F01(Output Frequency Setpoint) b09(Software Lock Mode) F02, F03(Accel/ Decel Time 1)

- **b10 Start Frequency Adjustment**

  - Range 0.10 ~ Max. frequency(A04) Hz in 0.01 Hz

  Setting the starting frequency from the VFD output
  - ❖ Related Parameters:

- **b11 Carrier frequency setting**

  - Range 0.75 ~ 16.0 Hz in 0.1 kHz (0.4kW~3.7kW)
  - Range 0.75 ~ 10.0 Hz in 0.1 kHz (5.5kW~22kW)

  Select Heavy Duty or Normal Duty factory setting per VFD model and loading type
  - ❖ Related Parameters:

Model	Setting Range(kHz)
iMASTER C1-004LF~022SF iMASTER C1-004LF~037LF iMASTER C1-004HF~037HF	0.75 ~16.0
iMASTER C1-055LF~150LF iMASTER C1-055HF~1320HF	0.75 ~10.0
iMASTER C1-1600HF~3500HF	0.75 ~4.0

Setting Range of Carrier Frequency

Model	Heavy Duty (b26 = 0)	Normal Duty (b26 = 1)
iMASTER C1-004LF~022SF iMASTER C1-004LF~037LF iMASTER C1-004HF~037HF	5.0kHz	-
iMASTER C1-055LF~150LF iMASTER C1-055HF~220HF	5.0kHz	2.0kHz
iMASTER C1-300HF~1320HF	3.0kHz	2.0kHz
iMASTER C1-1600HF~3500HF	2.0kHz	2.0kHz

Initial value of Carrier Frequency

- **b12 Initialization mode**

  - 0: Trip history clear
  - 1: Parameters except b13(Country Code) and A53(Motor Input Voltage)

  Select an initialization mode
  - ❖ Related Parameters:

- **b13 Country code for initialization**

  - 0: Korea version
  - 1: Europe version
  - 2:US version

  Select a country code of which default parameter values to use
  - ❖ Related Parameters:

- **b14 RPM conversion factor setting**

  - Range: 0.01 ~ 99.99 in 0.01

  Program RPM Scale factor for d08 Display
  - ❖ Related Parameters: d08

- **b15 STOP key validity during terminal operation**

  - 0: Enabled
  - 1: Disabled

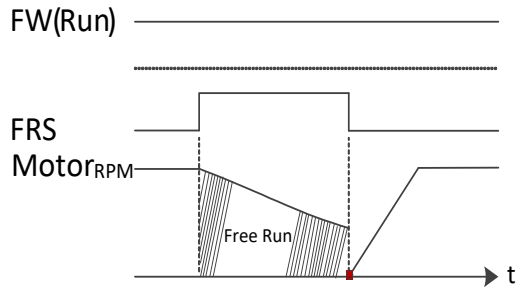
  To avoid un-desired stop by pressing the STOP key on the panel by some other operator when the main operation is being performed by terminal or remotely.
  - ❖ Related Parameters:

- **b16 Resume on FRS cancellation mode**

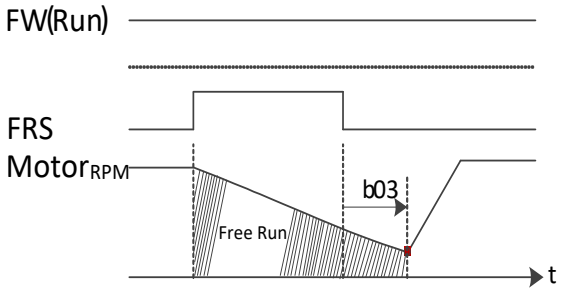
  - 0: Start from 0Hz
  - 1: Restart from frequency corresponding motor speed

  Select what frequency VFD to resume its operation when the Free Run Stop (FRS) is cancelled.
  - ❖ Related Parameters: b03

i) When b16=0



i) When b16=1



- **b17 Communication number**

  - Range: 1~32

  Node ID for Modbus Communication
  - ❖ Related Parameters:

- **b18 Ground fault setting**

  - Range: 0.0 ~ 100.0 % in 0.1 %
  - 0: Do not detect ground fault

  * Below 22kW, disable ground fault setting. (value is always 0)
  Upper 30kW, able to use as above range.

  Program to enable the Ground fault detection and its fault level as a percentage of rated current. For iMASTER C1 models under 3.7 kW(5 HP), this function is turned off from the Factory
  - ❖ Related Parameters:

- **b19 Speed Search Delay Time**

  - Range: 0.1 ~ 30.0 s in 0.1 s

  Controls delay time during speed search motion on the basis of the motor rated current
  - ❖ Related Parameters: b19~b23

- **b20 Voltage increase Time during Speed Search**

  - Range: 0.1 ~ 10.0 s in 0.1 s

  In case of the lower starting current time during speed search motion on the basis of the motor rated current, the increase level of the output voltage is set from 10% to 300%
  - ❖ Related Parameters: b19~b23

- **b21 Current limit level of Speed Search**

  - Range: 50.0 ~ 180.0 s in 0.1 %

  Related Parameters:

- **b22 Deceleration time at FRS (Free Run Stop Command)**

  - Range: 0.1 ~ 999.9 Sec in 0.1 Sec
    1000 ~ 6000 Sec in 1 Sec
  - 0.0 : Free Run to Stop
  - 0.1 ~ 6000.0 : Deceleration to Stop

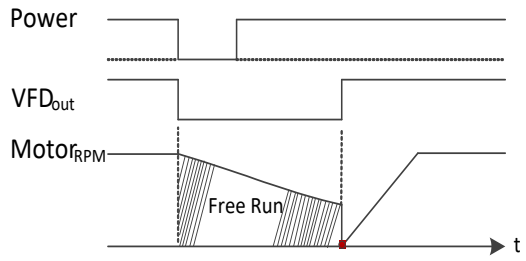
  Deceleration time from Maximum Frequency (A04) to 0Hz
  - ❖ Related Parameters: A55, A56, A58, A60

- **b23 Frequency match operation selection**

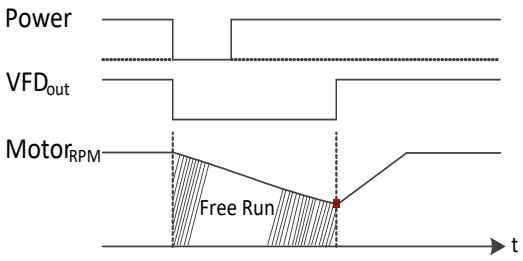
  - 0: 0Hz Starting operation
  - 1: Frequency matching & start operation

  In case of inverter starting operation, the start frequency of the inverter can be selected as follows
  - ❖ Related Parameters: b19~b20,b23

i) When b23 = 0



i) When b23 = 1



- **b25 Stop method selection**

  - 0: Decelerating stop
  - 1: Coast to Stop (Free Run to Stop)
  - 2: Decelerating stop & Nonstop reset
  - 3: Free run stop & Nonstop reset

  Select a stop method when Stop command is given. Depending on the selection, the reset command signal could enable or have no effect on stop command.
  - ❖ Related Parameters:

- **b26 Inverter type change to HD / ND**

  - 0: Heavy Duty (HD): Constant Torque Load Type (bellow 3.7kw, value is always 0)
  - 1: Normal Duty (ND): Variable Torque Load Type

  Select a torque type for appropriate “Rated Power” and “Overload Tolerance” values. For instance, for Fans, or centrifugal pump applications, select ND and Hoists, conveyors, pump process, select HD. Factory setting of Carrier Frequency value for HD and ND in the table.
  - ❖ Related Parameters: b11

- **b27 Input phase loss**

  - 0: Disabled
  - Range: 0 ~ 30 Sec in 1 Sec

  Enables & sets the time period to determine if an Input Phase Loss occurs. The VFD monitors the ripple on the DC bus voltage and if it occurs for the programmed magnitude and time period an Input Phase Loss fault will occur. The ripple on the DC bus will cause heating to the DC Bus capacitors which will shorten their life.
  - ❖ Related Parameters:

- **b28 Communication time out setting**

  - 0: Disabled
  - Range: 0 ~ 60 Sec in 1 Sec

  Select a time out detection period when communication discontinues. If no communication event occurs during this time period, a communication fault will occur.
  - ❖ Related Parameters:

- **b29 Communication time out operation mode**

  - 0: Always active & RESET alarm enabled
  - 1: Active in case of inverter is running & RESET alarm enabled
  - 2: Always active & RESET alarm disabled
  - 3: Active in case of inverter is running & RESET alarm disabled

  Select a time out detection mode. Depending on selection, the communication error alarm could be enabled or disabled by reset command.
  - ❖ Related Parameters:

- **b30 Display code setting**

  - Range: 1 ~ 13 (for d01 ~ d13)

  Select an initial display parameter at power on
  - ❖ Related Parameters:

- **b31 2nd communication channel 485 communication speed setting**

  - 1: 2,400 bps
  - 2: 4,800 bps
  - 3: 9,600 bps
  - 4: 19,200 bps
  - 5: 38,400 bps

  Select a baud rate for the RXP-RXN terminal communication RS485 channel
  - ❖ Related Parameters:

- **b32 BRD selection**

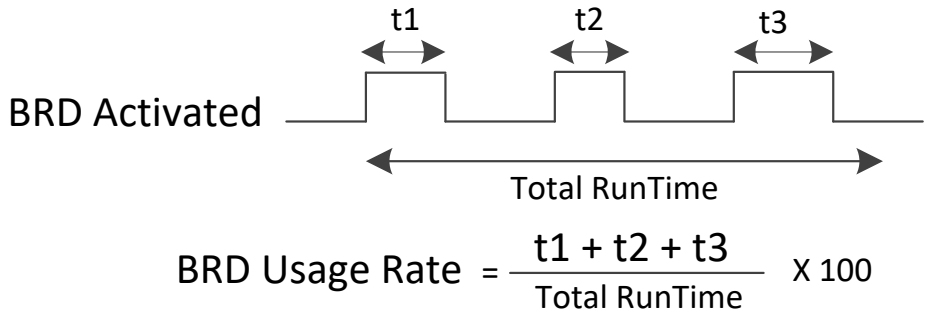
  - 0: Disabled
  - 1: Enable only during inverter running
  - 2: Enable

  This BRD function is only applicable to iMASTER C1 models under 22kW(30 HP) Regenerative energy from the motor is dissipated by the heat through this braking resistor module.
  - ❖ Related Parameters:

- **b33 BRD using ratio**

  - Range: 0.0 ~ 10.0 % in 0.1 % (0.4kW~3.7kW)
  - Range: 0.0 ~ 50.0 % in 0.1 % (5.5kW~22kW)

  Select a percentage value of total BRD on time before the overheating fault occurs
  - ❖ Related Parameters:

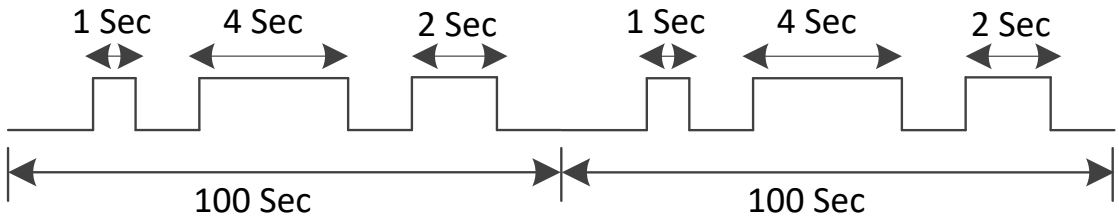


BRD Duty cycle

Ex) BRD usage rate (b33) is set to 10%

1) Normal operation

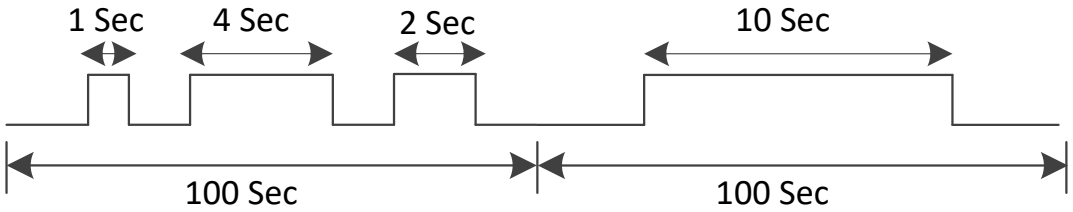
If the sum of the brake resistor ON sections does not exceed 10 seconds in the 100 second section, the brake resistor operates normally without overload protection trip.



=> BRD Normal Operation => BRD Normal Operation

2) Trip operation

If the sum of the brake resistor ON sections exceeds 10 seconds in the 100 second section, the brake resistor overload protection trip (E06) is issued and the motor stops.
Regardless of the section, if the braking resistor is turned on continuously for 10 seconds, the braking resistor overload protection trip (E06) is generated.



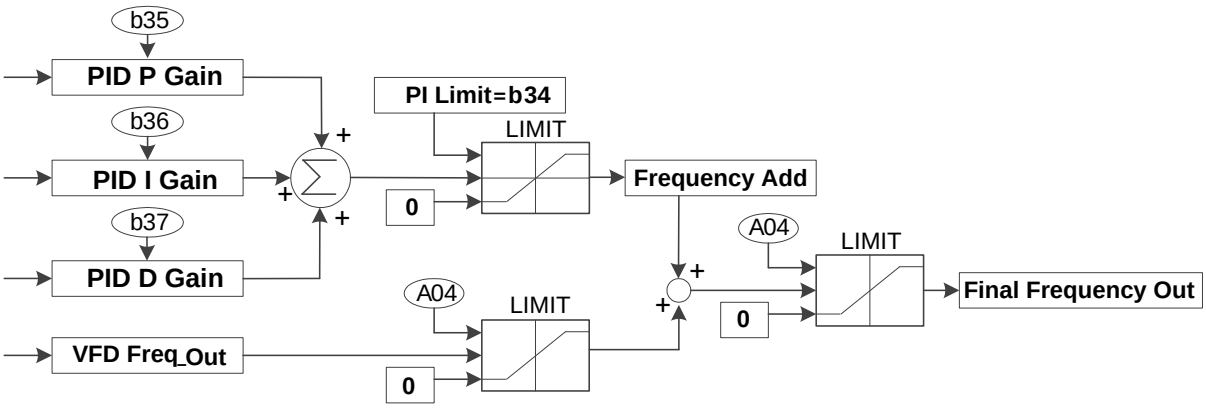
=> BRD Normal Operation => Over heat Trip (E06)

◆ **b34 ~ b41 Overvoltage Suppression(OVS) Function**

The Overvoltage Suppression (OVS) feature will over speed the motor up to the Maximum OVS Output Frequency (b34) to prevent motor regeneration and creating an Overvoltage Fault. If the OVS runs at maximum frequency for longer than the Limit Time (b41), the unit will fault on E02.

OVS Functional Description

- By calculating torque in real time, reduce regeneration energy by increasing speed.
- For speed control, PI controller is applied.
- If torque is bigger than 0, “PI Out” become 0 by “PI Limiter”; no increase in frequency value
- If torque is lower than 0, “PI Out” would be increased to “Max Add Req”; frequency value increased
- If output of PI controller is reached to b34(Max Add Freq) The counter is started.
- When the value of counter is reached to b41 (wRegen Time), the trip(E02) will be occur.



OVS Function diagram

- **b34 Maximum OVS output frequency**
  - Range: 0.00 ~ 300.00 Hz in 0.01 Hz
    Real time editable a maximum frequency limit for OVS function
    ❖ Related Parameters:
- **b35 OVS P gain**
  - Range: 0 ~ 10000 in 1
    - Real time editable P gain for OVS PID loop
    - PIOut = err * Kp
    - Hz = err(%) * Kp * scalefactor(50 * 1e-6)

    Example
    - err 10%, Kp = 1000
      ⇨ PIOut = 0.5Hz

    ✓ Recommended Value in test bench
      ⇨ 1000 or less than 5000

    ❖ Related Parameters

- **b36 OVS I gain**

  - Range: 0 ~ 10000 in 1

    Real time editable I gain for OVS PID loop
    - PIOut = ∫(err * Ki)
    - Hz += err(%) * Ki * scalefactor(50 *1e-6), dT = 1msec

    Example (Integration Time to 10Hz on Error)
    - err 10%, Ki = 1000
      - ⇨ Time to 10Hz on 10% Error = 20msec
    - err 10%, Ki = 100
      - ⇨ Time to 10Hz on 10% Error = 200msec
    - err 10%, Ki = 10
      - ⇨ Time to 10Hz on 10% Error = 2000msec

    ✓ Recommended Value in test bench
      - ⇨ 100 or less than 500

    ❖ Related Parameters:

- **b37 OVS D gain**

  - Range: 0 ~ 10000 in 1

    Real time editable D gain for OVS PID loop. Its value depends on b39; filter bandwidth. Thus, if b39 is not changed, no need to change OVS PID D Gain value. Most application, this value should not be set over 3000

    ✓ Recommended Value as a function of b39
      - ⇨ If b39 < 10 → b37: 0 ~ 500
      - ⇨ If b39 < 30 → b37: 500 ~ 1000
      - ⇨ If b39 < 50 → b37: 1000 ~ 1500

    ❖ Related Parameters:

- **b38 Q axis reference (q axis reference current)**

  - Range: -100.0 ~ 100.0 in 0.1

    Real time editable q axis reference current compensates Torque Estimate Error.

    - If Torque estimate offset is bigger than 0
      - ⇨ No increase in output frequency even if regeneration is occurred.
      - ⇨ This situation could be end with OV Trip.
      - ⇨ If so, set b38 to a positive value
    - If Torque estimation offset smaller than 0
      - ⇨ No increase in output frequency even if regeneration is not occurred.
      - ⇨ Output Frequency could be increased to Max. Freq (Reference Frequency + b34) and end up with E02 (OVS Fail)
      - ⇨ If so, set b38 to a negative value

    ❖ Related Parameters

- **b39 Filter bandwidth (q axis LPF coefficient)**

  - Range: 0 ~ 1000 ms in 1 ms

    Real time editable Iq feedback Low Pass Filter time constant

    - If output Frequency is not stable,
      - ⇨ Increase b39 value
    - ➢ Recommended Value as a function of (b39); (b37) value should be set accordingly
      - ⇨ Not set over 50

    ❖ Related Parameters:

- **b40 Overvoltage suppression (Normal Mode)**

  - 0: Disabled
  - 1: Enable for current control
  - 2: Enable for voltage control

    Select to enable the Voltage Suppression Control function.

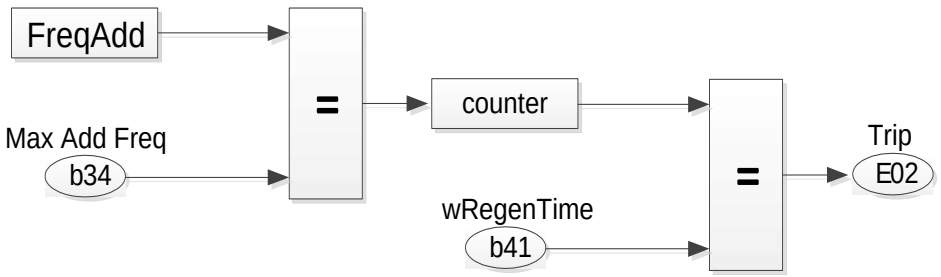
    ❖ Related Parameters:

- **b41 Limit Time (Regen Time)**

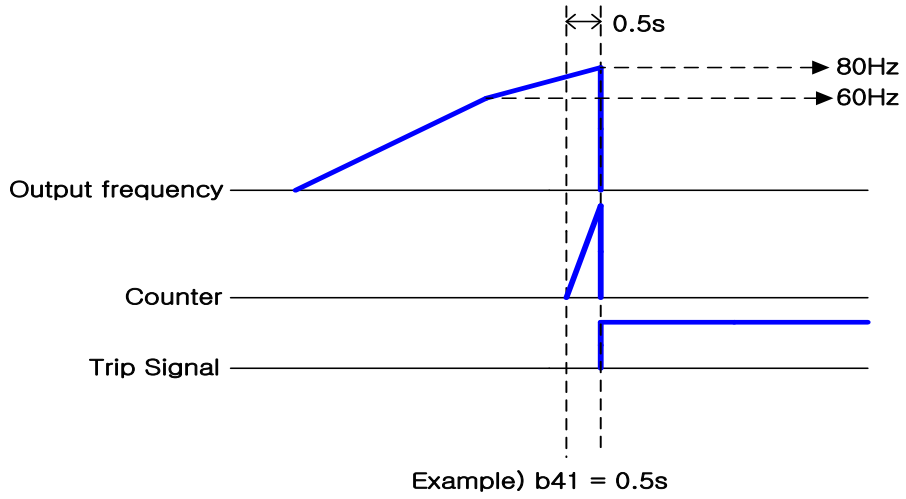
  - Range: 0.0 ~ 100.0 Sec in 0.1 Sec

    Real time editable OVS control fail check time. If PID output is saturated to Maximum OVS output Frequency (b34) during this time period, VFD will stop and E02 will be occurred.

    ❖ Related Parameters:



Example of overvoltage suppression error detection operation



Example of voltage suppression (OVS) function operation during constant speed operation

b42 ~ b46 (Extended A33 ~ A37) – Also Explained in A -Group

- **b42 VFD start delay time after DC injection braking**
  - Range: 0.0 ~ 60.0 Sec in 0.1 Sec

  Program the VFD start delay time after braking time at start is done
  - Related Parameters: A33, b43~b46

- **b43 DC injection braking time at start**
  - Range: 0.0 ~ 6000.0 Sec in 0.1 Sec

  Program the DC Injection Braking duration before VFD start
  - Related Parameters: A33, b42~b46

- **b44 Current controller P gain in DC braking**
  - Range: 1 ~ 10000 in 1

  Program the current controller P gain in DC braking
    - This value is applied both brake modes (start and stop)
    - If motor speed has a large overshoot at DC braking, decrease this value
    - If value is too big, motor can be vibrated or can't be stopped
  - Related Parameters: A33, b42~b46

- **b45 Current controller I gain time in DC braking**
  - Range: 0 ~ 10000 in 1

  Program the current controller I gain in DC braking
    - This value is applied both brake modes (start and stop)
    - If motor is vibrated or not stop at DC braking, decreased this value
    - If value is too big, DC braking force can be weak
  - Related Parameters: A33, b42~b46

- **b46 DC injection braking force**

  - Range: 0.0 ~ 100.0 % in 0.1 %

  Program the level of DC injection braking force of rated electric power of iMASTER C1
  - ❖ Related Parameters:

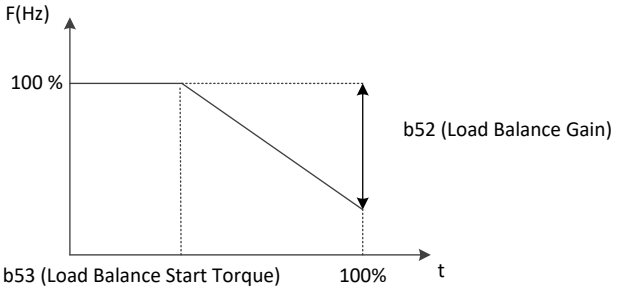
- **b49 Overload restriction level at acceleration & deceleration**

  - Range: 20.0 ~ 200.0 % (HD)
  - Range: 20.0 ~ 165.0 % (ND)

  Separately programmable overload restriction is that applies only during the acceleration and deceleration periods. This function works the same as b07, but can be configured to a different value to account for the difference in current draw during normal operation and flying start.
  - ❖ Related Parameters:b06, b07, b23

◆ **b50 ~ b55 Load Balance Function**

Load Balance is a feature that automatically shares the load level between two independent motors driving the same load. The Output Frequency of each motor is independently changed by the amount of torque it is applying. The amount of the increase/decrease is dependent on the amount of torque being applied.



$$\text{Control Frequency} \times \frac{(\text{Output Torque} - \text{Load Balance Start Torque})}{100\% - \text{Load Balance Start Torque}} \times \text{Load Balance Gain} \times \text{Load Balance Target Frequency}$$

- **b50 Droop control start freq.**

  - Range: 0.00 ~ Max. frequency (A04) Hz in 0.01 Hz

  Sets the frequency where the Load Balance Start Frequency feature is enabled.
  When running below this frequency the feature is disabled

- **b51 Droop control standard freq.**

  - Range: 10.00 ~ Max. frequency (A04) Hz in 0.01 Hz

  Sets the frequency where the Load Balance Start Frequency feature is enabled.
  When running below this frequency the feature is disabled.

- **b52 Droop control gain**

  - Range: 0.00 ~ 50.00 % in 0.01%

  Sets the rate of change when this feature is functioning.
  It is based on a percentage of the output torque being applied.

- **b53 Droop star torque**

  - Range: 0.0 ~ 100.0 % in 0.1 %

  Sets the amount of output torque applied at start when the Load Balance function is enabled.

- **b54 Droop acceleration time**
  - Range: 0.0 ~ 100.0 Sec in 0.1 Sec

  Sets the ramp rate applied to the output frequency when the Load Balance function is enabled.

- **b55 Droop control mode**

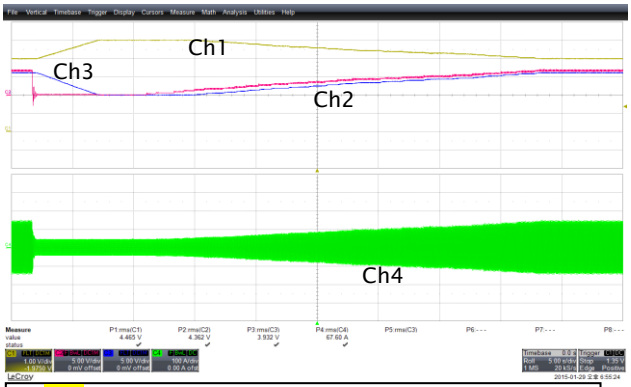
  - 0: Disabled
  - 1: Enabled

◆ **Set 0: Disabled**
Load balance is disabled

◆ **Set 1: Enabled**
Load balance works without any feedback

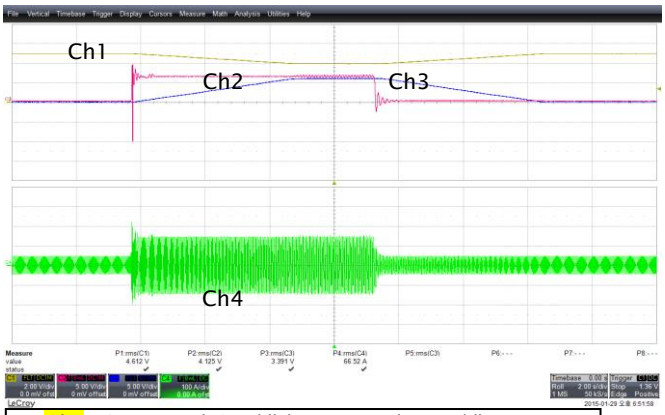
Example

1) Increased the load ratio up to 100%
Output frequency decreased by the amount of load



Ch1 : Out Freq. (12Hz/div) time 5s/div
Ch2 : Estimated Torque
Ch3 : Calculated Load Balance Freq
Ch4 : Output Current(100A/div)

2) Put 100% step load and removed 100% load in a moment
Put the step load (100%) for 8 seconds and then remove the step load.
The Load Balance control decreased the output frequency for b54 value (5sec) at step load.
The Load Balance control increased the output frequency for b54 value (5sec) at no step load.



Ch1 : Out Freq. (12Hz/div) time 5s/div
Ch2 : Estimated Torque
Ch3 : Calculated Load Balance Freq
Ch4 : Output Current(100A/div)

◆ **b56 ~ b60 Motor load detection**

The drive provides two independent torque detection functions that trigger an alarm or fault signal when the load is too heavy or suddenly drops

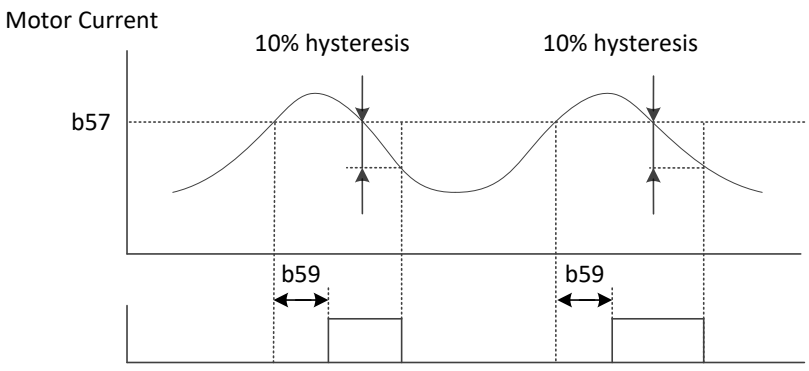
- **b56 Motor load detection selection**
  - 0: Disabled
  - 1: Overload Detection
  - 2: Underload Detection
  - 3: Overload/Underload Detection
  - 4: Overload Detection with Fault (E23)
  - 5: Underload Detection with Fault (E24)
  - 6: Overload/Underload Detection with Fault (E23, E24)

  For settings, 1~6 allows a relay contact to alert an external device, related parameters C13, C14, C15. In addition, setting 4~6 triggers trip signals display on the keypad

- **b57 Motor overload detection level**
  - Range: 20.0 ~ 200.0 % in 0.1 %

  Sets the System Overload level. This feature is triggered when the motor current exceeds this level. 100% level is based off of the value in H05.

System Overload Detection

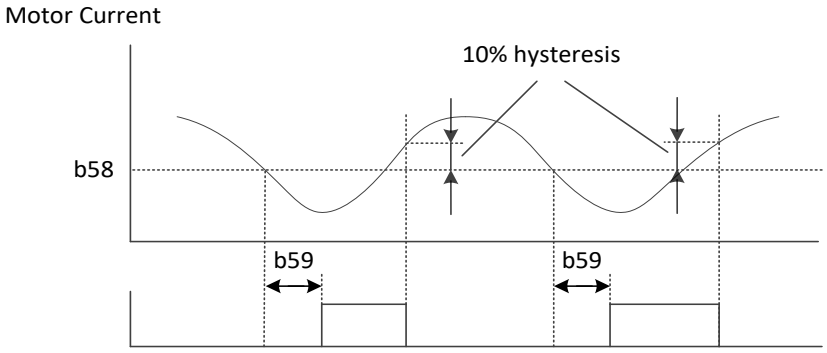


- **b58 Motor underload detection level**

  - Range: 20.0 ~ 200.0 % in 0.1 %

  Sets the System Underload level. This feature is triggered when the motor current exceeds this level. 100% level is based off of the value in H05.

System Underload Detection



- **b59 Overload/Underload detection time**

  - Range: 0.0 ~ 60.0 Sec in 0.1 Sec

  Sets the System Overload/Underload Detection time.

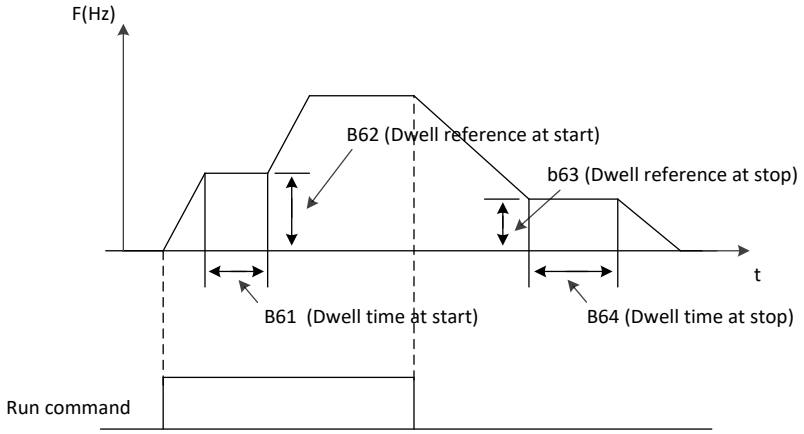
- **b60 Overload/Underload detection safe zone**

  - Range: 0.00 ~ Max frequency (A04) in 0.01 Hz

  Sets the level at which this feature is disabled.
  System Overload/Underload detection doesn't work below b60 value

◆ **b61 ~ b64 Dwell Function**

The Dwell Function temporarily holds the output frequency at a predetermined value for a predetermined time before accelerating or decelerating to the current frequency reference. The Dwell function helps preventing speed loss when starting and stopping a heavy load



- **b61 Dwell frequency at start**
  - Range: 0.00 ~ Max frequency (A04) in 0.01 Hz

  Program Dwell frequency at start

- **b62 Dwell time at start**
  - Range: 0.0 ~ 10.0 Sec in 0.1 Sec

  Program Dwell time at start

- **b63 Dwell frequency at stop**
  - Range: 0.00 ~ Max frequency (A04) in 0.01 Hz

  Program Dwell frequency at stop

- **b64 Dwell time at stop**
  - Range: 0.0 ~ 10.0 Sec in 0.1 Sec

  Program Dwell time at stop

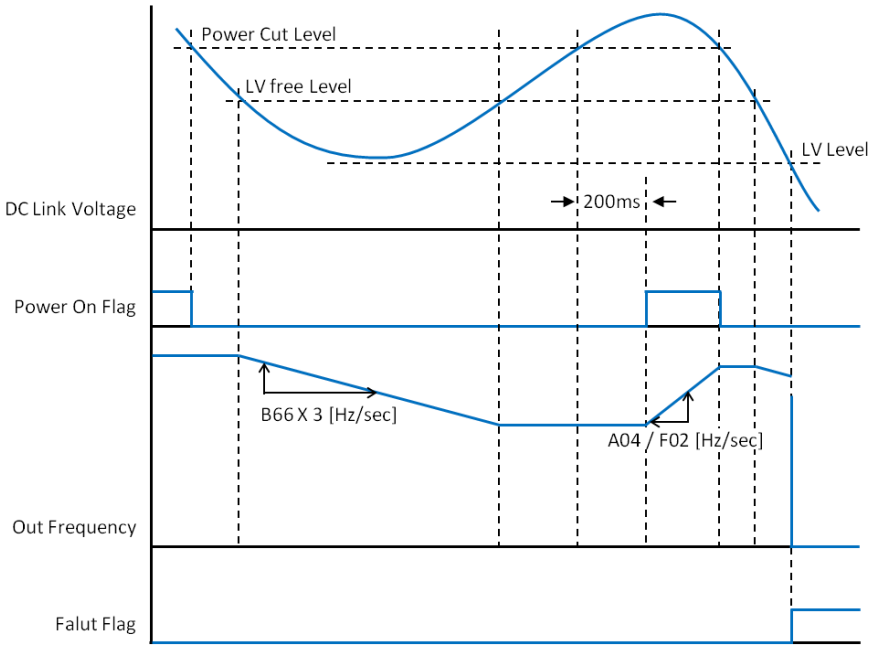
◆ **b65 ~ b66 KEB Function**

When power loss is detected, the Kinetic Energy Backup Ride-Thru function (KEB Ride-Thru) decelerates the motor and uses regenerative energy to keep the main circuit operating. Despite power loss, the drive output is not interrupted.

- **b65 KEB control selection**
  - 0: Disabled
  - 1: Enable (According to b66 Setting)
  - 2: Enable (DC Link Control)

- **b66 KEB control gain**
  - Range: 0.1 ~ 100.0 % in 0.1 %

set the degree of rapid deceleration of the motor during KEB operation.

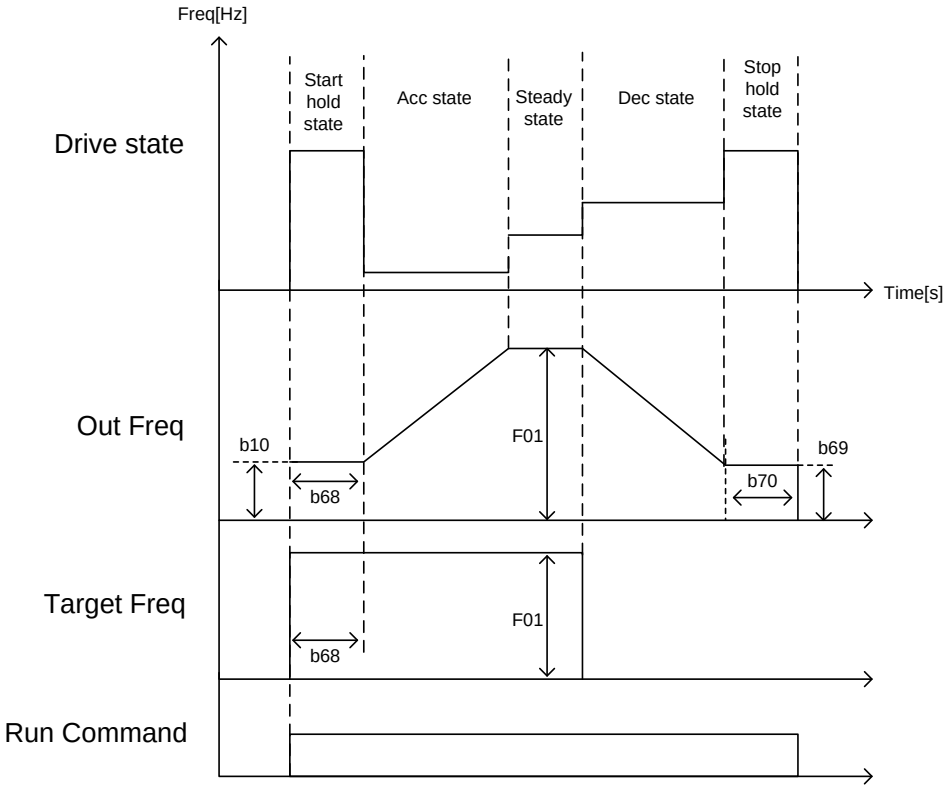


KEB operation diagram

- **b67 Overcurrent selection(Decel Mode)**
  - 0: Disabled
  - 1: Enable
- **b68 Hold time at running**
  - Range: 0.0 ~ 60.0 Sec in 0.1 Sec
- **b69 Stop frequency setting**
  - Range: 0.00 ~ Max frequency (A04) in 0.01 Hz

  When inverter is stop operation, stop frequency can be set by using B69 code.
- **b70 Hold time at stop**
  - Range: 0.0 ~ 60.0 Sec in 0.1 Sec

  It can be set to maintain the set stop frequency (B69) in the inverter stop operation until the set time.



- **b71 User parameter setting**

  - 1: Output frequency monitor
  - 2: Output current monitor
  - 3: Output voltage monitor
  - 4: Rotation direction monitor
  - 5: PID feedback monitor
  - 6: Intelligent terminal input monitor
  - 7: Intelligent terminal output monitor
  - 8: RPM monitor
  - 9: Power consumption monitor
  - 10: Display of cumulative time (day)
  - 11: Display of cumulative time (minute)
  - 12: DC link voltage

  Change the F06 (User Display) according to b71 selection.

  - Related Parameters:b71~b73, F06

- **b72 User mathematical sign**

  - 0 – '+' calculation
  - 1 - '-' calculation
  - 2 - 'X' calculation
  - 3 - '/' calculation

  F06 (User Display) select the Scale Factor (b73) and the operator(b72) to operate on.

  - Related Parameters:b71~b73, F06

- **b73 Define user setting**

  - Range: 1.00 ~ 600.00 in 0.01

  F06 (User Display) select the Scale Factor (b73) and the operator(b72) to operate on.

  - Related Parameters:b71~b73, F06

6.5 C Group Parameters

INPUT

- **C01~C06Intelligent Input Terminals 1~6**

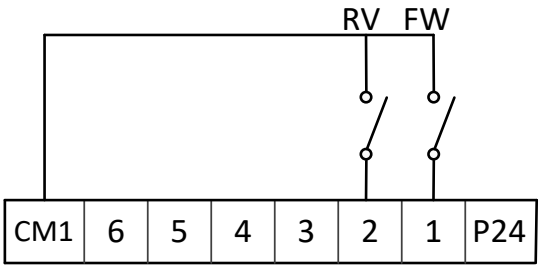
These input terminals can be programmed one of following functions.

Value	Name	Function	Comment
0	FW	Forward Run Command	C01 Initial value
1	RV	Reverse Run Command	C02 Initial value
2	CF1	Multiple Speed Command 1	C03 Initial value
3	CF2	Multiple Speed Command 2	C04 Initial value
4	CF3	Multiple Speed Command 3	
5	CF4	Multiple Speed Command 4	
6	JG	Jogging Operation Command	
8	2CH	Acceleration 2/Deceleration 2 Command	
7	ZERO	Zero Speed Command	Encoder Manual
9	FRS	Free Run Stop Command	
10	EXT	External Trip 1	
11	USP	Unattended Start Protection	
12	SFT	Software Lock Function	
13	AT	Analog Input Current/Voltage Selection	C05 Initial value
14	RS	Reset	C06 Initial value
15	STA	Start	
16	STP	Keep	
17	F/R	Forward / Reverse	
18	UP	Remote Control Up	
19	DOWN	Remote Control Down	
20	O/R	Local Keypad Operation	
21	T/R	Local Terminal Input Operator	
22	PIDIR	PID Integral Reset	
23	PIDD	PID Disabled	
24	F.O	Frequency Override	
25	R.O	Reset Override	
26	EXT2	External Trip 2	
27	EXT3	External Trip 3	
28	EXT4	External Trip 4	
29	EXT5	External Trip 5	
30	EXT6	External Trip 6	
31	U/D CLR	Up/Down Value Clear	

- **C07~C12 Input Terminal Mode 1~6**

  - 0: Normally Open (NO)
  - 1: Normally Closed (NC)

  Set 0:Forward Run/Stop (FW)
  Set 1: Reverse Run/Stop (RV)



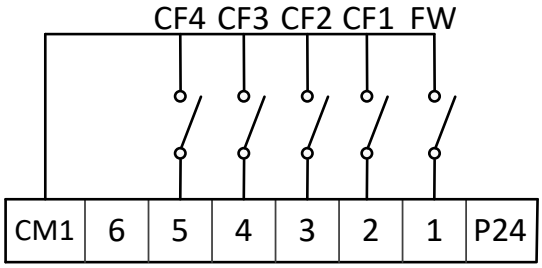
[Example FW/RV Function Terminal Setting]

Code	Set Value	Description
A01	1	Frequency Command by Terminal Input
A02	1	Run Command by Terminal Input
C01	0	Set Terminal 1 to FW Operation
C02	1	Set Terminal 2 to RV Operation
C07	0	FW Operation: Terminal 1 to Normal Open
		When shorted(Closed); FW Run, When Open, FW Stop
C08	0	FW Operation: Terminal 1 to Normal Open
		When Shorted(Closed): FW Run; When Open, FW Stop
Caution	* If Terminal 1 and Terminal2 are closed at the same time, VFD will stop	
	** If Run Connection and Command are set prior to the power up, as soon as power is on, motor will be running. Check if any command is set prior to the power is applied.	

-

- **Set 2: Multiple Speed Command 1 (CF1)**
- **Set 3: Multiple Speed Command 2 (CF2)**
- **Set 4: Multiple Speed Command 3 (CF3)**
- **Set 5: Multiple Speed Command 4 (CF4)**

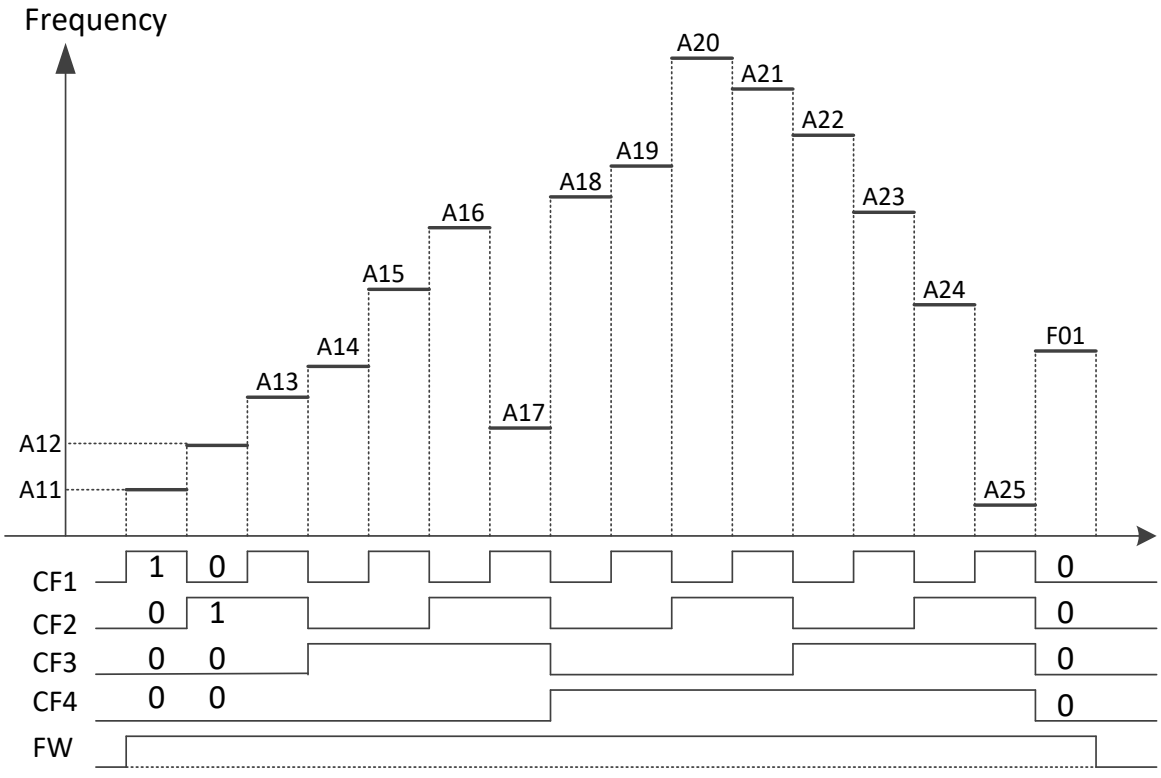
By combining CF4 ~ CF1, a frequency value can be selected
From A11 ~ A25.



[Example Multiple Speed Function Terminal Setting]

Code	Set Value	Description
A02	1	Run Command by Terminal Input
C01	0	Set Terminal 1 to FW Operation
C02	2	Set Terminal 2 to Multi Speed Command 1
C03	3	Set Terminal 3 to Multi Speed Command 2
C04	4	Set Terminal 4 to Multi Speed Command 3
C05	5	Set Terminal 5 to Multi Speed Command 4
C07~C11	0	Set Terminal 1 to 5 Normal Open
		When shorted(Closed); FW Run, When Open, FW Stop
F01	60	Set Output Frequency to 60Hz, but user programmable from 0 to 400 Hz
A11~A25	Hz	Program values for respective parameters. Refer to A Group.

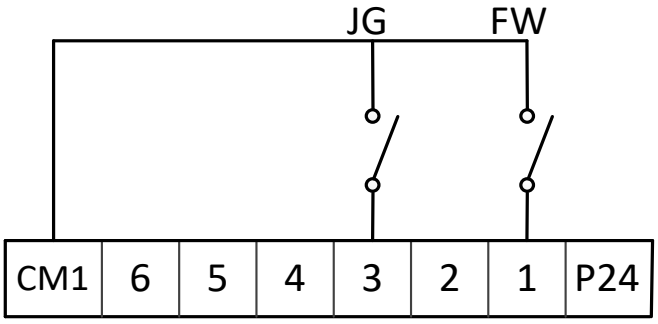
Multiple Speed	Code	Control Terminal				
		SW5	SW4	SW3	SW2	SW1
		CF4	CF3	CF2	CF1	FW
Multiple Speed 0	F01	OFF	OFF	OFF	OFF	ON
Multiple Speed 1	A11	OFF	OFF	OFF	ON	ON
Multiple Speed 2	A12	OFF	OFF	ON	OFF	ON
Multiple Speed 3	A13	OFF	OFF	ON	ON	ON
Multiple Speed 4	A14	OFF	ON	OFF	OFF	ON
Multiple Speed 5	A15	OFF	ON	OFF	ON	ON
Multiple Speed 6	A16	OFF	ON	ON	OFF	ON
Multiple Speed 7	A17	OFF	ON	ON	ON	ON
Multiple Speed 8	A18	ON	OFF	OFF	OFF	ON
Multiple Speed 9	A19	ON	OFF	OFF	ON	ON
Multiple Speed 10	A20	ON	OFF	ON	OFF	ON
Multiple Speed 11	A21	ON	OFF	ON	ON	ON
Multiple Speed 12	A22	ON	ON	OFF	OFF	ON
Multiple Speed 13	A23	ON	ON	OFF	ON	ON
Multiple Speed 14	A24	ON	ON	ON	OFF	ON
Multiple Speed 15	A25	ON	ON	ON	ON	ON



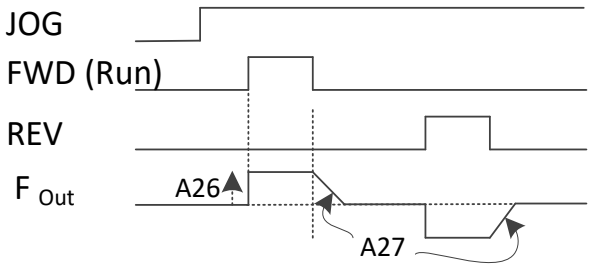
- **Set 6: Jogging Operation Command (JG)**

Jogging frequency is used to move/rotate the motor in small increment at low frequency.

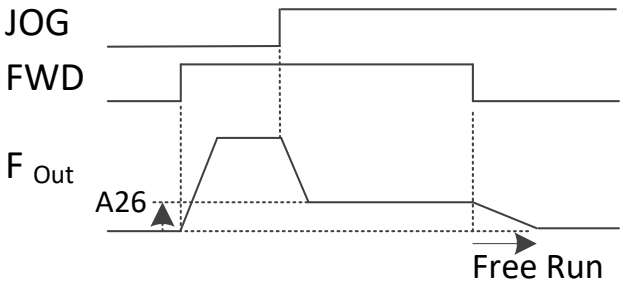
Code	Set Value	Description
A02	1	Run Command by Terminal Input
C01	0	Set Terminal 1 to FW Operation
C03	6	Set Terminal 3 to JG Operation
C07	0	Set Terminal 1 to Normally Open
		When shorted(Closed); FW Run, When Open, FW Stop
C09	0	Set Terminal 3 to Normally Open
A26	[0.5~10Hz]	Jog Frequency Setpoint
A27	[0,1,2]	Jog Stop Mode (0:Free Run, 1: Deceleration, 2: DC Braking)



[Example Jogging OperationFunction Terminal Setting]



[Jogging Operation Diagram1]



[Jogging Operation Diagram2]

- **Jogging operation(Communication)**

When the operation command is input through communication, JOG forward/reverse operation can be performed using special parameters.

Code	Set Value	Description
A02	2	Remote Operator-Communication
A26	[0.5~10Hz]	Jog Frequency Setpoint
A27	[0,1,2]	Jog Stop Mode (0:Free Run, 1: Deceleration, 2: DC Braking)

■ **FRAME**

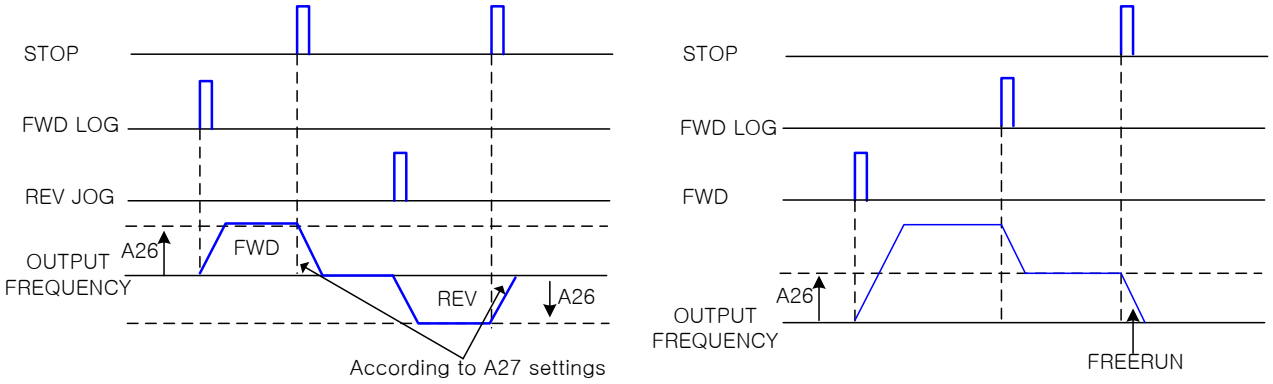
Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Reserved				JOG	RST	REV	FWD

Ex1)JOG FWD RUN FRAME

Communication number	Command	Parameter	Data	CRC
0x01	0x06	0x0002	0x0009	0xe80c

Ex2) JOG REV RUN FRAME

Communication number	Command	Parameter	Data	CRC
0x01	0x06	0x0002	0x000A	0Xa80d



Caution	
	If A26 (jogging frequency) is set to a value lower than b10 (starting frequency) or 0Hz, jogging operation does not operate. For reliable operation, check if the motor is stopped when changing with the [JG] function. Since jogging operation is a direct operation and tripping is easy, set A26 (jogging frequency setting) to 5Hz or less.

- **Set 8: 2 Stage Acceleration/Deceleration (2CH)**

By activating FRS command, second set of frequency acceleration and deceleration values can be selected.

Code	Set Value	Description
A02	1	Run Command by Terminal Input
C01	0	Set Terminal 1 to FW Operation
C05	6	Set Terminal 5 to 2CH Operation
C07	0	Set Terminal 1 to Normal Open
		When shorted(Closed); FW Run, When Open, FW Stop
C11	0	Set Terminal 5 to Normal Open
A54	[0.1~3000]	Acceleration Time 2
A55	[0.1~3000]	Deceleration Time 2
A56	0	Accel/Decel 2 Command Select to Teminal (if 1: use A57 & A58 F setpoint)
A57	User	Accel Time 2 Transition Frequency Setpoint
A58	User	Decel Time 2 Transition Frequency Setpoint

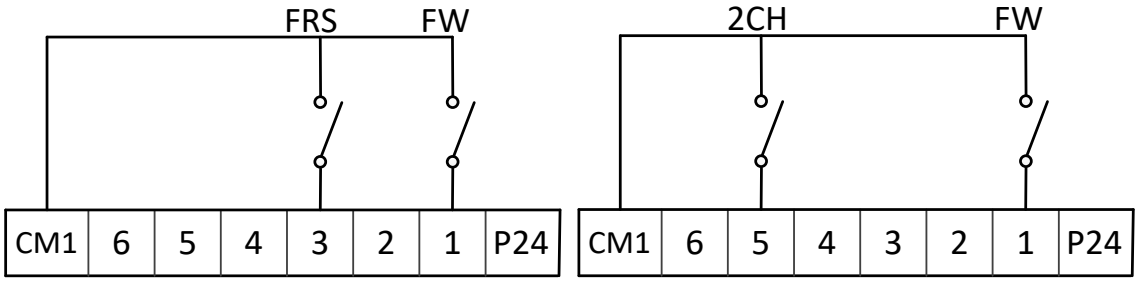
1. Set A54 (acceleration time 2) and A55 (deceleration time 2).

2. Depending on the setting of A56, you can drive in the following two ways.

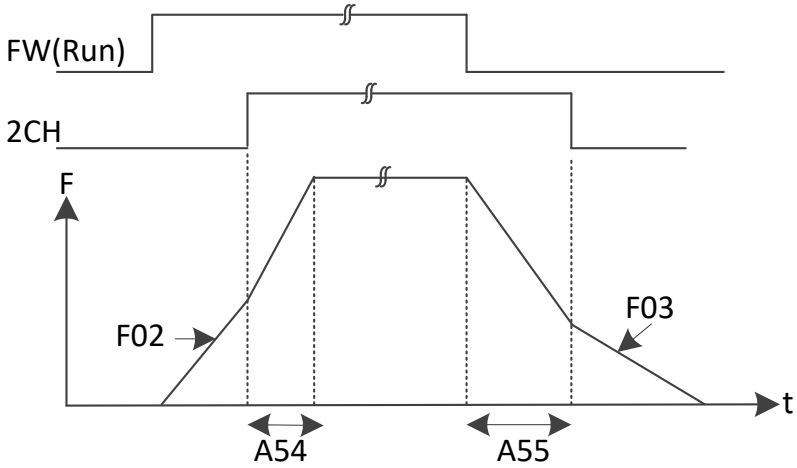
   1) In case A56 is set to “0”, it operates with 2 acceleration/deceleration when inputting the terminal block.
      ① Set A02 to “1 (control circuit terminal)”.
      ② Set “8(2CH, 2-step acceleration/deceleration command)” to the terminal you want to use among C01 ~ C06.

      The wiring in case 2-step acceleration/deceleration operation is set in terminal 5 is as follows. While the set terminal [2CH]-[CM1] is turned ON (short-circuited), it operates with the 2-step acceleration/deceleration time. When the terminal is turned OFF (opened), it returns to the original acceleration/deceleration time (acceleration time 1, deceleration time 1).
      (However, if “b contact” is set for C07~C12, OFF and ON are reversed.)

   2) In case A56 is set to “1”, it is accelerated and decelerated in 2 steps according to the switching frequency set in A57 and A58. (Refer to Section 6.3.11 2nd Acceleration/Deceleration Function Setting)



[Example 2CH Function Terminal Setting]

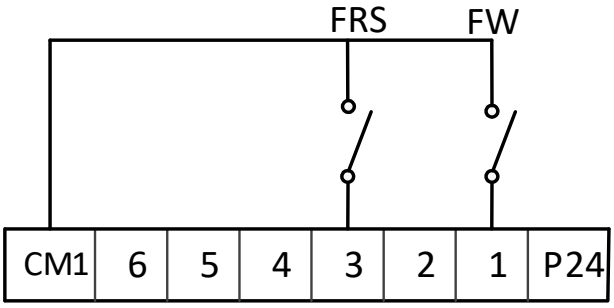


[2CH Operating Diagram]

- **Set 9: Free Run Stop Command (FRS)**

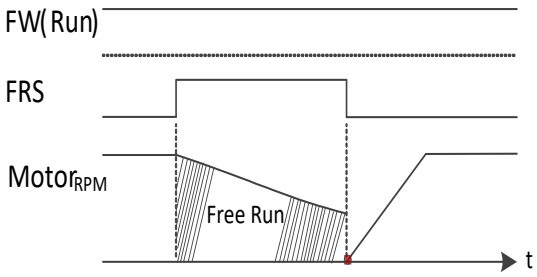
By activating FRS command, VFD stops the output and the motor coasts to stop.

Code	Set Value	Description
A02	1	Run Command by Terminal Input
C01	0	Set Terminal 1 to FW Operation
C03	9	Set Terminal 3 to FRS Operation
C07	0	Set Terminal 1 to Normal Open
		When shorted(Closed); FW Run, When Open, FW Stop
C09	0	Set Terminal 3 to Normal Open
b03	[0.1~10]	Delay Time to VFD Restart
b16	0	Restart Frequency Set to 0Hz on FRS Cancellation (1: Resume M-Fre)



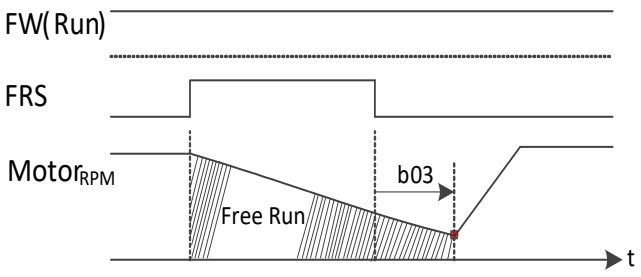
[Example FRS Function Terminal Setting]

i) When b16 = 0



[FRS Operating Diagram1]

i) When b16 = 1

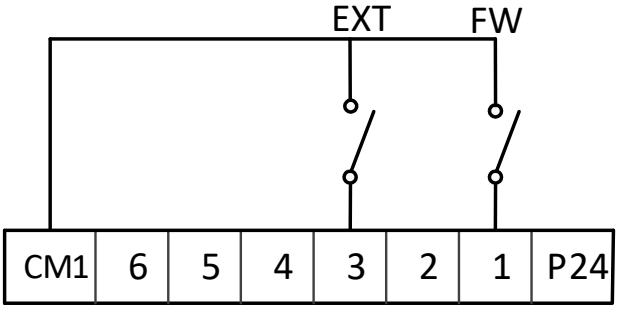


[FRS Operating Diagram2]

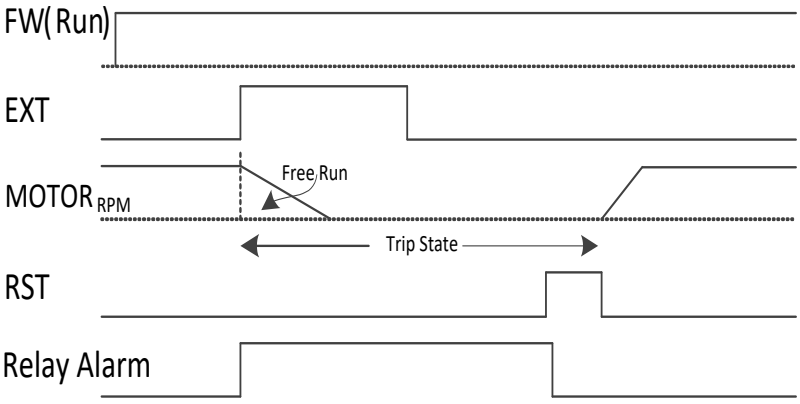
- **Set 10: External Trip 1 (EXT)**

By asserting a trip signal, it forces the VFD to stop and generates E12. Even when EXT becomes inactive by opened the switch, the VFD remains the trip state. Thus, activating reset signal or recycle the power must be done to clear the error state.

Code	Set Value	Description
A02	1	Run Command by Terminal Input
C01	0	Set Terminal 1 to FW Operation
C03	10	Set Terminal 3 to FRS Operation
C07	0	Set Terminal 1 to Normal Open
		When shorted(Closed); FW Run, When Open, FW Stop
C09	0	Set Terminal 3 to Normal Open



[Example EXT Function Terminal Setting]

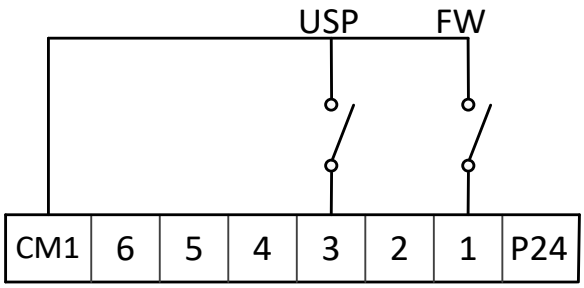


[EXT Operating Diagram]

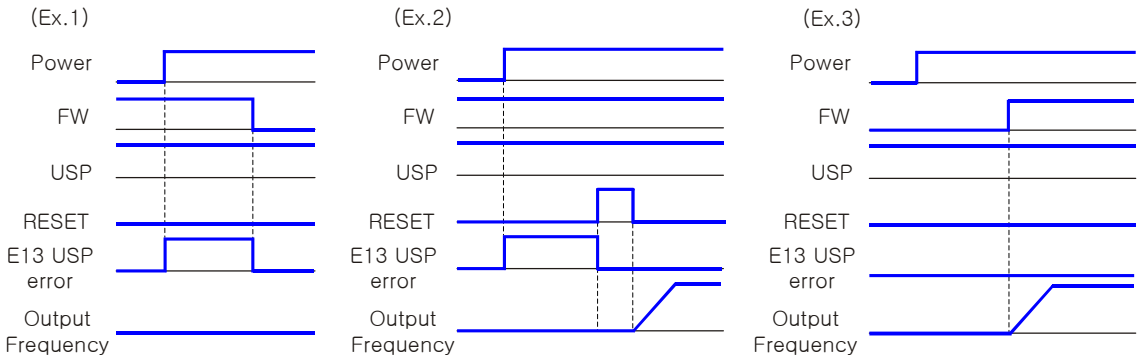
- **Set 11: Unintended Start Protection (USP)**

  USP function is to prevent the automatic start up at power on. If the Run(FW/RV) command is activated prior to the power up, as soon as the power is applied, the VFD starts to run immediately. If USP is enabled, the VFD would not run till VFD is reset.

Code	Set Value	Description
A02	1	Run Command by Terminal Input
C01	0	Set Terminal 1 to FW Operation
C03	11	Set Terminal 3 to USP Operation
C07	0	Set Terminal 1 to Normal Open
		When shorted(Closed); FW Run, When Open, FW Stop
C09	0	Set Terminal 3 to Normal Open



[Example USP Function Terminal Setting]

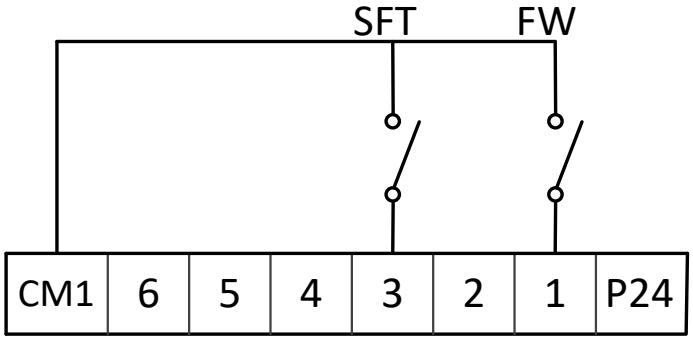


[USP Operating Diagram]

- **Set 12: Software Lock Function (SFT)**

  Software lock function disables all the parameter value editing except b09

Code	Set Value	Description
A02	1	Run Command by Terminal Input
C01	0	Set Terminal 1 to FW Operation
C03	12	Set Terminal 3 to SFT Operation
C07	0	Set Terminal 1 to Normal Open
		When shorted(Closed): FW Run, When Open: FW Stop
C09	0	Set Terminal 3 to Normal Open

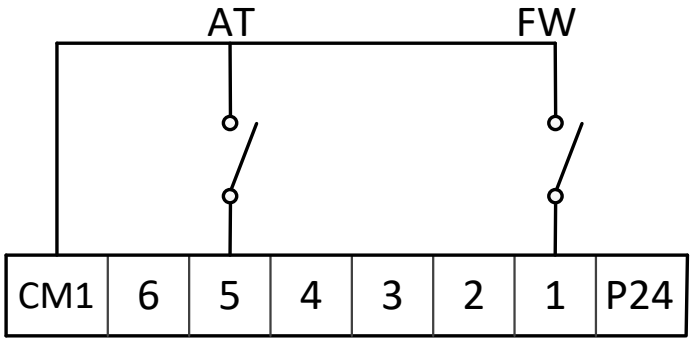


[Example SFT Function Terminal Setting]

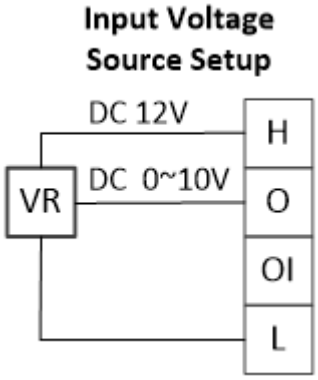
- **Set 13: Analog Input Current / Voltage Select (AT)**

  If Shorted: Select Current Source
  If Opened: Select Voltage Source

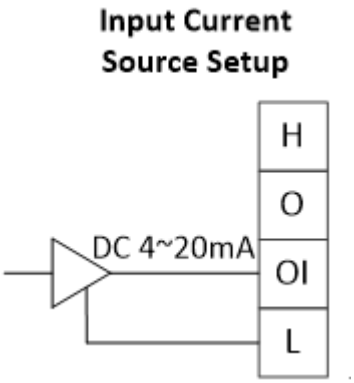
Code	Set Value	Description
A02	1	Run Command by Terminal Input
A01	1	Frequency Command by Terminal Input
C01	0	Set Terminal 1 to FW Operation
C05	13	Set Terminal 5 to AT Operation
C07	0	Set Terminal 1 to Normal Open
		When shorted(Closed), Select Current Source; When Open, Voltage Source
C11	0	Set Terminal 5 to Normal Open
Caution		
	* If A01 is programmed to 1, but AT is not assigned on the terminal, VFD uses internal algebraic sum of the voltage and the current inputs for the frequency value	



[Example AT Function Terminal Setting]



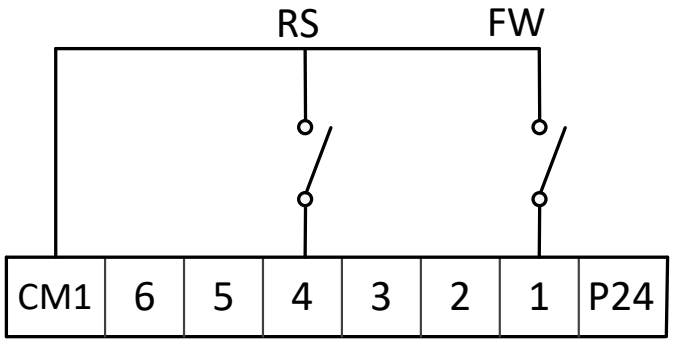
[Example Voltage input terminal setting]



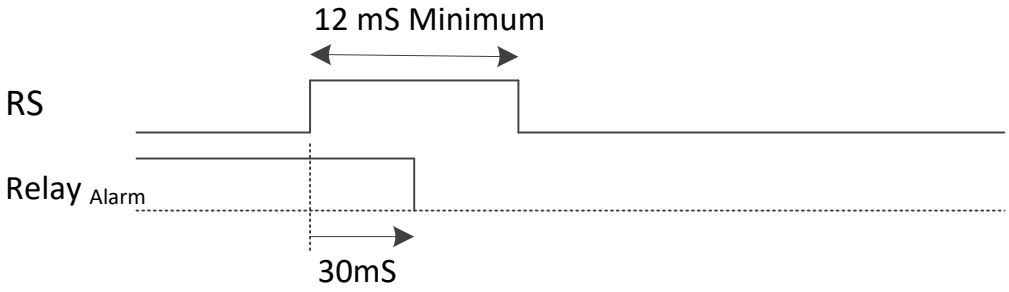
[Example Current input terminal setting]

- **Set 14: Reset (RS)**

Code	Set Value	Description
A02	1	Run Command by Terminal Input
C01	0	Set Terminal 1 to FW Operation
C04	14	Set Terminal 4 to RS Operation
C07	0	Set Terminal 1 to Normal Open
		When shorted(Closed): FW Run, When Open: FW Stop
C10	0	Set Terminal 4 to Normal Open
Danger 	*When Reset is asserted to clear the fault, if the RUN command is executed by FW/RV terminal set, the motor will immediately run to the speed. Be sure to set the RS after RUN command is disconnected in order to prevent	
Caution 	* The reset function operates in the rising edge section. If a new trip occurs in the reset-on state, the trip must be re-entered to release the trip. [RS]terminal OFF→ ON → OFF to turn off the alarm. When the power is turned OFF/ON, it returns to the state as if [RS] was input. If b29 is set to 0 or 1 and RST is hold longer than 4 second is continued to be ON, E60, communication error will be displayed. Reset by disconnect RS terminal to OFF or press STOP/RESET Key and resume VFD operation to normal. If b29 is set to 2 or 3 the reset action time does not cause the E60 communication error.	



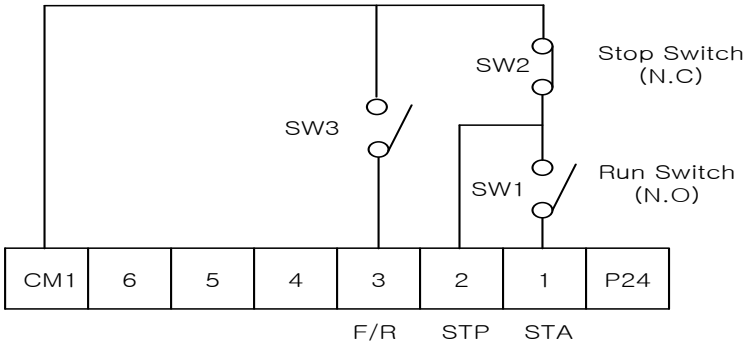
[Example RS Function Terminal Setting]



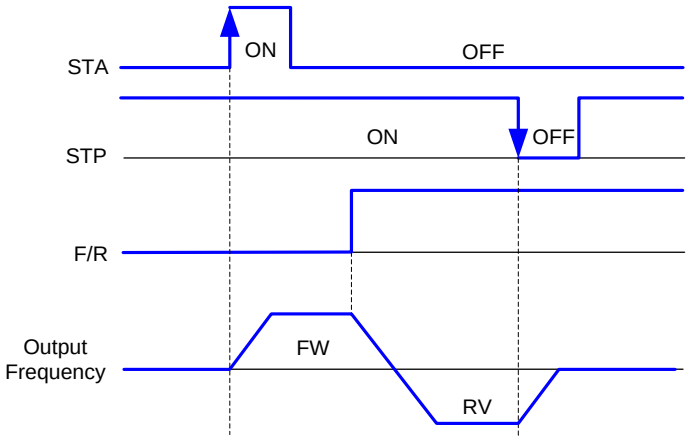
[RS Operating Diagram]

- **Set 15: Start (STA) 3 Wire Run/Stop Application**
- **Set 16: Keep (STP)**
- **Set 17: Forward / Reverse (F/R)**

Code	Set Value	Description
A02	1	Run Command by Terminal Input
C01	15	Set Terminal 1 to STA Operation
C02	16	Set Terminal 2 to STP Operation
C03	17	Set Terminal 3 to F/R Operation
C07	0	FW Operation: Terminal 1 to Normal Open
		When shorted(Closed): FW Run, When Open: FW Stop
C08	0	FW Operation: Terminal 2 to Normal Open
C09	0	FW Operation: Terminal 3 to Normal Open



[Example 3 Wire Input Function Terminal Setting]

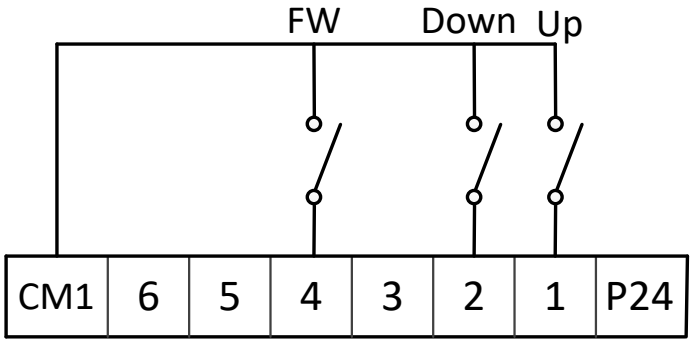


[3 Wire Input Operating Diagram]

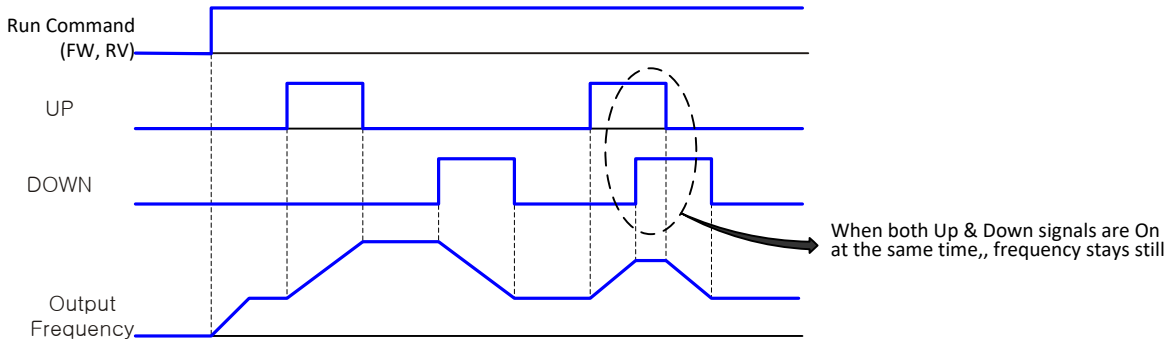
Caution: When the STP terminal is set, the functions of the FW terminal and RV terminal are invalid.

- **Set 18: Remote Control Up (UP)**
- **Set 19: Remote Control Down (DOWN)**

Code	Set Value	Description
A02	1	Run Command by Terminal Input
A01		Frequency Setting
C01	18	Set Terminal 1 to UP Operation
C02	19	Set Terminal 2 to Down Operation
C04	1	Set Terminal 3 to F/R Operation
C07	0	FW Operation: Terminal 1 to Normal Open
		When shorted(Closed): FW Run, When Open: FW Stop
C08	0	FW Operation: Terminal 2 to Normal Open
C28	0,1	UP/Down value saving selection
C29	0 ~ A04	Up/Down initial value setting
C30	0.1~3000.0s	Up/Down Target Frequency Acc/decel time setting
C31	0 ,1	Up/Down function selection
C32	0.00~400.00%	Up/Down value setting



[Example Up/Down Function Terminal Setting]



[Up/Down Operating Diagram]

- **C28 UP/DOWN Initial Value Saving**

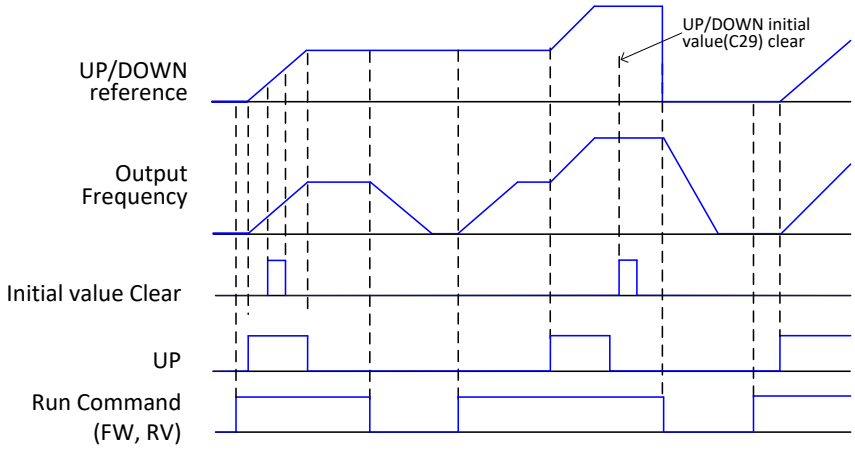
The user can use C28 to store the current up/down command frequency indicated on C32 as the initial up/down command frequency, which is stored when the inverter is turned off by cutting off the inverter power in the C28 On state.
When C28 is 0 the U/D Clear function does not clear the up/down command frequency initial value, the up/down command frequency initial value does not clear even in the inverter Run state.

- 0: The initial value of the UP/DN command frequency is used as the C29 setting value.
- 1: Set the current UP/DN command frequency to C29 as the initial value.
- The initial value is 0.

- **C29 UP/DOWN Initial Value Setting**

- Range: 0.00 ~ Max Frequency(A04) in 0.01 Hz
- The initial value is 0.00 Hz

The user can set the 'up/down initial command frequency' to the maximum A04 value using C29.
It can be used as the 'up/down initial command frequency' when applying the inverter for the first time. If C28 is 0, the 'up/down initial command frequency' setting is maintained when the power is completely cut off and re-applied.
You can change the value when C31 is 1 and C28 is 0.
If C28 is in the 1 state, it displays the value of C32 and cannot change the value.



[Up/Down Reference Operating Diagram]

- **C30 UP/DOWN Target Frequency Arriving Time**

- Range: 0.1 ~ 3000 Sec in 0.1 Sec
- The initial value is 10.0 seconds.

The user can set the 'up/down command frequency increase/decrease time' using C30.
If the time is long, the command frequency will increase or decrease slowly, and if it is short, it will increase or decrease rapidly.

- **C31 Up/Down function selection**

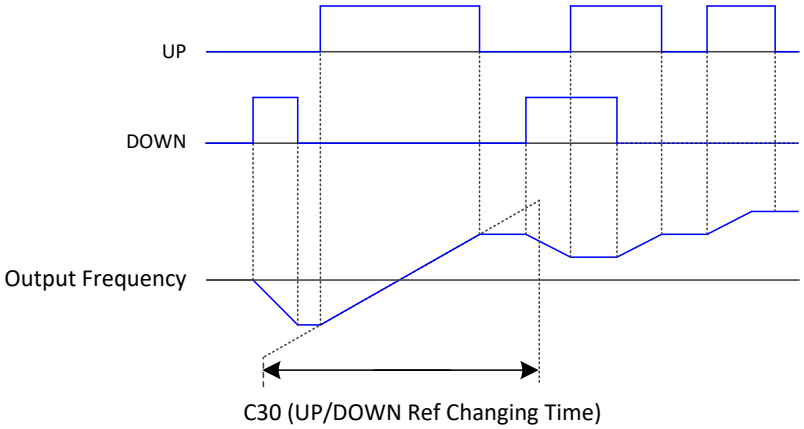
- 0 – Disable the up/down function.
- 1 - Use the up/down function.

The user can check the status of the up/down function on and off using C31.
When both Up and Down functions are set in C01 to C06, C31 automatically becomes 1.

- **C32 Up/Down value setting**

▪ You can check from 0.00 to A04 (maximum frequency).

The user can check the 'current up/down command frequency' using C32.
Increase or decrease based on the initial value set in C29, the command frequency rises to a maximum of A04.

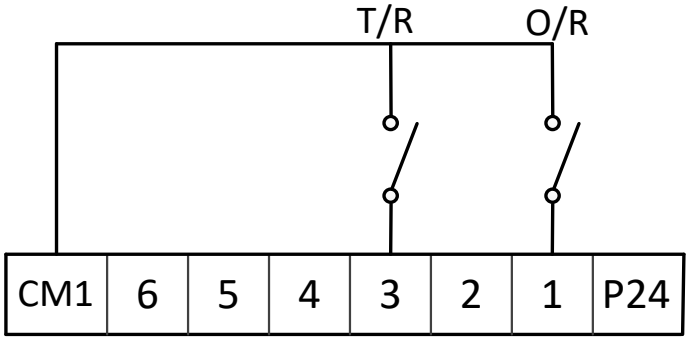


[Up/Down Ref Change Time Operating Diagram]

- **Set 20: Local Keypad Override (O/R)**
- **Set 21: Local Terminal Override (T/R)**

Even when the frequency command (A01) and run command (A02) are set for VFD operation, Keypad (or local terminal input) can override these commands by activating these terminal bits.

Code	Set Value	Description
C01	20	Set Terminal 1 to O/R (Keypad Override)
C03	21	Set Terminal 3 to T/R (Terminal Override)
C07	0	FW Operation: Terminal 1 to Normal Open
		When shorted(Closed): FW Run, When Open: FW Stop
C09	0	FW Operation: Terminal 3 to Normal Open



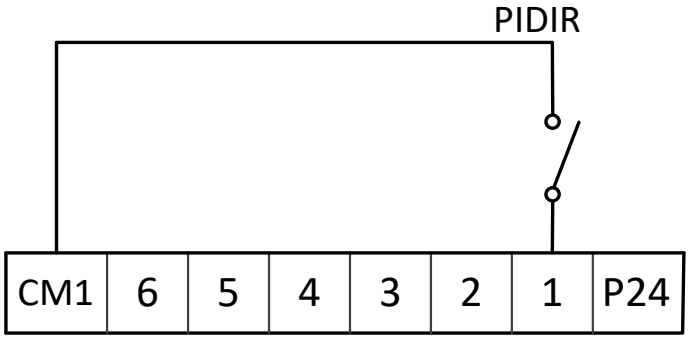
[Example O/R, T/R Function Terminal Setting]

Caution: If O/R and T/R switched on simultaneously, O/R has a priority than T/R.
If switched on during VFD running,
the VFD will stop and then operate by given command.

- **Set 22: PID Integral Reset Override (PIDIR)**

  Even when the PID controller is activated, PIDIR can force resetting an accumulated integral term.

Code	Set Value	Description
C01	22	Set Terminal 1 to PIDIR
C07	0	FW Operation: Terminal 1 to Normal Open
		When shorted(Closed): FW Run, When Open: FW Stop
A70	1 or 2	PID Control or F/F Control

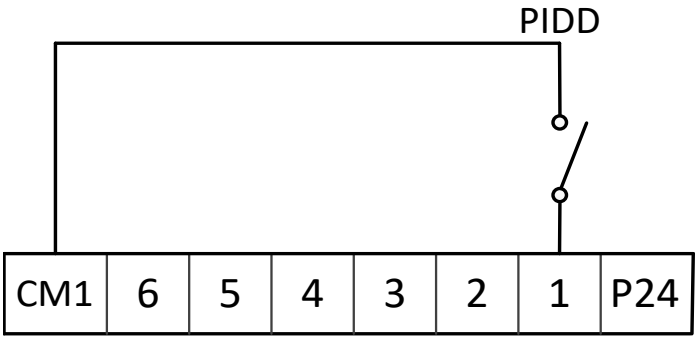


[Example PIDIR Function Terminal Setting]

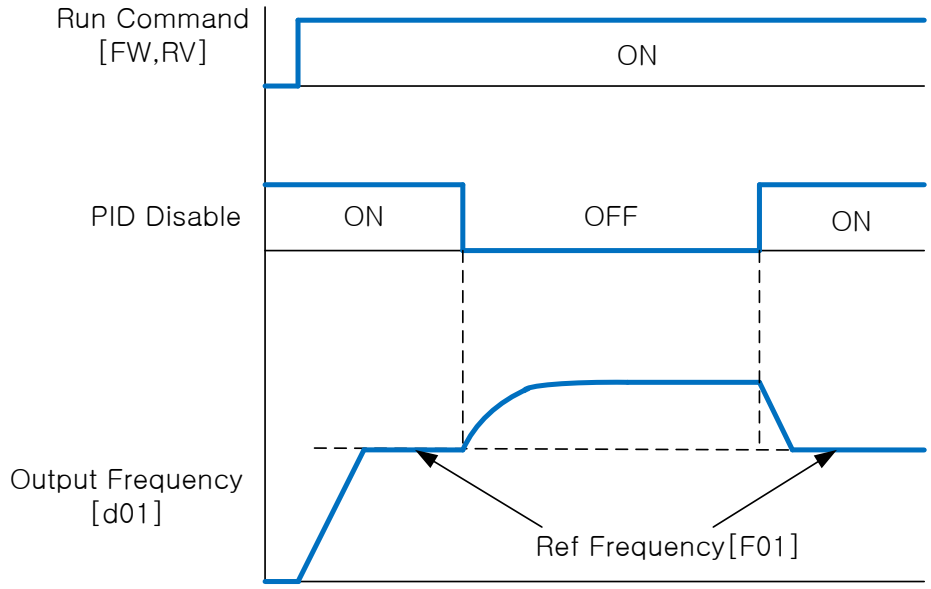
- **Set 23: PID Disabled (PIDD)**

  Even when the PID controller is activated, PIDD can override disable the function. When PIDD becomes activated, VFD Frequency setpoint follows the value in A01.

Code	Set Value	Description
C01	22	Set Terminal 1 to PIDIR
C07	0	FW Operation: Terminal 1 to Normal Open
		When shorted(Closed): FW Run, When Open: FW Stop
A70	1 or 2	PID Control or F/F Control
A01		Frequency Command
F01	60	Output Frequency Setpoint



[Example PIDD Function Terminal Setting]

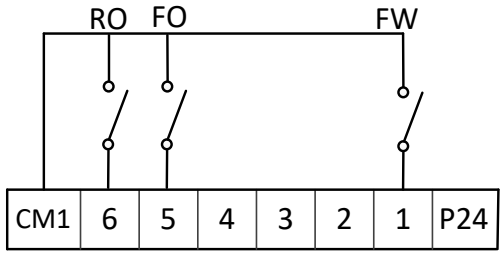


[PID Disable Operating Diagram]

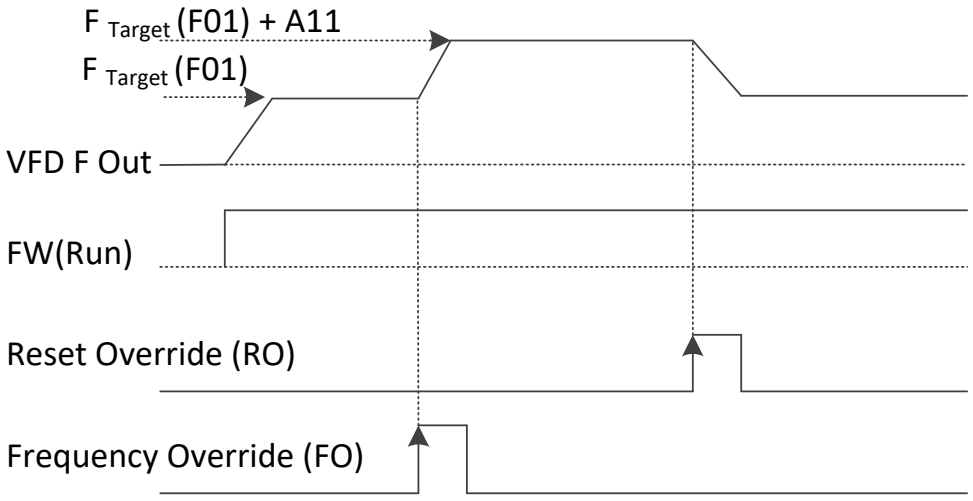
- **Set 24: Frequency Override (FO)**
- **Set 25: Reset Override (RO)**

Frequency Override is a manual frequency adder enables adding a frequency value to the target frequency setpoint. Since it is an edge triggered signal, it stays activated till Reset Override signal is provided. Once RO is activated, VFD frequency output follows back to the target value in F01.

Code	Set Value	Description
A02	1	Run command by Terminal Input
C01	0	Set Terminal 1 to Forward Run
C05	24	Set Terminal 5 to Manual Frequency Adder
C06	25	Set Terminal 6 to Reset Override
C07	0	Terminal 1 to Normal Open
		When Shorted(Closed): FW Run, When Open: FW Stop
C11	0	Terminal 5 to Normal Open
C12	0	Terminal 6 to Normal Open
F01	[0.5 ~ Max Hz]	Output Frequency Setting
A11	[0.5 ~ F04 Hz]	1st Multi Speed Frequency (Shared with this function)



[Example FO, RO Function Terminal Setting]

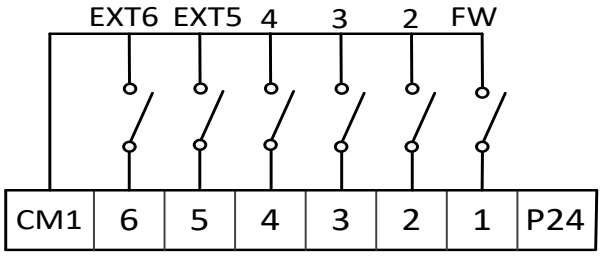


[FO, RO Operating Diagram]

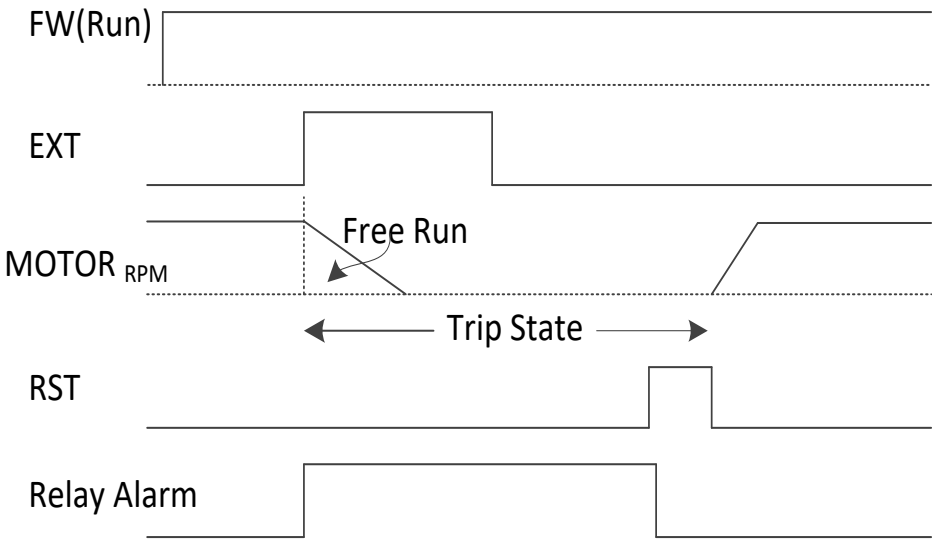
- **Set 26: External Trip 2 (EXT2)**
- **Set 27: External Trip 3 (EXT3)**
- **Set 28: External Trip 4 (EXT4)**
- **Set 29: External Trip 5 (EXT5)**
- **Set 30: External Trip 6 (EXT6)**

In addition to External Trip in Set 10, five more external trip signals are provided for flexible control of corresponding function.

Code	Set Value	Description
C01	1	Run command by Terminal Input
C02	26	Set Terminal 2 to External Trip 2
C03	27	Set Terminal 3 to External Trip 3
C04	28	Set Terminal 4 to External Trip 4
C05	29	Set Terminal 5 to External Trip 5
C06	30	Set Terminal 6 to External Trip 6
C07~C12	0	Terminal 1~6 Normal Open
		When Shorted(Closed): FW Run, When Open: FW Stop



[Example EXT2~6 Function Terminal Setting]



[EXT2~6 Operating Diagram]

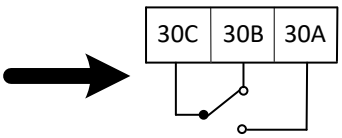
OUTPUT

- **C13 Output Relay 1 (30A, 30B, 30C)**

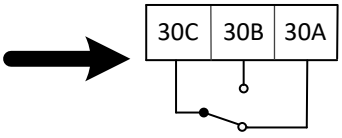
Program one of following output command

Value	Name	Function	Comment
0	RUN	VFD Run Signal	C15 Initial value
1	FA1	Frequency Arrival 1	C14 Initial value
2	FA2	Frequency Arrival 2	
3	OL	Overload Warning Signal	
4	OD	Output Deviation Excess for PID Control	
5	AL	Fault Signal	C13 Initial value
6	MO	Operation by Communication	
7	SOL	System Overload Detection	
8	SUL	System Underload Detection	
9	SOL/SUL	System Overload/Underload Detection	
10	AI Loss	Analog Input Loss Detection	
11	KEY_Loss	Keypad Information Loss Detection	
12	BRK	Control external braking	

If C13 = 0: When VFD is not Running
If C13 = 1: When Frequency is not Arrival 1
If C13 = 2: When Frequency is not Arrival 2
If C13 = 3: When Overload condition isn't occurred
If C13 = 4: When PID Error does not Exceed the Set Level
If C13 = 5: No fault condition is occurred
If C13 = 6: When it is not operated by modbus
If C13 = 7: When System Overload is not detected
If C13 = 8: When System Underload is not detected
If C13 = 9: When System Overload and Underload are not detected



If C13 = 0: When VFD is Running
If C13 = 1: When Frequency is at Arrival 1
If C13 = 2: When Frequency is at Arrival 2
If C13 = 3: When Overload condition occurred
If C13 = 4: When PID Error does Exceed the Set Level
If C13 = 5: Fault condition is occurred
If C13 = 6: When it is operated by modbus
If C13 = 7: When System Overload is detected
If C13 = 8: When System Underload is detected
If C13 = 9: When System Overload and Underload are detected
If C13 = 10: When Analog Input Loss Detection
If C13 = 11: When Keypad Information Loss Detection
If C13 = 12: When Control external braking



- **C14 Output Relay 2 (11-CM2)**
- **C15 Output Relay 3 (12-CM2)**

Program one of following output command below. These intelligent relay out terminals can be configured to Form A or B type by programming C16 and C17 to 0 or 1.

- 0: RUN VFD Run Signal
- 1: FA1 Frequency Arrival 1
- 2: FA2 Frequency Arrival 2
- 3: OL Overload Warning Signal
- 4: OD Output Deviation Excess for PID Control
- 5: AL Fault Signal
- 6: COM Operation by Communication
- 7: SOD System Overload Detection
- 8: SUD System Underload Detection
- 9: SOD/SUD System Overload/Underload Detection
- 10: AI_LOSS Analog Input Loss Detection
- 11: KEY_LOSS Keypad Information Loss Detection
- 12: BRK Control external braking

- **C16~C17Output Relay 2, 3 (11-CM2, 12-CM2) Mode**

- 0: Normally Open (NO) – Form A Configuration
- 1: Normally Closed (NC) – Form B Configuration

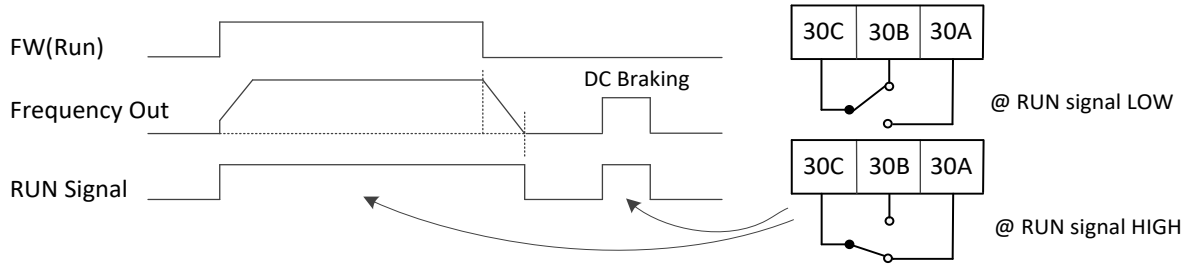
Contact specification

Maximum	Minimum
AC250V, 2.5A(Resistor load), 0.2A(Inductive load)	AC100V, 10mA
DC30V, 3.0A(Resistor load), 0.7A(Inductive load)	DC5V, 100mA

- **Set 0: RUN**

Even when the PID controller is activated, PIDD can override disable the function. When PIDD becomes activated, VFD Frequency setpoint follows the value in A01.

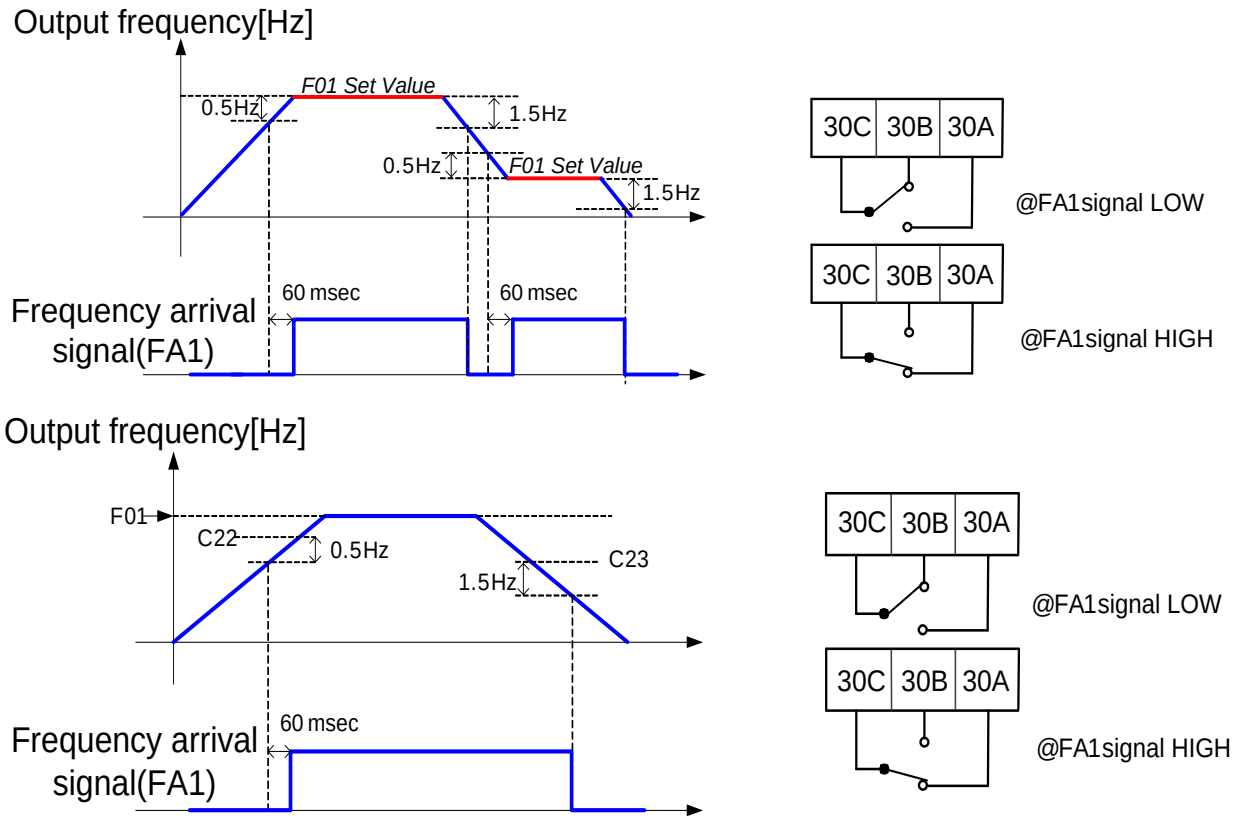
Code	Set Value	Description
C13	0	Set Intelligent Relay Out 1 Terminal to RUN Mode
C14	0	Set Intelligent Single Pole Single Throw (SPST) Relay Out Terminal to RUN Mode
C16	0	Set C14 to Normally Open to Form A configuration
		If set to 1, Form B configuration (Normally Closed)



- **Set 1: Frequency Arrival Signal 1 (FA1)**
- **Set 2: Frequency Arrival Signal 2 (FA2)**

Frequency Arrival signals indicate if the VFD output frequency reaches the set frequency specified in F01. FA1 (FA2) becomes triggered active from 0.5Hz lower set frequency value during acceleration and 1.5Hz lower during deceleration. But there is 60mS of delay time from the beginning of its activation.

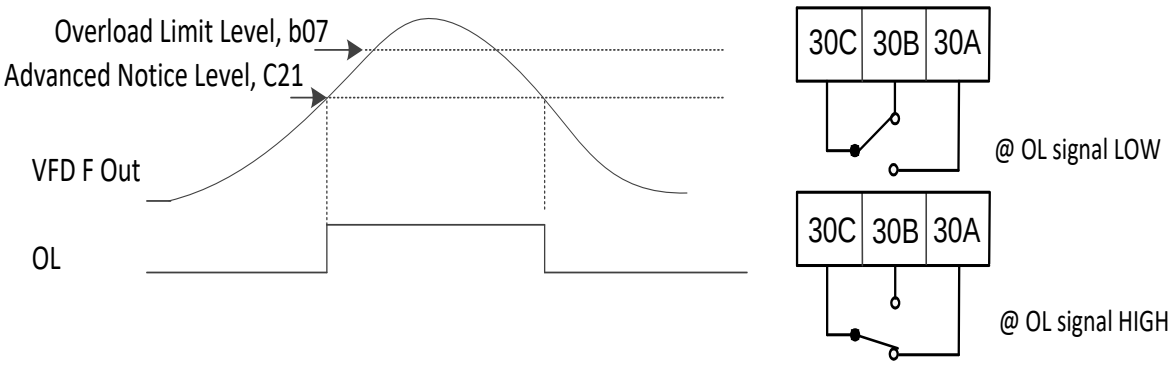
Code	Set Value	Description
C13	1	Set Intelligent Relay Out 1 Terminal to FA1
C15	0	Set C13 to Normally Open to Form A configuration
		If set to 1, Form B configuration (Normally Closed)
F01	0~ Max F	VFD Out Target Frequency
C22	[0 ~ A04] Hz	Target Frequency Setpoint during Acceleration for Frequency Arrival Signal
C23	[0 ~ A04] Hz	Target Frequency Setpoint during Deceleration for Frequency Arrival Signal



- **Set 3: Overload Advanced Notice Signal (OL)**

  Before the VFD becomes overload, iMASTER C1 generates an advanced warning signal to prevent any damage by the excessive output current. Overload detection circuit is designed to operate during powered motor operation and regenerative braking operation. The OL signal becomes ACTIVE High when the output current exceeds the setpoint programmed in C21, Overload Advance Notice Signal Setting

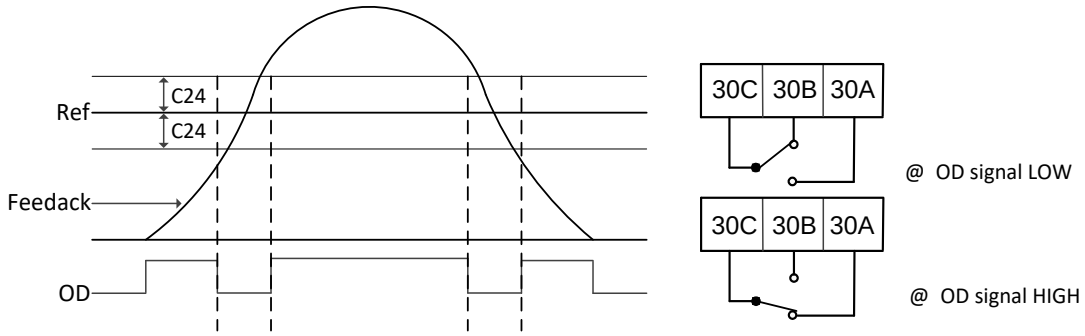
Code	Set Value	Description
C13	3	Set Intelligent Relay Out 1 Terminal to OL
C16	0	Set C13 to Normally Open to Form A configuration
		If set to 1, Form B configuration (Normally Closed)
C21	[10~200] %	Overload Advanced Notice Signal Setting; % x VFD rated current



- **Set 4: Output Deviation Excess for PID Control (OD)**

  The PID loop error is defined as the magnitude of the difference between the set point and process variable. When the error magnitude exceeds the value of C24, the OD terminal signal turns on

Code	Set Value	Description
C13	3	Set Intelligent Relay Out 1 Terminal to OD
C16	0	Set C13 to Normally Open to Form A configuration
		If set to 1, Form B configuration (Normally Closed)
C24	[0.0~100] %	PID Deviation level Setting



- **Set 5: Alarm Signal (AL)**

The inverter fault signals is active when a fault has occurred

Code	Set Value	Description
C13	3	Set Intelligent Relay Out 1 Terminal to AL
C16	0	Set C13 to Normally Open to Form A configuration
		If set to 1, Form B configuration (Normally Closed)

- **Set 6: Operation by Communication (COM)**

The digital outputs can be controlled by modbus communication

Parameter	Address	Description
Digital Output (Relay Output)	0x1001	Refer to below bit table 0: Stop Write Command has to set C13~C16 = 6

Digital Output Bit Table

1st byte

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Reserved							

2nd byte

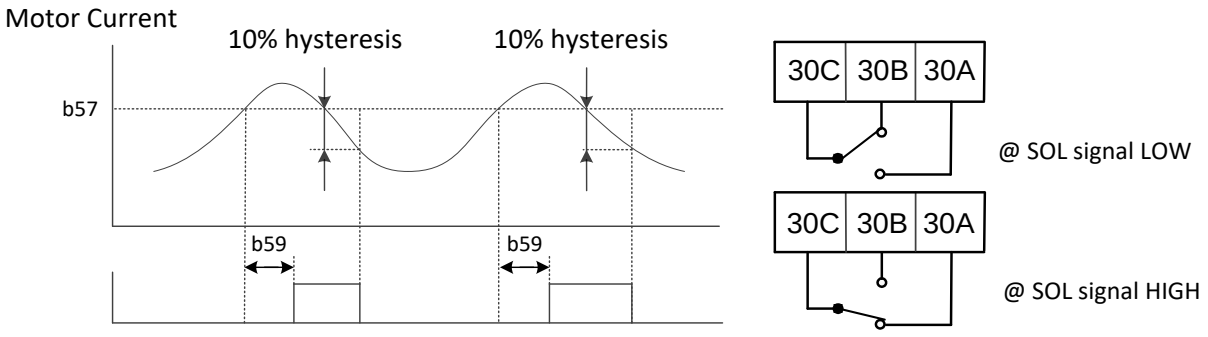
Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Reserved					30A~C	12~CM2	11~CM2

- **Set 7: System Overload Detection (SOL)**

The inverter System Overload is active by b57 level

Code	Set Value	Description
C13	7	Set Intelligent Relay Out 1 Terminal to SOL
C16	0	Set C13 to Normally Open to Form A configuration
		If set to 1, Form B configuration (Normally Closed)
b56	1 or 4 or 6	System Overload Detection or Detection with Fault (E23)
b57	[20~200] %	System Overload Detection Level

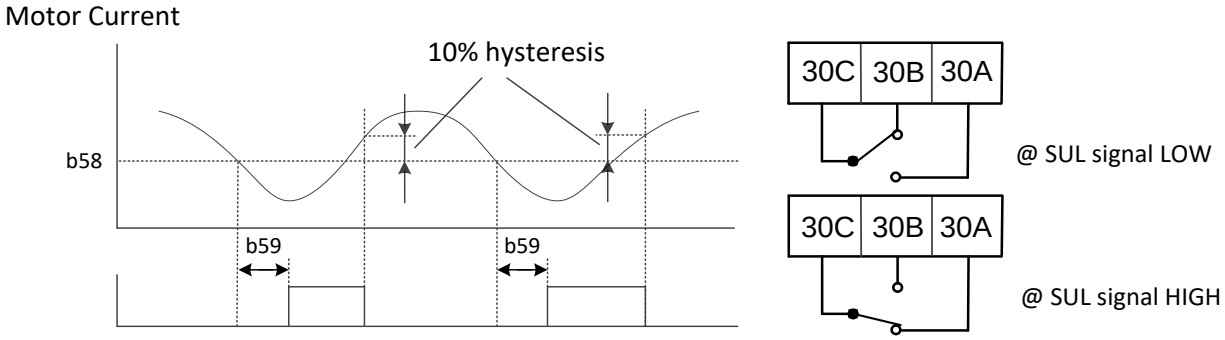
System Overload Detection



- **Set 8: System Underload Detection (SUL)**
  The inverter System Underload is active by b58 level

Code	Set Value	Description
C13	8	Set Intelligent Relay Out 1 Terminal to SUL
C16	0	Set C13 to Normally Open to Form A configuration
		If set to 1, Form B configuration (Normally Closed)
b56	2 or 5 or 6	System Underload Detection or Detection with Fault (E24)
b58	[20~200] %	System Underload Detection Level

System Underload Detection



- **Set 9: System Overload/Underload Detection (SOL/SUL)**

  The inverter System Overload/Underload is active by the each(b57, b58) level

Code	Set Value	Description
C13	9	Set Intelligent Relay Out 1 Terminal to SOL/SUL
C16	0	Set C13 to Normally Open to Form A configuration
		If set to 1, Form B configuration (Normally Closed)
b56	6	System Underload/Overload Detection with Fault (E23, E24)
b57	[20~200] %	System Underload Detection Level
b58	[20~200] %	System Underload Detection Level

- **Set 10: Analog Input Loss Detection (AI_LOSS)**

  The inverter System Analog Input Loss detection is active by the each(C36~C39) value

Code	Set Value	Description
C13	10	Set Intelligent Relay Out 1 Terminal to AI_LOSS
C16	0	Set C13 to Normally Open to Form A configuration
		If set to 1, Form B configuration (Normally Closed)
C36	1	Loss frequency (50%) (Less than 50% of A07)
C37	2	Selection of run command when speed losing(Deceleration stop)
C38	[0~120] Sec	Waiting time in case of frequency command loss
C39	[0~A04] Hz	Frequency setting in case of analog command loss

- **Set 11: Keypad Information Loss Detection (KEY_LOSS)**

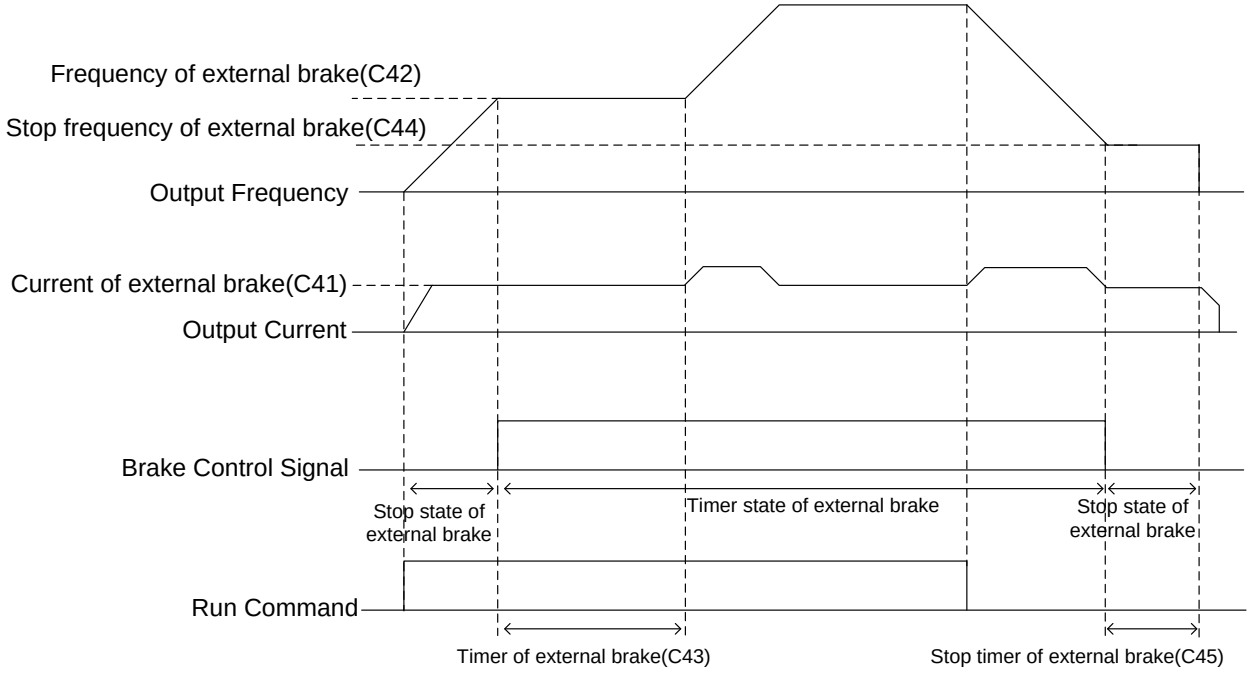
  The inverter Keypad Information Loss detection is active by the each(C33~C35) value

Code	Set Value	Description
C13	11	Set Intelligent Relay Out 1 Terminal to KEY_LOSS
C16	0	Set C13 to Normally Open to Form A configuration
		If set to 1, Form B configuration (Normally Closed)
C33	[0~6000] Sec	Decel time at fault occur
C34	1	Selection of running state when keypad connection failed(Stop)
C35	1	Selection of keypad detection(Abnormal move detection)

- **Set 12: Control external braking (BRK)**

The inverter external braking Control is active by the each(C41~C45) value

Code	Set Value	Description
C13	12	Set Intelligent Relay Out 1 Terminal to BRK
C16	0	Set C13 to Normally Open to Form A configuration
		If set to 1, Form B configuration (Normally Closed)
C41	[0~200] %	Current of external brake
C42	[0~25] Hz	Frequency of external brake
C43	[0~5] Sec	Timer of external brake
C44	[0~25] Hz	Stop frequency of external brake
C45	[0~5] Sec	Stop timer of external brake



- **C18 FM Output Setting**

Program what output performance to be monitored from following selections

- 0: Output Frequency Monitor
- 1: Output Current Monitor
- 2: Output Voltage Monitor
- 3: Output Power Monitor
- 4: Output Torque Monitor
- 5: Operation by Communication
- 6: DC voltage

◆ **Set 0: Output Frequency Monitor**

Monitor the VFD output frequency value. The highest analog output value is the maximum frequency value. The indicator accuracy after the adjustment is about +/- 5%.

◆ **Set 1: Output Current Monitor**

Monitor the VFD output current value. The highest analog value is the 200% of rated VFD current. The indicator accuracy after the adjustment is about +/- 10%.

◆ **Set 2: Output Voltage Monitor**

Monitor the VFD output voltage value. The highest analog value is the 100% of rated VFD voltage out. The indicator accuracy after the adjustment is about +/- 10%.

◆ **Set 3: Output Power Monitor**

Monitor the VFD output power value. The highest analog value is the 200% of rated VFD power out. The indicator accuracy after the adjustment is about +/- 10%.

◆ **Set 4: Output Torque Monitor**

Monitor the VFD output torque value. The highest analog value is the 150% of rated VFD output torque. The indicator accuracy after the adjustment is about +/- 10%

FM output	Torque
0V	-150%
5V	0%
10V	+150%

◆ **Set 5: Operation by Communication**

It can control FM output value (0~10V) by Modbus command

Parameter	Address	Description
Analog Output (FM)	0x1004	0 ~ 10000 (0.1 scale, 0 ~ 10V, 0 ~ 100%) Write Command has to set C18 = 5

Digital Output Bit Table

1st byte

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Reserved							

2nd byte

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Reserved					30A~C	12~CM2	11~CM2

◆ **Set 6: DC voltage Monitor**

Monitor the VFD DC voltage value. The highest analog value is the 100%(400/800Vdc) of rated VFD DC voltage. The indicator accuracy after the adjustment is about +/- 10%.

- **C19 FM Gain**

▪ Range: 0.0 ~ 250.0 % in 0.1
Program the gain factor to FM motoring setting

- **C20 FM Offset**

▪ Range: -3.0 ~10.0 % in 0.1
Program the offset factor to FM monitoring setting

- **C21 Motor Overload Alarm**

▪ Range: 10.0 ~200.0 % in 0.1
Program a level of the rated motor current

- **C22 FA2 SetPoint at Acceleration**

▪ Range: 0.00 ~ A04 Hz in 0.01
Program the frequency arrival threshold during acceleration

- **C23 FA2 SetPoint at Deceleration**

▪ Range: 0.00 ~A04 Hz in 0.01
Program the frequency arrival threshold during deceleration

- **C24 PID Error Tolerance**

▪ Range: 0.0 ~100.0 % in 0.1
Program the allowable PID loop error magnitude

- **C25 AMI Output Setting**

Program what output performance to be monitored from following selections

- 0: Output Frequency
- 1: Output Current
- 2: Output Voltage
- 3: Output Power
- 4: Output Torque Monitor
- 5: Operation by Communication
- 6: DC voltage

◆ **Set 0: Output Frequency Monitoring**
Monitor the VFD output frequency value. The highest analog output value is the maximum frequency value. The indicator accuracy after the adjustment is about +/- 5%.

◆ **Set 1: Output Current Monitoring**
Monitor the VFD output current value. The highest analog value is the 200% of rated VFD current. The indicator accuracy after the adjustment is about +/- 10%.

◆ **Set 2: Output Voltage Monitoring**
Monitor the VFD output voltage value. The highest analog value is the 100% of rated VFD voltage out. The indicator accuracy after the adjustment is about +/- 10%.

◆ **Set 3: Output Power Monitoring**
Monitor the VFD output power value. The highest analog value is the 200% of rated VFD power out. The indicator accuracy after the adjustment is about +/- 10%

◆ **Set 4: Output Torque Monitor**

Monitor the VFD output torque value. The highest analog value is the 150% of rated VFD output torque. The indicator accuracy after the adjustment is about +/- 10%

AMI output	Torque
4mA	-150%
12mA	0%
20mA	+150%

◆ **Set 5: Operation by Communication**

It can control AMI output value(4~20mA) by Modbus command

Parameter	Address	Description
Analog Output (AMI)	0x1005	0 ~ 10000, (0.1 scale, 4 ~ 20mA, 0 ~ 100% Write Command has to set C25 = 5

Digital Output Bit Table

1st byte

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Reserved							

2nd byte

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Reserved					30A~C	12~CM2	11~CM2

◆ **Set 6: DC voltage Monitor**

Monitor the VFD DC voltage value. The highest analog value is the 100%(400/800Vdc) of rated VFD DC voltage. The indicator accuracy after the adjustment is about +/- 10%.

- **C26 AMI Gain**

▪ Range: 0.0 ~ 250.0 % in 0.1

Program the gain factor to AMI motoring setting

- **C27 AMI Offset**

▪ Range: -99.9 ~100.0 % in 0.1

Program the offset factor to AMI monitoring setting

- **C46 Change Parameter check**

The user can check the changed function code (based on the initial value) by using the C46 code.
If you enter 1 in the C46 code, only the changed function code is displayed, and you can check the changed function code with the operator up/down buttons.The displayed function codes can be changed directly.

▪ 0: Disabled
▪ 1: Enabled

6.6 H Group Parameters

iMASTER C1 VFD offers Sensorless Vector control, enabling high starting torque and high precision operations. Motor data required for Sensorless Vector control design can be selected from standard motor data or auto-tuning algorithm. If VFD size is more than twice the motor size, the required torque characteristics or speed control characteristics are not well controlled.

- **H01 Auto Tuning**

  - 0: Disabled
  - 1: Enabled

  Program to enable auto tuning function. Motor parameters are calculated using the internal auto tuning algorithm and automatically set for Sensorless Vector control design.
  - ❖ Related Parameters: A31 (2: Sensorless Vector Control)

- **H02 Motor Data Select**

  - 0: Standard Motor Data
  - 1: Auto Tuning Data

  Program to select between standard motor data and auto tuned motor data.
  - ❖ Related Parameters:

- **H03 Motor Capacity**

0:MOT_004LF	12:MOT_004HF	24:MOT_370HF
1:MOT_007LF	13:MOT_007HF	25:MOT_450HF
2:MOT_015LF	14:MOT_015HF	26:MOT_550HF
3:MOT_022LF	15:MOT_022HF	27:MOT_750HF
4:MOT_037LF	16:MOT_037HF	28:MOT_900HF
5:MOT_055LF	17:MOT_055HF	29:MOT_1100HF
6:MOT_075LF	18:MOT_075HF	30:MOT_1320HF
7:MOT_110LF	19:MOT_110HF	31:MOT_1600HF
8:MOT_150LF	20:MOT_150HF	32:MOT_2200HF
9:MOT_185LF	21:MOT_185HF	33:MOT_2800HF
10:MOT_220LF	22:MOT_220HF	34:MOT_3500HF
11:MOT_300LF	23:MOT_300HF	35:MOT_3800HF

  Program the corresponding iMASTER C1 model used for the current application.
  - ❖ Related Parameters:

- **H04 Motor Poles Setting**

  - 2~48
  - 2 Poles for 3600 RPM (60 Hz), 3000 RPM (50 Hz)
  - 4: 4 Poles for 1800 RPM (60 Hz), 1500 RPM (50 Hz)
  - 48: 48 Poles for 150 RPM (60 Hz), 125 RPM (50 Hz)

  Program a number of poles to the corresponding motor used with the VFD.
  - ❖ Related Parameters:

- **H05 Motor Rated Current**

  - Range: 0.1 ~ 800.0 A in 0.1 A

  Program a rated current off of the motor nameplate (Motor FLA)

  - Related Parameters:

- **H06 Motor Flux Current**

  - Range: 0.1 ~ 400.0 A in 0.1 A

  Program the no load (flux) current value. Not all motors will have this information on the nameplate.

  - Related Parameters:

- **H07 Motor Rated Slip**

  - Range: 0.01 ~ 20.0 Hz in 0.1 Hz

  Program the slip percent of the motor rated nameplate rpm.
  ie- [(1800 rpm – 1750 rpm)] * (4pole/120)= 1.67Hz

  - Related Parameters:

- **H08 Motor Resistance R1**

  - Range: 0.1 ~ 3000.0 mOhms in 0.1 mOhms

  Hyundai motor data

  - Related Parameters:

- **H09 Transient Inductance**

  - Range: 0.001 ~ 30.000 mH in 0.001 mH

  Hyundai motor data

  - Related Parameters:

- **H10 Motor Resistance R1 Auto Tuning Data**

  - Range: : 0.1 ~ 3000.0 mOhms in 0.1 mOhms

  Value determined during Auto Tuning process

  - Related Parameters:

- **H11 Transient Inductance Auto Tuning Data**

  - Range: 0.001 ~ 30.000 mH in 0.001 mH

  Value determined during Auto Tuning process

- **H12 State of Auto-tuning**

  Display value determined during Auto Tuning process

*****Auto Tuning Application**

Setting Procedures

- H02:
- H03:
- H04:
- H05:
- H06
- H07

Execution: Press “Run” Key

Successful Completion ; --oK (if failed: Err on display)

- H01: Select the latest to 1

Auto Tuning

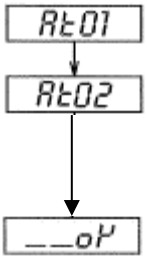
Function description

The auto tuning procedure automatically sets the motor parameters related to sensorless vector control and automatic torque boost. Since these functions are dependent upon specific motor parameters, default motor parameters have been set at the factory.
An auto tune is recommended before running in sensorless vector or automatic torque boost mode in order to achieve optimal performance

Auto-Tune Procedure

Follow the steps below to auto tune the inverter, finally set the parameter H01.

1. F02, F03: Set to 30 s, the default for each parameter
2. H03: Set the motor rating
3. H04: Set the motor poles
4. A01: Set to 0 (frequency command source at potentiometer)
5. A03: Set the base frequency (default is 60Hz)
6. F01: Set the target frequency to 0Hz by turning the potentiometer all the way down. Verify this setting by looking at the value in F01.
7. A53: Select the output voltage to the motor.
8. A33: Set to 0 (disables DC injection braking).
9. H01: Set to 1 (turns auto tuning mode on).
10. After setting above parameters, press the RUN key on the standard operator.
11. The VFD will run the auto tuning procedure on the motor. During this procedure the motor may run up to 80% of full speed. During the auto tune you will see the following messages on the screen:



12. When you see the last screen (__oY , for " OK") the auto tune has successfully completed.
    a. If the display shows Err instead, the auto tune has failed. Verify that the motor is wired properly
13. H02: Set to 1 (uses auto tune data)

Auto Tuning method

Motor connection
↓
Auto Tuning mode selection H01=1
↓
Run command ON
↓
Motor parameter setting
↓
Auto Tuning mode selection H01=1

① DC excitation(no rotation)
② Single phase excitation.

End display
Auto Tuning process completed :

Auto Tuning process failed :

Note : The default motor parameters of the iMASTER C1 use standard data of a HYUNDAI 4-pole motor. If using sensorless vector or auto-torque boost with a different motor type, use the auto tune feature to set the motor data.

Fine Tuning

1. If satisfactory performance through auto tuning cannot be fully obtained,
   adjust the motor constants for the observed symptoms according to the table below.

Symptom		Adjustment	Parameter
At Motoring Status	When low frequency (a few Hz) torque is insufficient.	Slowly increase the motor constant 1.2 times the auto tune data.	H08/H10
	When the speed deviation is negative.	Slowly increase the rated motor slip up to 1.5 times original setting.	H07
	When the speed deviation is positive.	Slowly decrease the rated motor slip down to 0.5 times original setting	H07
	When Over current Fault occurs as the load is applied	Slowly increase the motor no load current in up to 1.2 times original setting.	H06
At Regeneration Status	When low frequency (a few Hz) torque is insufficient.	Slowly increase the motor constant R1 1.2 times the auto tune data	H08/H10
		Slowly increase the motor no load current in up to 1.2 times original setting	H06
		Decrease the carrier frequency.	b11

2. If the inverter capacity is more than twice the capacity of the motor in setting of A28=1, A31=2, the VFD may not achieve its full performance specifications.
3. When DC injection braking is enabled (A33 = 1), the motor constant will not be accurately set. Therefore, disable DC injection braking (A33 = 0) before starting the auto tuning procedure.
4. The motor and load must be stationary before initiating the auto tune. Auto tuning while the motor is rotating may produce inaccurate results.
5. If the auto tuning procedure is interrupted by the stop command, the auto tuning constants may be stored in the inverter incorrectly. It will be necessary to reset the inverter to factory defaults (b12 = 1 *NOTE: This will reset all inverter parameter back to the factory)

Permanent magnet synchronous motor control function

Function description

When driving a permanent magnet synchronous motor (PMSM), observe the following notes. Items not covered in this section are the same as for induction motor (IM) drive.
The PMSM drive is available in the ROM version 1.050 or later.

Item	Specifications
Drive by commercial power	A PMSM cannot be driven by commercial power. Be sure to use an inverter. A failure could occur.
Wiring	Be sure to match inverter's output terminals (U, V and W) with motor's input terminals (U, V and W).
Control mode	When A31 = 4 (VF_ Permanent magnet synchronous motor control) At the start of driving the motor, the inverter flows current equivalent of the motor rated current (H05) to pull in the magnetic pole position for synchronization. After that, the inverter accelerates the motor to the reference frequency. No magnetic pole position detection function is provided. No auto search for an idling PMSM and restart function are provided. Depending upon the magnetic pole position, the motor may run in the reverse direction slightly at the start of running.
Speed control range	The speed control range is from 20% to 100% of the base frequency(A03). Set the reference frequency to 20% or more of the A03 data.
Starting torque	Set b46(DC Injection braking force) of A03(Base frequency)
Motor constants	The following motor parameters are used, so consult the motor manufacturer and configure the correct values. No tuning function is provided. A03: Base frequency setting [Hz] A53: Motor input voltage setting [V] H04: Motor poles setting [P] H05: Motor rated current [A] H09: Transient Inductance [mH] If motor parameters are not correct, the inverter cannot run normally. A failure could occur
2nd motor	A PMSM cannot be driven as the 2nd motor.
V/f pattern	Linear V/f pattern only.
Auto energy saving	When driving a PMSM, the high-efficiency control is always ON.
Auto-tuning	A PMSM cannot be tuned.
Restart mode	Not available for a PMSM.
Jogging operation	Not available for a PMSM.
DC braking	Not available for a PMSM.
Others	Be sure to consult the motor manufacturers before actual operation. A failure could occur

Code that needs to be set up

A03 (Base frequency setting)
A04 (Maximum frequency setting)
A31 (V/F characteristic curve selection)
A53 (Motor input voltage setting)
b46 (DC Injection braking force)
H04 (Motor poles setting)
H05 (Motor rated current)
H09 (Transient Inductance)
H13 (Control switching start level)
H14 (Control switching completion level)
H15 (d-axis current controller P gain)
H16 (d-axis current controller I gain)
H17 (q-axis Stabilization Controller gain)
H18 (d-axis Stabilization Controller gain)
H19 (High Efficiency Controller P Gain)
H20 (High Efficiency Controller I Gain)

Precautions

When operating a permanent magnet synchronous motor, please make sure to drive it after reviewing it with the seller in advance.

Output frequency holding function

■ **Holding frequency (H21)**

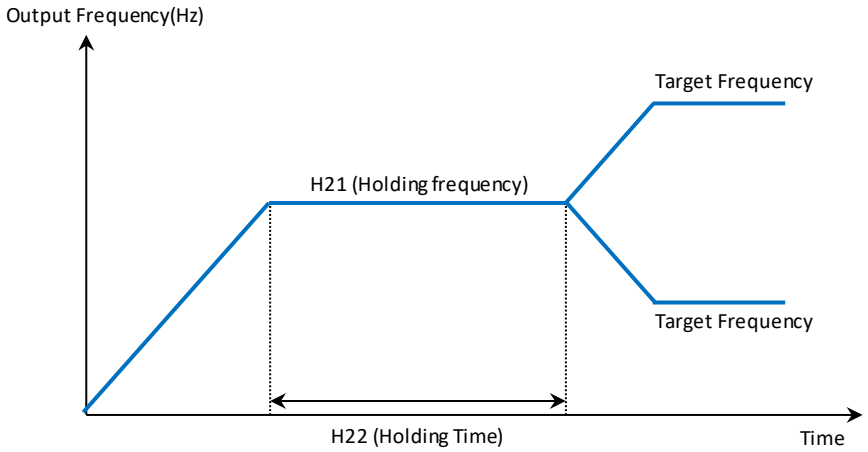
The user can set the holding frequency at startup using the H21 code.

- Range: 0.00 ~ Maximum frequency (A04) [Hz] in 0.01Hz
- Default: 60.00Hz

■ **Holding time (H22)**

The user can set the holding time at startup using the H22 code.

- Range: 0.0 ~ 600.0 [sec] in 0.1sec
- Default: 0.0sec
- If set to 0.0 seconds, the output frequency holding function is disabled.



Vector Control (Encoder Option)

■ **Vector control speed controller P gain (H23)**

- Range: 0 ~ 1000 in 1
- Initial value: 100

Set the proportional controller gain required for speed control when using vector control. If it is set too high, it may diverge, so be careful when setting it.
The encoder option is mandatory. Please refer to the manual attached to the encoder option box and use it after correct installation.

- The larger the P gain value, the faster the response speed.
- Be careful because too high P-gain value may cause vibration or overshoot.

■ **Vector control speed controller I gain (H24)**

- Range: 0 ~ 1000.0% in 0.1%
- Initial value: 100.0%

Set the integral controller gain required for speed control when using vector control.
If it is set too high, it may diverge, so be careful when setting it.
The encoder option is mandatory. Please refer to the manual attached to the encoder option box and use it after correct installation.

- The larger the I gain value, the faster the response speed.
- Be careful because too high I-gain value may cause vibration or overshoot.

■ **Forward torque limit (H25)**

- Range: 0 ~ 200.0% in 0.1%
- Initial value: 150.0%

■ **Forward regeneration torque limit (H26)**

- Range: 0 ~ 200.0% in 0.1%
- Initial value: 150.0%

■ **Reverse torque limit (H27)**

- Range: 0 ~ 200.0% in 0.1%
- Initial value: 150.0%

■ **Reverse regeneration torque limit (H28)**

- Range: 0 ~ 200.0% in 0.1%
- Initial value: 150.0%

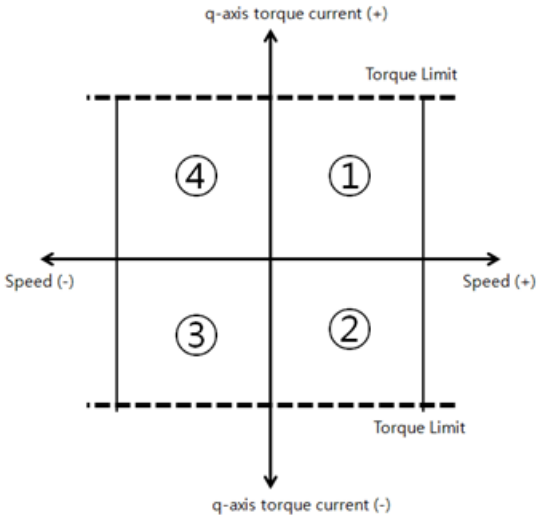
■ **Zero speed torque limit (H29)**

- Range: 0 ~ 200.0% in 0.1%
- Initial value: 150.0%

■ **Zero speed regeneration torque limit (H30)**

- Range: 0 ~ 200.0% in 0.1%
- Initial value: 150.0%

- **Torque Limit**
  - As shown in the figure below, when the motor is driven in the forward or reverse direction, you can set the motoring and regenerative torque limits.



  - Forward Motoring Torque limit : √i * motor rated current * 98.16 %
  - Forward Regeneration Torque limit : √2 * motor rated current * 98.17 %
  - Reverse Motoring Torque limit : √2 * motor rated current * 98.18 %
  - Reverse Regeneration Torque limit : √2 * motor rated current * 98.19 %
  - Zero Speed Motoring Torque limit : √2 * motor rated current * 98.20 %
  - Zero Speed Regeneration Torque limit : √2 * motor rated current * 98.21 %

Torque limit setting method (H31)

- 0: AI1 (O)
  - 0 ~ 10V -> 0.0% ~ 200.0% torque limit configuration
  - H25 ~ H30- code value is changed equally
- 1: AI2 (OI)
  - 4 ~ 20mA -> 0.0% ~ 200.0% torque limit configuration
  - H25 ~ H30 code value is changed equally
- 2: Keypad ----- Initial value
- 3 : Modbus
- 4 : Feildbus
- 5 : UP/DOWN function

Speed controller output low pass filter time constant (H32)

- Range: 0 ~ 100 ms in 1ms
- Initial value: 0 ms

During vector control operation, a low-pass filter is applied to the output of the speed controller to smooth the torque change. Excessive filter application destroys vector control, so it is recommended to set it to 0 msec as much as possible. Also, when it is set to torque mode, it operates with the filter time constant of the torque reference.

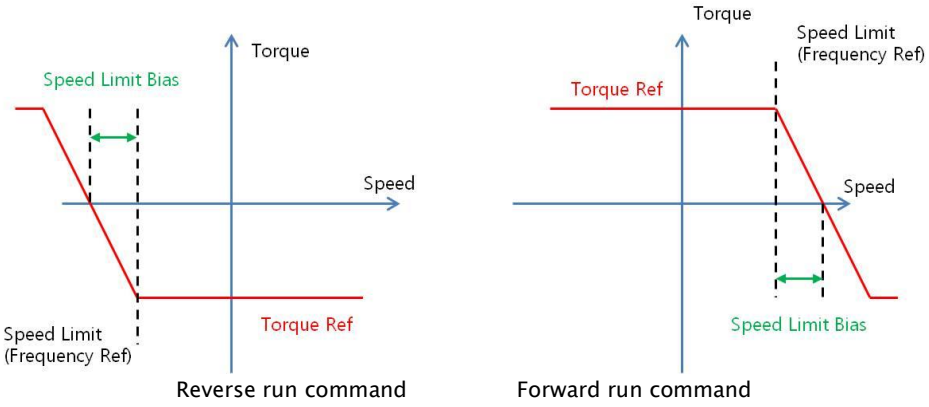
■ **Speed/Torque mode select (H38)**

- 0: Speed control mode----- Initial value
- 1: Torque control mode

Speed control mode - A general encoder uses the actual motor speed to control the desired command speed. At this time, the output of the speed controller is a torque reference to follow the command speed and is used to control the torque in the current controller.
Torque control mode - Torque command can be set as a torque limit of H25 ~ H30, and only torque is controlled. At this time, if the torque is controlled constant, the motor can continue to accelerate in the direction of the applied torque. To prevent this, the command speed acts as a speed limit, and the torque is reduced so as not to accelerate beyond the speed limit. H43 (Speed Limit Bias) makes the torque decrease in the vicinity of the speed limit, so that the torque shock is alleviated.

- Torque Mode Operation

In case torque control mode is set using H38 code, torque limit (H25~H30) is set as torque reference and speed reference is set as speed limit. The speed limit bias set in code H43 reduces the torque command near the speed limit to prevent infinite acceleration of the motor. Please note that if the speed limit bias is small, system failure may occur due to sudden torque change.



■ **Speed limit bias in torque mode (H43)**

- Range: 0.01 ~ 10.00 Hz in 0.01 Hz
- Initial value: 1.0 Hz

In the torque control mode, if a torque command greater than the load torque is applied, the motor can continue to accelerate. To prevent this, the torque is linearly reduced from near the speed limit to the speed limit bias to prevent the motor from continuing to accelerate. If the speed limit bias is too small, the torque may change rapidly and torque shock may occur.

■ **Encoder PPR (H44)**

- Range: 0 ~ 9999
- Initial value: 1024
- Encoder option required

■ **Encoder direction setting (H45)**

- 0: Counterclockwise ----- Initial value
- 1: Clockwise
- Encoder option required

■ **Encoder low pass filter time constant (H46)**

- Range: 0 ~ 10000 ms
- Initial value: 0 ms
- Encoder option required

A low-pass filter can be applied to the motor speed measured by the encoder. To prevent speed hunting due to noise, set the filter time constant. In vector control, feedback speed delay may cause controller divergence, so set it to 0msec as much as possible

■ **Encoder frequency deviation error frequency (H47)**

- Range: 0.00 ~ 10.00 Hz
- Initial value: 3.00 Hz
- Encoder option required

■ **Encoder frequency deviation error detection time (H48)**

- Range: 0.0 ~ 10.0 sec
- Initial value: 0.0 sec
- Encoder option required

■ **Overspeed error detection level (H49)**

- Range: 100.0 ~ 120.0 %
- Initial value: 110.0 %
- Encoder option required

■ **Overspeed error detection time (H50)**

- Range: 0.0 ~ 3.0 sec
- Initial value: 0.0 sec
- Encoder option required

During vector control operation, if the actual motor speed measured by the encoder is higher than [Speed reference * “H49” and maintained for the set time “H50”, the inverter stops and an error is displayed.

■ **Torque rise time in torque mode (H51)**

- Range: 0.0 ~ 3000.0 s in 0.1s
- Initial value: 0.0 s

When the inverter run command is applied in the torque mode setting, the torque is gradually increased to alleviate the torque shock.

■ **Torque fall time in torque mode (H52)**

- Range: 0.0 ~ 3000.0 s in 0.1s
- Initial value: 0.0 s

When the inverter stop command is applied in the torque mode setting, the torque is gradually reduced to alleviate the torque shock.

■ **Encoder pulse error detection method select (H53)**

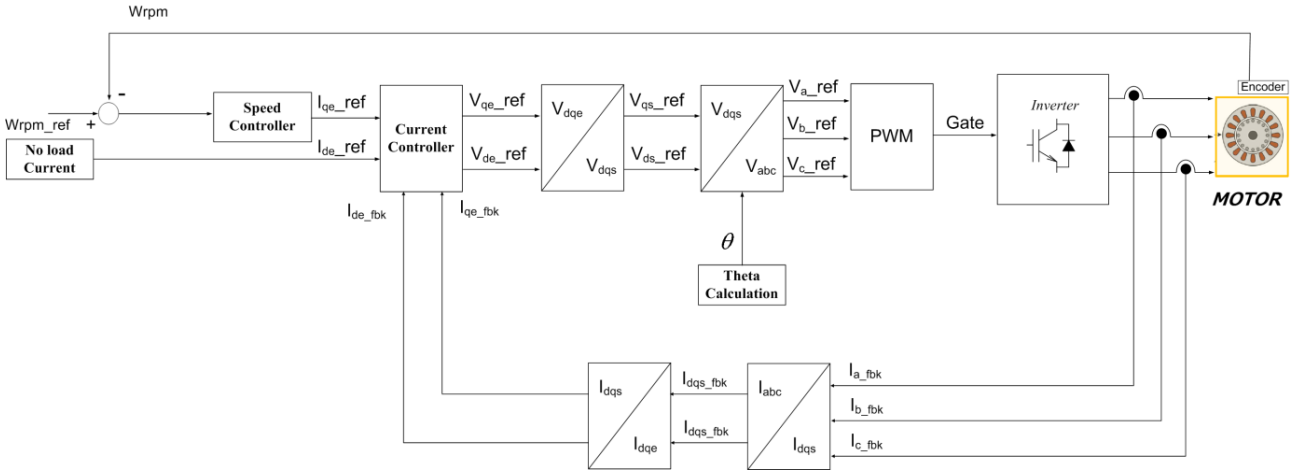
- 0: Disable detection ----- Initial value
- 1: Detection all encoder pulse error
- 2: A and B all pulse error
- 3: A or B pulse error
- Encoder option required

■ **Encoder pulse error detection time (H54)**

- Range: 0.0 ~ 60.0 sec
- Initial value: 3.0 sec
- Encoder option required

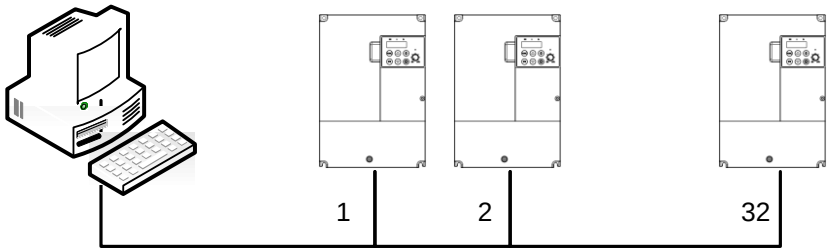
Vector Control

- Controls the motor speed and instantaneous torque using an encoder.
- Vector control block diagram



7. COMMUNICATION

iMASTER C1 offers two communication interfaces between the inverter and external controller through RS485. Use RJ-45 modular connector and RXP, PXN as second way. By communication, the main controller (iMASTER C1) can control 1~32 pcs controllers as slave.



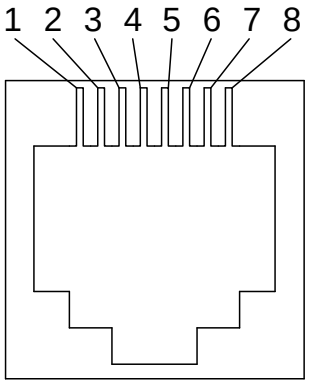
[RS485 Serial Communication Network]

■ **RS485 Communication specification**

Item	Description	Remark
Interface	RS485	
Communication method	Half duplex	
Communication speed	9600 (1st RJ-45) 2400~38400 (2nd terminal)	Fixing Changeable setting(b31)
Communication code	Binary code	
Date bit	8	Fixing
Parity	No	Fixing
Stop bit	1	Fixing
Staring method	External request	Inverter is only slave part
Wait time	10~1000㎳	
Connection type	1: N (Max 32) (Note1)	
Error check	Frame/CRC/CMD/MAXREQ/Parameter	Communication number is selected at b17

(Note 1) Depending on the installation environment, there is a high probability of communication malfunction due to wiring type, wiring method, and other noise. For reliable communication, we recommend fewer than 16 connections.

■ **RJ45 specification (1st Communication)**



Pin No.	Signal Descriptions
1	5V
2	
3	RS - 485+
4	
5	
6	RS - 485-
7	24V
8	5V, 24V GND

■ **Terminal specification (2nd communication)**

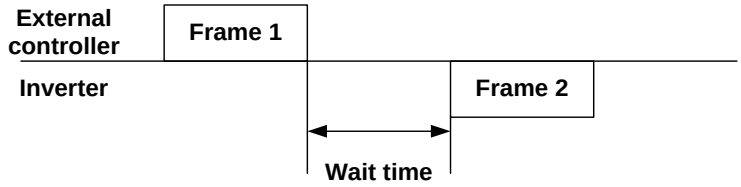
Name	Description
RXP	RS485 (+)
RXN	RS485 (-)

■ **RS485 related code**

Func-code	Range	Default	Setting
b17	1 ~ 32	1	Setting communication number
b31	1 – 2400 [bps] 2 – 4800 [bps] 3 – 9600 [bps] 4 – 19200 [bps] 5 – 38400 [bps]	3	Setting 485 and 2nd communication speed
A01	0 – Keypad potentiometer 1 – Control input terminal 2 – Standard operator 3 – Remote (1st communication RJ45) 4 – Remote (2nd communication Terminal) 5 – Option 6 – Potentiometer and remote	1	
A02	0 – Keypad potentiometer 1 – Control input terminal 2 - Remote (1st communication RJ45) 3 – Remote 2nd communication Terminal) 4 – Fieldbus (option)	1	

■ Communication sequence

The communication sequence is as follows,



Frame start: Frame start is recognized by signal line data transmitted.
Frame completion: Frame completion is recognized by no data during correspond 4, 5-character time.
Frame 1: Transmit from external controller to inverter.
Frame 2: Indication reflects from inverter to external controller

■ Communication frame type and form

- **External controller transmit frame**

Communication number	Command	Parameter	Parameter count	CRC Hi	CRC Lo

Item	Description	Data size	Specifications
Communication number	Inverter communication number	1 byte	1~32
Command	Frame type	1 byte	0x03
Parameter	Parameter	2 bytes	1st byte: Group 2nd byte: Index
Parameter count	Request parameter number(count)	2 bytes	1st byte: 0x00 2nd byte: N(0x01~0x08)
CRC Hi	-	1 byte	Higher 8bit of 16bit CRC
CRC Lo	-	1 byte	Lower 8bit of 16bit CRC

- **Inverter response frame**

Communication number	Command	Byte Number	Data 1	• • •	Data N	CRC Hi	CRC Lo

Item	Description	Data size	Specifications
Communication number	Inverter communication number	1 byte	1~32
Command	Frame type	1 byte	0x03
Byte Number	Data Byte Number	1 byte	Request parameter * 2
Data 1	Parameter 1	2 bytes	Parameter value
Data N	Parameter N	2 bytes	Nth parameter value
CRC Hi	-	1 byte	Higher 8bit of 16bit CRC
CRC Lo	-	1 byte	Lower 8bit of 16bit CRC

※ Frame Size = 5 + Request parameter number x 2

■ Parameter frame type and form

Set 1 parameter and command (Note3) to inverter.

- **External transmit frame**

Communication number	Command	Parameter	Data	CRC Hi	CRC Lo

	Description	Data size	Specifications
Communication number	Target inverter communication number	1 byte	1~32
Command	Frame type	1 byte	0x06
Parameter	Parameter	2 bytes	1st byte: Group 2nd byte: Index (Note1)
Data	Data	2 bytes	Setting value (Note 2)
CRC Hi	-	1 byte	Higher 8bit of 16bit CRC
CRC Lo	-	1 byte	Lower 8bit of 16bit CRC

- **Inverter response frame**

Communication number	Command	Parameter	Data	CRC Hi	CRC Lo

	Description	Data size	Specifications
Communication number	Target inverter communication number	1 byte	1~32
Command	Frame type	1 byte	0x06
Parameter	Parameter	2 bytes	1st byte: Group 2nd byte: Index (Note1)
Data	Data	2 bytes	Setting value (Note 4)
CRC Hi	-	1 byte	Higher 8bit of 16bit CRC
CRC Lo	-	1 byte	Lower 8bit of 16bit CRC

(Note 1) Parameter setting

1) Basic parameter
Set each group to 1st byte and set the parameter number to 2nd byte.
For example, A60 parameter reading or writing, set 0x03 to 1st byte and 0x3C to 2nd byte.

1st byte		2nd byte
Group	Set	Parameter number
d	0x01	
F	0x02	
A	0x03	
B	0x04	
C	0x05	
H	0x06	

Trip information is 13 parameters.
(output frequency, output current, DC link voltage, Output voltage, output torque, Reference frequency, Run direction , Run status, module temperature, I/O Terminal Status, I/O Comm Status, Run Time at trip occurs)

	Trip information (d13)	Previous first trip (d14)	Previous second trip (d15)	Previous third trip (d16)	Trip count (d17)
1st byte	0x01	0x01	0x01	0x01	0x01
2nd byte	0x0D	0x1A	0x27	0x34	0x41

※ Trip information data

Trip data	Description	Trip data	Description
1	Over current trip	20	HW power trip 1
2	Over voltage trip	21	HW power trip 2
3	Under voltage trip	22	External trip 2
4	Arm short trip	23	External trip 3
5	Reserved	24	External trip 4
6	Inverter over heat	25	External trip 5
7	Electric thermal trip	26	External trip 6
8	External trip	27	Fan trip
9	EEPROM error	28	Option trip (Profibus)
10	Communication error	29	Option trip (DeviceNet)
11	USP trip	30	System Overload Detection Fault
12	Ground Fault trip (Over 30kW)	31	System Underload Detection Fault
13	Reserved	32	Keypad communication trip
14	Inverter Overload	33	Option trip (CCLink)
15	Input phase loss	34	Encoder Frequency Deviation Trip
16	CPU error	35	Encoder Overspeed Trip
17	Safety function	36	Encoder Pulse Error1 Trip
18	Braking resistor overload	37	Encoder Pulse Error2 Trip
19	OVS fail		

※ Exception Code

Code	
0x01	ILLEGAL_FUNCTION
0x02	ILLEGAL_DATA_ADRESS
0x03	ILLEGAL_DATA_VALUE
0x04	SLAVE_DEVICE_FAILURE

※ Exception Code Response

Response	
Modbus Node ID	
Function	Status with the highest bit set.
Exception Code	
CRC Lo	
CRC Hi	

(Note 2) Data value setting

Data value is transmitted except decimal point.
(Please contact to ADT for more details)

Description	Related code	Scale	Remark
Frequency	d01, F01 etc.	0.01	Communication date 6000 Conversion hexadecimal 60 [Hz]
Acc/decel time	F02, F03 etc.	0.1	Communication data 100 Conversion hexadecimal 10 [sec]
Current	d02 etc.	0.1	Communication data 100 Conversion hexadecimal 10[A]

(Note3) Special parameter

1) Run command
Parameter frame: 0x0002
Setting data: Forward (0x0001), Reverse (0x0002), Reset (0x0004), Stop (0x0000)

Ex) Forward run command frame

Description	Comm.no.	Command	Parameter	Data	CRC
Data	0x01	0x06	0x0002	0x0001	0xe9ca

2) Frequency command
Parameter frame: 0x0004
Setting data: Hexadecimal of (Output frequency command * 100)

Ex) Frequency command (60Hz) frame

Description	Comm.no.	Command	Parameter	Data	CRC
Data	0x01	0x06	0x0004	0x1770	0xc61f

Data additional explanation: 60Hz → 6000(Scale) → 0x1770

(Note4) Response data for parameter setting

The set data is responded according to the request frame, and if the setting is not made due to reasons such as impossible to change during operation, the original data is responded.

Ex) Frequency command (60Hz) response frame (same frame as transmission frame is responded)

Description	Comm.no.	Command	Parameter	Data	CRC
Data	0x01	0x06	0x0004	0x1770	0xc61f

(Reference) 16bit CRC generation

The step of CRC generation is as follows:

1) All of 16-bit Parameter is 1.0xffff
2) The exclusive OR of 16-bit Parameter and 8-bit Parameter.
3) Shift right side 1bit 16-bit Parameter
4) If the result of step 3 is 1, exclusive OR 16-bit Parameter and 0xa001.
5) Execute 8 times step 3 and step 4.
6) Execute step 2～6 until data completion.
7) Exchange the step 6 result of higher 8bit and lower 8bit.

Ex) The case of d01 output frequency reading

Byte 1	Byte 2	Byte 3	Byte 4	Byte 5	Byte 6
Communication number	Command	Parameter		Parameter Number	
0x01	0x03	0x01	0x01	0x00	0x01

The sequence of addition Byte (01x01)

16-BIT REGISTER	MSB				Flag
(Exclusive OR)	1111	1111	1111	1111	
01	0000	0001			
	1111	1111	1111	1110	
Shift 1	0111	1111	1111	1111	
Shift 2	0011	1111	1111	1111	1
Polynomial(0xa001)	1010	0000	0000	0001	
	1001	1111	1111	1110	
Shift 3	0100	1111	1111	1111	
Shift 4	0010	0111	1111	1111	1
Polynomial(0xa001)	1010	0000	0000	0001	
	1000	0111	1111	1110	
Shift 5	0100	0011	1111	1111	
Shift 6	0010	0001	1111	1111	1
Polynomial(0xa001)	1010	0000	0000	0001	
	1000	0001	1111	1110	
Shift 7	0100	0000	1111	1111	
Shift 8	0010	0000	0111	1111	1
Polynomial(0xa001)	1010	0000	0000	0001	
	1000	0000	0111	1110	

Byte 1~6	CRC of operation results
0x01	0x807e
0x03	0x3364
0x01	0x30e1
0x01	0x8831
0x00	0xd449
0x01	0x36d4

Change upper and lower 8 bit of result 0x36d4: 0xd436
Byte7: Upper 8 bit of CRC = 0xd4
Byte8: Lower 8 bit of CRC = 0x36

■ ModBus Address Table

FS : Factory Setting *Data Type is unsigned integer16

Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
d01	Output Frequency Monitor	0x0101	257	R	0	0	40000	0.01	Hz
d02	Output Current Monitor	0x0102	258	R	0	0	60000	0.1	A
d03	Output Voltage Monitor	0x0103	259	R	0	0	2000	1	V
d04	Rotation Direction	0x0104	260	R	0	0	1		
d05	PID Feedback	0x0105	261	R	0	0	10000		
d06	Intelligent Input Terminal Status	0x0106	262	R	0	0	255		
d07	Intelligent Output Terminal Status	0x0107	263	R	0	0	7		
d08	RPM Output	0x0108	264	R	0	0	60000		
d09	Power Consumption	0x0109	265	R	0	0	10000		W
d10	VFD Runtime (Day)	0x010a	266	R	0	0	65535		Day
d11	VFD Runtime (Minutes)	0x010b	267	R	0	0	65535		Minute
d12	DC Bus Voltage	0x010c	268	R	0	0	2000	1	V
d13	Current Fault,Fault Code	010D	269	R	0	0	40000		
	Trip Monitor 1,Frequency at Trip	010E	270	R	0	0	40000	0.01	Hz
	Trip Monitor 1,Current at Trip	010F	271	R	0	0	60000	0.1	A
	Trip Monitor 1,Vdc at Trip	0110	272	R	0	0	2000	1	V
	Trip Monitor 1,Output voltage at Trip	0111	273	R	0	0	2000		
	Trip Monitor 1,Output torque at Trip	0112	274	R	0	0	40000		
	Trip Monitor 1,Reference frequency at Trip	0113	275	R	0	0	40000	0.01	Hz
	Trip Monitor 1,Run direction at Trip	0114	276	R	0	0	40000		
	Trip Monitor 1,Run Status at Trip	0115	277	R	0	0	40000		
	Trip Monitor 1,Module Temperature at Trip	0116	278	R	0	0	40000		
	Trip Monitor 1,I/O Terminal Status at Trip	0117	279	R	0	0	40000		
	Trip Monitor 1,I/O Comm Status at Trip	0118	280	R	0	0	40000		
	Trip Monitor 1,Run Time at Trip	0119	281	R	0	0	40000		
d14	Previous Fault 1,Fault Code	011A	282	R	0	0	40000		
	Trip Monitor 2,Frequency at Trip	011B	283	R	0	0	40000	0.01	Hz
	Trip Monitor 2,Current at Trip	011C	284	R	0	0	60000	0.1	A
	Trip Monitor 2,Vdc at Trip	011D	285	R	0	0	2000	1	V
	Trip Monitor 2,Output voltage at Trip	011E	286	R	0	0	2000		
	Trip Monitor 2,Output torque at Trip	011F	287	R	0	0	40000		
	Trip Monitor 2,Reference frequency at Trip	0120	288	R	0	0	40000	0.01	Hz
	Trip Monitor 2,Run direction at Trip	0121	289	R	0	0	40000		
	Trip Monitor 2,Run Status at Trip	0122	290	R	0	0	40000		
	Trip Monitor 2,Module Temperature at Trip	0123	291	R	0	0	40000		
	Trip Monitor 2,I/O Terminal Status at Trip	0124	292	R	0	0	40000		
	Trip Monitor 2,I/O Comm Status at Trip	0125	293	R	0	0	40000		
	Trip Monitor 2,Run Time at Trip	0126	294	R	0	0	40000		

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Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
d15	Previous Fault 2,Fault Code	0127	295	R	0	0	40000		
	Trip Monitor 3,Frequency at Trip	0128	296	R	0	0	40000	0.01	Hz
	Trip Monitor 3,Current at Trip	0129	297	R	0	0	60000	0.1	A
	Trip Monitor 3,Vdc at Trip	012A	298	R	0	0	2000	1	V
	Trip Monitor 3,Output voltage at Trip	012B	299	R	0	0	2000		
	Trip Monitor 3,Output torque at Trip	012C	300	R	0	0	40000		
	Trip Monitor 3,Reference frequency at Trip	012D	301	R	0	0	40000	0.01	Hz
	Trip Monitor 3,Run direction at Trip	012E	302	R	0	0	40000		
	Trip Monitor 3,Run Status at Trip	012F	303	R	0	0	40000		
	Trip Monitor 3,Module Temperature at Trip	0130	304	R	0	0	40000		
	Trip Monitor 3,I/O Terminal Status at Trip	0131	305	R	0	0	40000		
	Trip Monitor 3,I/O Comm Status at Trip	0132	306	R	0	0	40000		
	Trip Monitor 3,Run Time at Trip	0133	307	R	0	0	40000		
d16	Previous Fault 3,Fault Code	0134	308	R	0	0	40000		
	Trip Monitor 4,Frequency at Trip	0135	309	R	0	0	40000	0.01	Hz
	Trip Monitor 4,Current at Trip	0136	310	R	0	0	60000	0.1	Arms
	Trip Monitor 4,Vdc at Trip	0137	311	R	0	0	2000		
	Trip Monitor 4,Output voltage at Trip	0138	312	R	0	0	2000		
	Trip Monitor 4,Output torque at Trip	0139	313	R	0	0	40000		
	Trip Monitor 4,Reference frequency at Trip	013A	314	R	0	0	40000	0.01	Hz
	Trip Monitor 4,Run direction at Trip	013B	315	R	0	0	40000		
	Trip Monitor 4,Run Status at Trip	013C	316	R	0	0	40000		
	Trip Monitor 4,Module Temperature at Trip	013D	317	R	0	0	40000		
	Trip Monitor 4,I/O Terminal Status at Trip	013E	318	R	0	0	40000		
	Trip Monitor 4,I/O Comm Status at Trip	013F	319	R	0	0	40000		
	Trip Monitor 4,Run Time at Trip	0140	320	R	0	0	40000		
d17	Trip count	0141	321	R	0	0	40000		
d18	Inverter S/W version	0142	322	R	0	0	65535	0.001	
d19	Fan operation time (day)	0143	323	R	0	0	65535		day
d20	Fan operation time (minute)	0144	324	R	0	0	65535		min
d21	Inverter internal temperature	0145	325	R	0	-400	1600	0.1	℃
d22	Encoder Speed	0146	326	R	0	0	6000		RPM
F01	Output Frequency Set Point	0201	513	R/W	6000	0	A04	0.01	Hz
F02	Acceleration Time 1	0202	514	R/W	50	0	60000	0.1	sec
F03	Deceleration Time 1	0203	515	R/W	100	0	60000	0.1	sec
F04	Rotation Direction	0204	516	R/W	0	0	1		
F05	Rotation direction selection	0205	517	R/W	0	0	2		
F06	Define custom display	0206	518	R/W	0	0	65535	0.1	

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Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
A01	Frequency Setpoint Source	0301	769	R/W	1	0	6		
A02	Run Source	0302	770	R/W	1	0	4		
A03	Base Frequency Setpoint	0303	771	R/W	6000	0	A04	0.01	Hz
A04	Maximum frequency Setpoint	0304	772	R/W	6000	A03	40000	0.01	Hz
A05	Frequency at Min. Analog Input	0305	773	R/W	0	0	A04	0.01	Hz
A06	Frequency at Max. Analog Input	0306	774	R/W	0	0	A04	0.01	Hz
A07	Minimum Analog Input Offset	0307	775	R/W	0	0	1000	0.1	%
A08	Maximum Analog Input Offset	0308	776	R/W	1000	0	1000	0.1	%
A09	Start Frequency	0309	777	R/W	0	0	1		
A10	Low pass Filter Gain	030A	778	R/W	10	1	500	0.1	sec
A11	Multi speed frequency Setpoint 1	030B	779	R/W	500	0	A04	0.01	Hz
A12	Multi speed frequency Setpoint 2	030C	780	R/W	1000	0	A04	0.01	Hz
A13	Multi speed frequency Setpoint 3	030D	781	R/W	1500	0	A04	0.01	Hz
A14	Multi speed frequency Setpoint 4	030E	782	R/W	2000	0	A04	0.01	Hz
A15	Multi speed frequency Setpoint 5	030F	783	R/W	3000	0	A04	0.01	Hz
A16	Multi speed frequency Setpoint 6	0310	784	R/W	4000	0	A04	0.01	Hz
A17	Multi speed frequency Setpoint 7	0311	785	R/W	5000	0	A04	0.01	Hz
A18	Multi speed frequency Setpoint 8	0312	786	R/W	6000	0	A04	0.01	Hz
A19	Multi speed frequency Setpoint 9	0313	787	R/W	0	0	A04	0.01	Hz
A20	Multi speed frequency Setpoint 10	0314	788	R/W	0	0	A04	0.01	Hz
A21	Multi speed frequency Setpoint 11	0315	789	R/W	0	0	A04	0.01	Hz
A22	Multi speed frequency Setpoint 12	0316	790	R/W	0	0	A04	0.01	Hz
A23	Multi speed frequency Setpoint 13	0317	791	R/W	0	0	AF04	0.01	Hz
A24	Multi speed frequency Setpoint 14	0318	792	R/W	0	0	A04	0.01	Hz
A25	Multi speed frequency Setpoint 15	0319	793	R/W	0	0	A04	0.01	Hz
A26	Jog Frequency	031A	794	R/W	50	50	1000	0.01	Hz
A27	Jog Stop Mode	031B	795	R/W	0	0	2		
A28	Torque Boost Mode	031C	796	R/W	0	0	1		
A29	Manual Torque Boost Voltage Setpoint	031D	797	R/W	10	0	500	0.1	%

FS : Factory Setting *Data Type is unsigned integer16

Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
A30	Manual Torque Boost Frequency Setpoint	031E	798	R/W	1000	0	1000	0.1	%
A31	Motor Control Method	031F	799	R/W	0	0	5		
A32	Voltage Gain Factor	0320	800	R/W	1000	200	1100	0.1	%
A33	DC Injection Braking	0321	801	R/W	0	0	1		
A34	DC Injection Braking Frequency Setpoint	0322	802	R/W	50	50	1000	0.01	Hz
A35	DC Injection Braking Delay Time	0323	803	R/W	0	0	50	0.1	sec
A36	DC Injection Braking Force at Stop	0324	804	R/W	500	0	1000	0.1	%
A37	DC Injection Braking Time at Stop	0325	805	R/W	0	0	100	0.1	sec
A38	Frequency Upper Limit	0326	806	R/W	0	A39	A04	0.01	Hz
A39	Frequency Lower Limit	0327	807	R/W	0	0	A38	0.01	Hz
A40	Jump Output Frequencies	0328	808	R/W	0	0	A04	0.01	Hz
A41	Jump Frequency Range	0329	809	R/W	0	0	1000	0.01	Hz
A42	Jump Output Frequencies	032A	810	R/W	0	0	A04	0.01	Hz
A43	Jump Frequency Range	032B	811	R/W	0	0	1000	0.01	Hz
A44	Jump Output Frequencies	032C	812	R/W	0	0	A04	0.01	Hz
A45	Jump Frequency Range	032D	813	R/W	0	0	1000	0.01	Hz
A46	Manual torque boost setting (Reverse)	032E	814	R/W	10	0	500	0.1	%
A47	Manual torque boost Frequency setting (Reverse)	032F	815	R/W	1000	0	1000	0.1	%
A48	Auto Torque Boost Gain	0330	816	R/W	100	0	250		
A49	Auto torque boost filter tow	0331	817	R/W	800	1	9999		
A52	Automatic Voltage Regulation(AVR)	0334	820	R/W	2	0	2		
A53	Motor Input Voltage	0335	821	R/W	380	80	500		
A54	Acceleration Time 2	0336	822	R/W	50	0	60000	0.1	sec
A55	Deceleration Time 2	0337	823	R/W	100	0	60000	0.1	sec
A56	Accel/Decel 2 Command Select	0338	824	R/W	0	0	1		
A57	Accel 2 Transition Frequency	0339	825	R/W	0	0	A04	0.01	Hz
A58	Decel 2 Transition Frequency	033A	826	R/W	0	0	A04	0.01	Hz
A59	Acceleration Curve Select	033B	827	R/W	0	0	2		
A60	Deceleration Curve Select	033C	828	R/W	0	0	2		

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Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
A61	Analog Input Voltage Offset	033D	829	R/W	0	-1000	1000	0.1	%
A62	Analog Input Voltage Gain	033E	830	R/W	1000	-2000	2000	0.1	%
A63	Analog Input Current Offset	033F	831	R/W	0	-1000	1000	0.1	%
A64	Analog Input Current Gain	0340	832	R/W	1000	-2000	2000	0.1	%
A65	FAN Operation Mode	0341	833	R/W	0	0	2		
A66	S curve start ratio setting of acceleration	0342	834	R/W	500	0	1000	0.1	%
A67	S curve stop ratio setting of acceleration	0343	835	R/W	500	0	1000	0.1	%
A68	S curve start ratio setting of deceleration	0344	836	R/W	500	0	1000	0.1	%
A69	S curve stop ratio setting of deceleration	0345	837	R/W	500	0	1000	0.1	%
A70	PID Function Select	0346	838	R/W	0	0	4		
A71	PID Setpoint	0347	839	R/W	0	0	10000	0.01	%
A72	PID Setpoint Source	0348	840	R/W	2	0	6		
A73	PID Feedback Type	0349	841	R/W	0	0	1		
A74	PID P Gain	034A	842	R/W	1000	1	10000	0.1	%
A75	PID I Gain Time	034B	843	R/W	10	0	36000	0.1	%
A76	PID D Gain Time	034C	844	R/W	0	0	1000	0.01	%
A77	PID Error Limit	034D	845	R/W	1000	0	1000	0.1	%
A78	PID Output High Limit	034E	846	R/W	1000	A79	1000	0.1	%
A79	PID Output Low Limit	034F	847	R/W	0	-1000	A78	0.1	%
A80	PID Output Invert	0350	848	R/W	0	0	1		
A81	PID Scale Factor	0351	849	R/W	1000	1	10000	0.1	%
A82	Pre PID Frequency Setpoint	0352	850	R/W	0	0	A04	0.01	Hz
A83	PID Sleep Frequency Setpoint	0353	851	R/W	0	0	A04	0.01	Hz
A84	PID Sleep/Wake Delay Time	0354	852	R/W	0	0	300	0.1	sec
A85	PID Wake Frequency Setpoint	0355	853	R/W	0	0	A04	0.01	Hz
A86	User V/F setting frequency 1	0356	854	R/W	1500	0	A88	0.01	Hz
A87	User V/F setting voltage 1	0357	855	R/W	250	0	A89	0.1	%
A88	User V/F setting frequency 2	0358	856	R/W	3000	A86	A90	0.01	Hz
A89	User V/F setting voltage 2	0359	857	R/W	500	A87	A91	0.1	%
A90	User V/F setting frequency 3	035A	858	R/W	4500	A88	A92	0.01	Hz
A91	User V/F setting voltage 3	035B	859	R/W	750	A89	A93	0.1	%
A92	User V/F setting frequency 4	035C	860	R/W	6000	A90	A04	0.01	Hz
A93	User V/F setting voltage 4	035D	861	R/W	1000	A91	1000	0.1	%
A94	FAN fault Detection	035E	862	R/W	1	0	2		
A95	Deceleration time after DC injection braking	035F	863	R/W	0	0	10	0.1	sec

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Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
b01	Restart Select	0401	1025	R/W	0	0	3		
b02	Line Loss Ride-Through Time	0402	1026	R/W	10	3	100	0.1	sec
b03	Line Loss Ride-Through Run Delay	0403	1027	R/W	10	3	100	0.1	sec
b04	Motor Thermal Overload Level	0404	1028	R/W	1000	200	1200	0.1	%
b05	Motor Thermal Overload Profile	0405	1029	R/W	1	0	1		
b06	Overload/Overvoltage Restriction Mode	0406	1030	R/W	2	0	3		
b07	Overload Restriction Level	0407	1031	R/W	1800	200	2000	0.1	%
b08	Overload Restriction Deceleration Rate	0408	1032	R/W	100	1	100	0.1	sec
b09	Software Lock Mode	0409	1033	R/W	0	0	9999		
b10	Start Frequency Setpoint	040A	1034	R/W	50	10	A04	0.01	Hz
b11	PWM Carrier Frequency	040B	1035	R/W	500	75	1600		
b12	Initialization Mode	040C	1036	R/W	0	0	3		
b13	Country Code	040D	1037	R/W	0	0	2		
b14	RPM Display Scale Factor	040E	1038	R/W	100	1	9999	0.01	%
b15	Stop Key Function	040F	1039	R/W	0	0	1		
b16	Resume Frequency on FRS Cancellation	0410	1040	R/W	0	0	1		
b17	Modbus Node ID	0411	1041	R/W	1	1	32		
b18	Ground Fault Detection Setpoint	0412	1042	R/W	0	0	1000	0.1	%
b19	Speed Search: Current level	0413	1043	R/W	20	1	300	0.1	sec
b20	Speed Search: Voltage Increase	0414	1044	R/W	10	1	100	0.1	sec
b21	Speed Search: Voltage Decrease	0415	1045	R/W	1000	500	1800		
b22	Decel time at FRS	0416	1045	R.W	0	0	60000	0.1	sec
b23	Frequency Match	0417	1047	R/W	0	0	1		
b24	Fault Relay Select	0418	1048	R/W	0	0	3		
b25	Stop Method	0419	1049	R/W	0	0	3		
b26	HD/ND (Torque Type) Select	041A	1050	R/W	0	0	1		
b27	Input Phase Loss Detection Period	041B	1051	R/W	10	0	30		
b28	Communication Time Out Detection	041C	1052	R/W	0	0	60		
b29	Communication Time Out Detection Mode	041D	1053	R/W	0	0	3		
b30	Display at Power On	041E	1054	R/W	1	1	13		
b31	RXP-RXN terminal Com.Baud Rate	041F	1055	R/W	3	1	5		
b32	BRD Mode	0420	1056	R/W	1	0	2		
b33	BRD using ratio	0421	1057	R/W	100	0	500	0.1	%

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Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
b34	Maximum OVS output frequency	0422	1058	R/W	2000	0	30000	0.01	Hz
b35	OVS P gain	0423	1059	R/W	1000	0	10000		
b36	OVS I gain	0424	1060	R/W	100	0	10000		
b37	OVS D gain	0425	1061	R/W	100	0	10000		
b38	Q axis reference	0426	1062	R/W	0	-1000	1000	0.1	%
b39	Filter bandwidth	0427	1063	R/W	1	0	1000		
b40	Overvoltage suppression	0428	1064	R/W	0	0	2		
b41	Limit Time	0429	1065	R/W	5	0	1000	0.1	sec
b42	VFD start delay time after DC Injection braking	042A	1066	R/W	0	0	600	0.1	sec
b43	DC Injection braking time at start	042B	1067	R/W	0	0	60000	0.1	sec
b44	Current controller P gain in DC braking	042C	1068	R/W	500	1	10000		
b45	Current controller I Gain time in DC braking	042D	1069	R/W	500	0	10000		
b46	DC Injection braking force	042E	1070	R/W	500	0	1000	0.1	%
b49	Overload restriction level at acceleration & deceleration	0431	1073	R/W	1800	200	2000	0.1	%
b50	Droop control start freq.	0432	1074	R/W	0	0	A04	0.01	Hz
b51	Droop control standard freq.	0433	1075	R/W	6000	1000	A04	0.01	Hz
b52	Droop control gain	0434	1076	R/W	500	0	5000	0.01	%
b53	Droop star torque	0435	1077	R/W	0	0	1000	0.1	%
b54	Droop acceleration time	0436	1078	R/W	200	10	1000	0.1	sec
b55	Droop control mode	0437	1079	R/W	0	0	1		

FS : Factory Setting *Data Type is unsigned integer16

Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
b56	Motor load detection selection	0438	1080	R/W	0	0	6		
b57	Motor overload detection level	0439	1081	R/W	1000	200	2000	0.1	%
b58	Motor underload detection level	043A	1082	R/W	1000	200	2000	0.1	%
b59	Overload/Underload detection time	043B	1083	R/W	100	0	600	0.1	sec
b60	Overload/Underload detection safe zone	043C	1084	R/W	0	0	A04	0.01	Hz
b61	Dwell frequency at start	043D	1085	R/W	0	0	A04	0.01	Hz
b62	Dwell time at start	043E	1086	R/W	0	0	100	0.1	sec
b63	Dwell frequency at stop	043F	1087	R/W	0	0	A04	0.01	Hz
b64	Dwell time at stop	0440	1088	R/W	0	0	100	0.1	sec
b65	KEB control selection	0441	1089	R/W	0	0	2		
b66	KEB control gain	0442	1090	R/W	100	1	1000	0.1	%
b67	Overcurrent selection	0443	1091	R/W	1	0	1		
b68	Hold time at running	0444	1092	R/W	0	0	600	0.1	sec
b69	Stop frequency setting	0445	1093	R/W	0	0	A04	0.01	Hz
b70	Hold time at stop	0446	1094	R/W	0	0	600	0.1	sec
b71	Unser parameter setting	0447	1095	R/W	1	1	12		
b72	User mathematical sign	0448	1096	R/W	0	0	3		
b73	Define user setting	0449	1097	R/W	100	1	60000	0.01	%

FS : Factory Setting *Data Type is unsigned integer16

Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
C01	Intelligent input terminal 1 setting	0501	1281	R/W	0	0	31		
C02	Intelligent input terminal 2 setting	0502	1282	R/W	1	0	31		
C03	Intelligent input terminal 3 setting	0503	1283	R/W	2	0	31		
C04	Intelligent input terminal 4 setting	0504	1284	R/W	3	0	31		
C05	Intelligent input terminal 5 setting	0505	1285	R/W	13	0	31		
C06	Intelligent input terminal 6 setting	0506	1286	R/W	14	0	31		
C07	Input terminal 1 a/b contact setting (NO/NC)	0507	1287	R/W	0	0	1		
C08	Input terminal 2 a/b contact setting (NO/NC)	0508	1288	R/W	0	0	1		
C09	Input terminal 3 a/b contact setting (NO/NC)	0509	1289	R/W	0	0	1		
C10	Input terminal 4 a/b contact setting (NO/NC)	050A	1290	R/W	0	0	1		
C11	Input terminal 5 a/b contact setting (NO/NC)	050B	1291	R/W	0	0	1		
C12	Input terminal 6 a/b contact setting (NO/NC)	050C	1292	R/W	0	0	1		
C13	Replay output(30A/30B/30C) terminal setting	050D	1293	R/W	5	0	12		
C14	Open collector output (11-CM2) terminal setting	050E	1294	R/W	1	0	12		
C15	Open collector output (12-CM2) terminal setting	050F	1295	R/W	0	0	12		
C16	Output terminal 11 - CM2 a/b contact setting	0510	1296	R/W	0	0	1		
C17	Output terminal 12 - CM2 a/b contact setting	0511	1297	R/W	0	0	1		
C18	FM output selection	0512	1298	R/W	0	0	6		
C19	FM gain adjustment	0513	1299	R/W	1000	0	2500	0.1	%
C20	FM offset adjustment	0514	1300	R/W	0	-30	100	0.1	%
C21	Overload advance notice signal level setting	0515	1301	R/W	1000	100	2000	0.1	%
C22	Acceleration arrival signal frequency setting	0516	1302	R/W	0	0	A04	0.01	Hz
C23	Deceleration arrival signal frequency setting	0517	1303	R/W	0	0	A04	0.01	Hz
C24	PID deviation level setting	0518	1304	R/W	100	0	1000	0.1	%
C25	AMI output selection	0519	1305	R/W	1	0	6		
C26	AMI gain adjustment	051A	1306	R/W	1000	0	2500	0.1	%
C27	AMI offset adjustment	051B	1307	R/W	0	-999	1000	0.1	%
C28	UP/Down value saving selection	051C	1308	R/W	0	0	1		
C29	Up/Down initial value setting	051D	1309	R/W	0	0	A04	0.01	Hz

FS : Factory Setting *Data Type is unsigned integer16

Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
C30	Up/Down Target Frequency Accel/decel time setting	051E	1310	R/W	100	1	30000	0.1	sec
C31	Up/Down function selection	051F	1311	R/W	0	0	1		
C32	Up/Down value setting	0520	1312	R/W	0	0	40000	0.01	%
C33	Decel time at fault occur	0521	1313	R/W	100	0	60000	0.1	sec
C34	Selection of running state when keypad connection failed	0522	1314	R/W	0	0	1		
C35	Selection of keypad detection	0523	1315	R/W	0	0	3		
C36	Selection of communication or analog speed command failure detection	0524	1316	R/W	0	0	3		
C37	Selection of run command when speed losing	0525	1317	R/W	0	0	3		
C38	Waiting time in case of frequency command loss	0526	1318	R/W	10	0	1200	0.1	sec
C39	Frequency setting in case of analog command loss	0527	1319	R/W	3000	0	A04	0.01	Hz
C40	Overload caution time	0528	1320	R/W	100	0	300	0.1	sec
C41	Current of external brake	0529	1321	R/W	1000	0	2000	0.1	%
C42	Frequency of external brake	052A	1322	R/W	1000	0	2500	0.01	Hz
C43	Timer of external brake	052B	1323	R/W	10	0	50	0.1	sec
C44	Stop frequency of external brake	052C	1324	R/W	1000	0	2500	0.01	Hz
C45	Stop timer of external brake	052D	1325	R/W	10	0	50	0.1	sec
C46	Changed Parameter Check	052E	1326	R/W	0	0	1		

FS : Factory Setting *Data Type is unsigned integer16

Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
H01	Auto-tuning mode selection	0601	1537	R/W	0	0	1		
H02	Motor data selection	0602	1538	R/W	0	0	1		
H03	Motor capacity	0603	1539	R/W	0	0	35		
H04	Motor poles setting	0604	1540	R/W	4	2	48		
H05	Motor rated current	0605	1541	R/W	1	1	8000	0.1	Arms
H06	Motor no-load current (Io)	0606	1542	R/W	1	1	4000	0.1	Arms
H07	Motor rated slip	0607	1543	R/W	1	1	2000	0.01	Hz
H08	Motor Resistance R1	0608	1544	R/W	1	1	30000	0.1	%
H09	Transient Inductance	0609	1545	R/W	1	1	30000	0.001	%
H10	Motor ResistanceR1	060A	1546	R/W	1	1	30000	0.1	%
H11	Transient Inductance auto tuning data	060B	1547	R/W	1	1	30000	0.001	%
H12	State of Auto-tuning	060C	1548	R	0	0	6		
H13	Control switching start level	060D	1549	RW	10	0	50		
H14	Control switching completion level	060E	1550	RW	100	0	200		
H15	d-axis current controller P gain	060F	1551	RW	50	0	10000		
H16	d-axis current controller I gain	0610	1552	RW	5	0	10000		
H17	q-axis Stabilization Controller gain	0611	1553	RW	10	0	1000		
H18	d-axis Stabilization Controller gain	0612	1554	RW	0	0	1000		
H19	High Efficiency Controller P Gain	0613	1555	RW	400	0	10000		
H20	High Efficiency Controller I Gain	0614	1556	RW	400	0	10000		
H21	Holding frequency	0615	1557	RW	6000	0	40000	0.01	Hz
H22	Holding time	0616	1558	RW	0	0	6000	0.1	sec
H23	Vector control speed controller P gain	0617	1559	RW	100	0	1000		
H24	Vector control speed controller I gain	0618	1560	RW	100	0	1000		
H25	Forward torque limit	0619	1561	RW	150	0	2000	0.1	%
H26	Forward regeneration torque limit	061A	1562	RW	150	0	2000	0.1	%
H27	Reverse torque limit	061B	1563	RW	150	0	2000	0.1	%
H28	Reverse regeneration torque limit	061C	1564	RW	150	0	2000	0.1	%
H29	Zero speed torque limit	061D	1565	RW	150	0	2000	0.1	%
H30	Zero speed regeneration torque limit	061F	1566	RW	150	0	2000	0.1	%
H31	Torque limit setting method	0620	1567	RW	3	0	6		
H32	Speed controller output low pass filter time constant	0621	1568	RW	0	0	100		

H03(Motor Capacity)
0:MOT_004LF, 1:MOT_007LF, 2:MOT_015LF, 3:MOT_022LF, 4:MOT_037LF, 5:MOT_055LF, 6:MOT_075LF, 7:MOT_110LF, 8:MOT_150LF, 9:MOT_185LF, 10:MOT_220LF , 11:MOT_300LF, 12:MOT_004HF, 13:MOT_007HF, 14:MOT_015HF, 15:MOT_022HF 16:MOT_037HF, 17:MOT_055HF, 18:MOT_075HF, 19:MOT_110HF, 20:MOT_150HF, 21:MOT_185HF, 22:MOT_220HF, 23:MOT_300HF, 24:MOT_370HF, 25:MOT_450HF, 26:MOT_550HF, 27:MOT_750HF, 28:MOT_900HF, 29:MOT_1100HF, 30:MOT_1320HF, 31:MOT_1600HF, 32:MOT_2200HF, 33:MOT_2800HF, 34:MOT_3500HF, 35:MOT_3800HF

FS : Factory Setting *Data Type is unsigned integer16

기능코드	기능명칭	주소 (Hex)	주소 (Dec)	R/W 특성	초기값	최소값	최대값	스케일	단위
H38	Speed/Torque mode select	0622	1569	RW	0	0	1		
H43	Speed limit bias in torque mode	0623	1570	RW	150	0	2000	0.01	Hz
H44	Encoder PPR	0624	1571	RW	1024	0	9999		
H45	Encoder direction setting	0625	1572	RW	0	0	1		
H46	Encoder low pass filter time constant	0626	1573	RW	0	0	10000		
H47	Encoder frequency deviation error frequency	0627	1574	RW	300	0	1000	0.01	Hz
H48	Encoder frequency deviation error detection time	0628	1575	RW	0	0	100	0.1	sec
H49	Overspeed error detection level	0629	1576	RW	1100	1000	1200	0.1	%
H50	Overspeed error detection time	062A	1577	RW	0	0	30	0.1	sec
H51	Torque rise time in torque mode	062B	1578	RW	0	0	30000	0.1	sec
H52	Torque fall time in torque mode	062C	1579	RW	0	0	30000	0.1	sec
H53	Encoder pulse error detection method select	062D	1580	RW	0	0	3		
H54	Encoder pulse error detection time	062E	1581	RW	30	0	600	0.1	sec

FS : Factory Setting *Data Type is unsigned integer16

Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
O01	Fieldbus Option Type	0801	2049	R/W	0	0	4		
O02	Fieldbus Station Number	0802	2050	R/W	1	0	MaxFB		
O03	Fieldbus Byte Swap	0803	2051	R/W	0	0	1		
O04	Fieldbus Communication Speed.	0804	2052	R/W	3	1	5		
O05	Set number of fieldbus Input data	0805	2053	R/W	12	1	12		
O06	Set number of fieldbus Output data	0806	2054	R/W	12	1	12		
O08	Fieldbus Input Address 1	0808	2056	R/W	0x0603	0	65535		
O09	Fieldbus Input Address 2	0809	2057	R/W	0x0001	0	65535		
O10	Fieldbus Input Address 3	080A	2058	R/W	0x0202	0	65535		
O11	Fieldbus Input Address 4	080B	2059	R/W	0x0203	0	65535		
O12	Fieldbus Input Address 5	080C	2060	R/W	0x0201	0	65535		
O13	Fieldbus Input Address 6	080D	2061	R/W	0x0101	0	65535		
O14	Fieldbus Input Address 7	080E	2062	R/W	0x0102	0	65535		
O15	Fieldbus Input Address 8	080F	2063	R/W	0x010C	0	65535		
O16	Fieldbus Input Address 9	0810	2064	R/W	0x010D	0	65535		
O17	Fieldbus Input Address 10	0811	2065	R/W	0x0111	0	65535		
O18	Fieldbus Input Address 11	0812	2066	R/W	0x0115	0	65535		
O19	Fieldbus Input Address 12	0813	2067	R/W	0	0	65535		
O20	Fieldbus Output Address 1	0814	2068	R/W	0x0202	0	65535		
O21	Fieldbus Output Address 2	0815	2069	R/W	0x0203	0	65535		
O22	Fieldbus Output Address 3	0816	2070	R/W	0x0004	0	65535		
O23	Fieldbus Output Address 4	0817	2071	R/W	0x0002	0	65535		
O24	Fieldbus Output Address 5	0818	2072	R/W	0	0	65535		
O25	Fieldbus Output Address 6	0819	2073	R/W	0	0	65535		
O26	Fieldbus Output Address 7	081A	2074	R/W	0	0	65535		
O27	Fieldbus Output Address 8	081B	2075	R/W	0	0	65535		
O28	Fieldbus Output Address 9	081C	2076	R/W	0	0	65535		
O29	Fieldbus Output Address 10	081D	2077	R/W	0	0	65535		
O30	Fieldbus Output Address 11	081E	2078	R/W	0	0	65535		
O31	Fieldbus Output Address 12	081F	2079	R/W	0	0	65535		
O32	Fieldbus Status	0820	2080	R	0	1	65535		
O33	Fieldbus Version	0821	2081	R	0	1	65535		
O34	Fieldbus communication speed setting	0822	2082	R/W	0	0	4		

FS : Factory Setting *Data Type is unsigned integer16

Code Number	Function Name	Address (Hex)	Address (Dec)	R/W attribute	Init. Value	Min. Value	Max. Value	Scale	Unit
O36	TCP IP Addr 1	0823	2083	R/W	192	0	255		
O37	TCP IP Addr 2	0824	2084	R/W	168	0	255		
O38	TCP IP Addr 3	0825	0285	R/W	10	0	255		
O39	TCP IP Addr 4	0826	2086	R/W	100	0	255		
O40	TCP IP Port ID	0827	2087	R/W	502	0	255		
MaxFB : Modbus: 32,Profibus DP:125,DeviceNet63,Ethernet Series:63,CC-LINK:63									

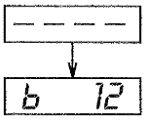
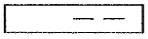
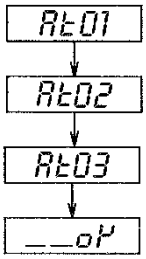
8. PROTECTIVE FUNCTION

The various functions are provided for the protection of the inverter itself. When the protective function is occurred, motor is stopped as free-run and stay the trip once user reset the inverter.

Name	Cause(s)	Error code
Overcurrent protection	When the inverter output current exceeds the rated current during the motor locked or reduced in speed. Protection circuit activates, halting inverter output.	E04
Overload protection	When the inverter output current causes the motor to overload, the electronic thermal trip in the inverter cuts off the inverter output.	E05
Overvoltage protection	If regenerative energy from the motor or the main power supply voltage is high, the protective circuit activates to cut off the inverter output when the voltage of DC link exceeds the specification	E07
Communication error	Communication error between inverter and its operator. If b29 is set to 0 or 1 and Reset signal persists for more than 4 seconds, it will occur.	E60
Under-voltage protection	When input voltage drops below the low-voltage detection level, the control circuit does not function normally. It will cause of overheat of motor and lack of torque that is why if receiving voltage is under 150~160V (200V class) or 300~320V (400V class), the inverter output is cut off.	E09
Output short-circuit	The inverter output was short-circuited. This condition causes excessive current for the inverter that is why, the inverter output is turned off.	E04 or E34
USP error	The USP error is indicated when the power is turned on with the Inverter in RUN state. (Enabled when the USP function selected)	E13
EEPROM	The inverter output is cut off when EEPROM in the inverter has an error due to external noise, excessive temperature rise, or other factors. If the error is occurred, please check setting data again. If error is occurred when power-on and does not off, please turn off the inverter at least 10minutes and power on again.	E08
External trip	When the external equipment or unit has an error, the inverter receives the corresponding signal and cuts off the output.	E12
Temperature trip	When the temperature in the main circuit increases due to cooling fan stop, the inverter output is cut off.	E21
Ground fault	When ground fault is detected on running condition, the output is cut off.	E14
Inverter overload	The power device IGBT is protected from over heat. The operating time of inverter is 1 minute with 150% load of HD or 120% load of ND. The operating time is changed depending on carrier frequency, load, ambient temperature and power rating.	E17
Input phase loss	A function that detects phase loss in the input AC source to prevent damages.	E20
Braking resistor overload protection	When BRD exceeds the usage ratio of the regenerative braking resistor, the over-voltage circuit activates and the inverter output is switched off.	E06
OVS fail	The OVS output frequency is higher than maximum OVS output frequency during the setting time when the OVS function is enabled.	E02
CPU error	It occurred it has error between inverter logic board and I/O board or communication error occurred. Turn off inverter completely, check there is any connection losses then power on.	E11

Name	Cause(s)	Error code
System overload detection fault	The output current of the drive is greater than the detection level set for this feature when it is enabled.	E23
System underload detection fault	The output current of the drive is less than the detection level set for this feature when it is enabled.	E24
FAN fault	The Fan fault is occurred, inverter output is cut off.	E33
Profibus fault (Option)	ProfibusDP optional card only. Host disconnection, or invalid host setting cause this error.	E40
DeviceNet fault (Option)	DeviceNet optional card only. Communication cable power loss, disconnect to host, or invalid host setting cause this error.	E41
HW Power fault 1	It occurred when inverter internal power is problem. Turn off power completely and try power on again.	E50
HW Power fault 2	It occurred when inverter internal power is problem. Turn off power completely and try power on again.	E51
Keypad fault	It occurred keypad communication error. Turn off power completely and try power on again.	E61
External trip 2	When the external equipment or unit has an error, the inverter receives the corresponding signal and cuts off the output. (Need setting for intelligent input terminal)	EE2
External trip 3	When the external equipment or unit has an error, the inverter receives the corresponding signal and cuts off the output. (Need setting for intelligent input terminal)	EE3
External trip 4	When the external equipment or unit has an error, the inverter receives the corresponding signal and cuts off the output. (Need setting for intelligent input terminal)	EE4
External trip 5	When the external equipment or unit has an error, the inverter receives the corresponding signal and cuts off the output. (Need setting for intelligent input terminal)	EE5
External trip 6	When the external equipment or unit has an error, the inverter receives the corresponding signal and cuts off the output. (Need setting for intelligent input terminal)	EE6
CCLink fault (Option)	CCLink optional card only. Communication cable power loss, disconnect to host, or invalid host setting cause this error.	E42
Encoder Frequency Deviation Trip	When using the encoder option card, if it exceeds the set speed deviation and is maintained for as long as the detection time	E44
Encoder Overspeed Trip	When the encoder option card is used, if it exceeds the set overspeed level and is maintained for as long as the detection time	E45
Encoder Pulse Error1 Trip	When using an encoder option card, if both A and B pulse of the encoder or encoder option card remain uninput for the detection time	E46
Encoder Pulse Error2 Trip	When using an encoder option card, if only one of the A or B pulses is input and maintained for as long as the detection time	E47

Other display

Contents	Display
It is displayed when initialization of data is processing (It is not displayed when initialization of history is processing.)	
There is no data available (Trip history, PID feedback data)	
The auto-tuning operation terminates normally	

9. TROUBLESHOOTING TIPS

Symptom		Probable Cause	Countermeasure
The motor will not move	The inverter outputs U, V and W are not supplying voltage	•Is the frequency command source A01 parameter setting correct? •Is the Run command sourceA02 parameter setting correct?	•Make sure the parameter A01 setting correct? •Make sure the parameter A02 setting correct?
		•Is power being supplied to terminals R, S and T? If so, the power lamp should be on.	•Check terminals R, S and T then U, V, and W. •Turn on the power supply/
		•Is there an error code E□□displayed?	•Press the Func key and determine the error types. Then clear the error (Reset).
		•Are the signals to the intelligent input terminals correct? •Is the Run Command active? •Is the[FW] terminal (or [RV]connected to CM1(via switch, etc.)	•Verify the terminal functions for C01-C06 are correct. •Turn on Run Command •Supply 24V to [FW] or [RV] terminal, if configured. (Terminal mode selection)
		•Has the frequency setting for F01 been set greater than zero? •Are the control circuit terminals H, O, and L connected to the potentiometer?	•Set the parameter for F01to a safe, non-zero value. •If the potentiometer is the frequency setting source, verify voltage at "O" ＞0V
		•Is the RS(reset) function or FRS (free-run stop) function on?	• Turn off the command(s)
	Inverter outputs U, V, W are supplying voltage	•Is the motor load too heavy? •Is the motor locked?	•Reduce load, and test the motor independently.
The direction of the motor is reversed		•Are the connections of output terminal U, V, and W correct? •Is the phase sequence of the motor forward or reverse with respect to U, V, and W?	•Make connections according to the phase sequence of the motor. In general: FWD=U-V-W REV=U-W-V
		•Are the control terminals [FW] and [RV]wired correctly? •Is parameter F04 properly set?	• Use terminal [FW] for [RV] is reverse.
The motor speeds will not reach the target frequency		• If using the analog input, is the current or voltage at "O" or "OI"?	•Change the wiring
		• Is the load too heavy?	•Reduce the load. •Heavy loads activate the overload restriction feature.

Symptom		Probable Cause	Countermeasure
The rotation is unstable		•Is the load fluctuation too great? •Is the supply voltage unstable? •Is the problem occurring at a particular frequency?	•Increase the motor capacity (both inverter and motor) •Fix power supply problem. •Change the output frequency slightly, or use the jump frequency setting to skip the problem frequency.
The RPM of the motor does not match the inverter output frequency setting		•Is the maximum frequency setting A04 correct?	•Verify the V/F settings match motor specifications •Make sure all scaling is properly set
Inverter data is not correct	No down-Load shave occurred	•Was power turned off after a parameter edit but before pressing the store key?	•Edit the data and press the store key once
		•Edits to data are permanently stored at power down. Was the time from power off to power on less than six seconds?	•Wait six seconds or more before turning power off after edit data.
A parameter is not change	The frequency setting will not change. Run/Stop does not operate	•Was the standard operator mode and terminal mode changed correctly?	•Make sure the setting mode of [A01], [A02] (Refer to 5-4)
	Parameter is not change	•Is the SFT setting selected? SFT (b09 -2,3) selected?	•Turn off SFT function and check the b09 parameter. (b09=0)

10. MAINTENANCE AND INSPECTION

Regularly perform maintenance and inspection. Failure to carry out regular maintenance checks will result in failure in some cases.

DANGER

- Wait at least ten (10) minutes after turning off the input power supply before performing maintenance of an inspection.
  Otherwise, there is the danger of electric shock.
- Make sure that only qualified personnel will perform maintenance, inspection, and part replacement. (Before starting to work, remove any metallic objects wristwatch, bracelet, etc.)
  Otherwise, there is a danger of electric shock and/or injury.

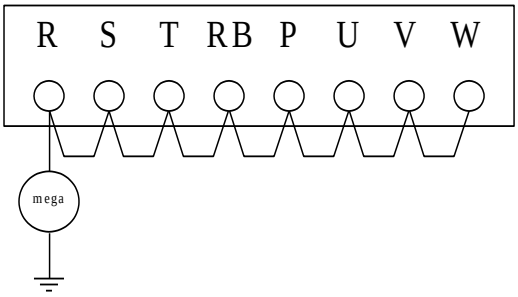
10.1 General precautions and notes

Always keep the unit clean so that dust of other foreign matter does not enter the inverter.
Firmly connect terminals and connectors.
Keep electronic equipment away from moisture and oil. Dust, steel filings and other foreign matter can damage insulation, causing unexpected accidents, so take special care.
When removing connectors, never pull the wires (wires for the cooling fan and logic P.C. board.)
Otherwise, there is danger of fire due to wire breakage and/or injury

10.2 Inspection items

(1) Daily inspection
(2) Periodic inspection (approximately once a year)
(3) Insulation resistance test (approximately once two years)

Conduct the insulation resistance test by short circuiting the terminals as shown below.



- Measure the above terminals and ground clearance with a 500 V mega tester and check if it is more than 5 MΩ.

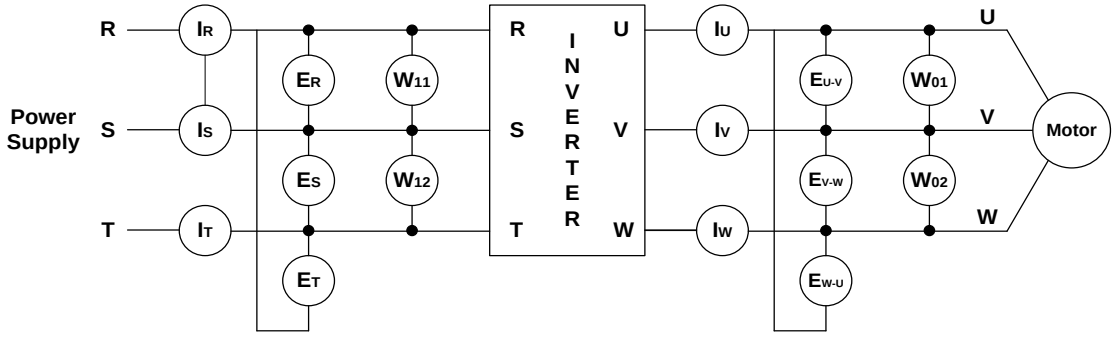
We recommend that you stock spare parts to reduce down time, which include

Recommend spare parts for stocks

Parts	Symbol	Quantity		Note
		Used	Spare	
Cooling Fan	FAN	2~5	2~5	Depends on power range 1EA: 007SF~022SF, 007LF~037LF, 007HF~037HF, 055LF~075LF 055HF~075HF 2EA: 110LF~150LF, 110HF~220HF 300HF~370HF, 450HF~550HF 3EA: 750HF~900HF, 1100HF~1600HF 4EA: 1850HF~2200HF 5EA: 2800HF~3500HF
Case	-	1	1	Front case Main case Bottom case

10.3 Inverter electrical measurements

The following table specifies how to measure key system electrical parameters.
The diagrams on the next page show inverter-motor systems the location of measurement points for these parameters.



Parameter	Measurement location	Measuring instrument	Notes	Reference value
Supply voltage E1	R-S, S-T, T-R (ER) (ES) (RT)	Moving-coil type voltmeter type voltmeter	Fundamental wave effective value	Commercial supply voltage (200V class) 200-220V 50Hz 200-240V 60Hz (400V class) 380-415V 50Hz 400-480V 60Hz
Supply current I1	R S T current (IR) (IS) (IT)	Moving-coil type ammeter	Total effective value	
Supply power W1	R-S, S-T (W11) + (W12)	Electronic type wattmeter	Total effective value	2wattmeter method
Supply power factor Pf1	Calculate the output power factor from the output voltage E1, output current I1, and output power W1. $$P_{f1} = \frac{W_1}{\sqrt{3} \times E_1 \times I_1} \times 100(\%)$$			
Output voltage E0	U-V, V-W, W-U (EU) (EV) (EW)	Rectifier type voltmeter	Total effective value	
Output current I0	U, V, W current (IU) (IV) (IW)	Moving-coil type ammeter	Total effective value	
Output power W0	U-V, V-W (W01) + (W02)	Electronic type wattmeter	Total effective value	2wattmeter method
Output power factor Pf0	Calculate the output power factor from the output voltage E0, output current I0, and output power W0. $$P_{f0} = \frac{W_0}{\sqrt{3} \times E_0 \times I_0} \times 100(\%)$$			

Use a meter indicating a fundamental wave effective value for voltage, and meters indicating total effective values for current and power.
The inverter output has a PWM waveform, and low frequencies may cause erroneous readings. However, the measuring instruments and methods listed above provide comparably accurate results.
A general-purpose digital volt meter (DVM) is not usually suitable to measure a PWM waveform.

Maker	**Advanced Drive Technology**	**Installation Date**	
Model No.	**iMASTER C1**	**Warranty Period**	
Customer Information	**Name**		
	Address		
	Tel.		
Sales Office (Distributor)	**Name**		
	Address		
	Tel.		

- Warranty period is 12 months after installation or 18 months after manufactured when the installation date is unidentified. However, the guarantee term may vary on the sales term

IN-WARRNTY service information

- If the defective part has been identified under normal and proper use within the guarantee term, contact your local authorized ADT distributor or Service center

OUT-WARRNTY service information

- The guarantee will not apply in the following cases, even if the guarantee term has not expired

- Damage was caused by misuse, negligence or accident
- Damage was caused by abnormal voltage and peripheral device' malfunction (failure)
- Damage was caused by an earthquake, fire, flooding, lightning, or other natural calamities
- When ADT nameplate is not attached
- When the warranty period has expired

iMASTER-C1 INSTRUCTION MANUAL REVISION HISTORY

No.	Revision contents	The date of issue	Version No.
1	First edition	19. 06	ADT-C1-01-K201906(T)
2	UL addtion	19. 12	ADT-C1-01-201906(01)
3	Full version	20. 01	ADT-C1-01-202001(01)
4	A01 Initial value change	20. 04	ADT-C1-01-202001(02)
5	Up/Down function description change	20. 11	ADT-C1-01-202001(03)
6	Added 3.7kw or less specification	21. 03	ADT-C1-01-202001(04)
7	Added 30kw~160kW specification Addes Modbus address map, Warrant	22. 03	ADT-C1-01-202001(05)
8	Added 30kw~160kW hole change	22. 05	ADT-C1-01-202001(06)
9	UL addition(30kw~160kW) b10, b22, A95, C30 change Added Modbus Exception Code #0 1Frame Depth change ND Rated Current change (30kw~160kW) Add New Code (H13 to H22) Modifying RJ45 Port Specifications	22. 08	ADT-C1-01-202001(07)
10	Communication & Encoder Option	23.05	ADT-C1-01-202001(08)
11	Add Parameters O05, O06 H03 parameter content modified. O04 Modifying the Set Range Modify Up/Down Function Description Modify reset related functions (b25, b29) d10 parameter corrected d14, d15, d16, d17 parameters' 2nd byte corrected	24.05	ADT-C1-01-202001(09)
12	Added 185kw~350kW specification Applicable tools change B06 Initial value change	24.12	ADT-C1-01-202001(10)